

THE LAMBDA CALCULUS AS A PROGRAMMING LANGUAGE.

λ -CALCULUS:

LOGIC \rightarrow FUNCTIONAL PROGRAMMING
 \rightarrow CATEGORY THEORY

- o AN EXPRESSION LANGUAGE ("EVALUATE")
- o FUNCTIONAL (NO SIDE EFFECTS)
- o HIGHER-ORDER (FUNCTIONS OF FUNCTIONS)
- o PROTOTYPICAL (BASIS FOR STUDYING LANGUAGE FEATURES)

ACTUAL PROGRAMMING LANGUAGES BASED ON λ -CALCULUS:

ML, Lisp, Scheme, Miranda, Haskell ...



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THE UNIFIED LAMBDA CALCULUS

- o NO TYPES
- o NO QUIET-IN DATA OR OPERATIONS
- o REPRESENT BOTH PROGRAMS AND DATA AS λ -TERMS

SYNTAX

TERMS $M, N ::= x \mid MN \mid \lambda x.M$

FREE VARIABLES:

$$FV(x) = \{x\}$$

$$FV(MN) = FV(M) \cup FV(N)$$

$$FV(\lambda x.M) = FV(M) - \{x\}$$

α -EQUIVALENCE: RENAMING OF BOUND VARIABLES

CONVENTIONS: $MNP = (MN)P$
 $\lambda x.MN = \lambda x.(MN)$

RULES: EQUATIONAL

$$(B) \quad (\lambda x.M)N = M[x:=N] \quad \text{(APPROXIMATE-ABSTRACTING)}$$

$$(\eta) \quad \lambda x.Mx = M \quad \text{where } x \notin FV(M)$$

REDUCTION

$$(B) \quad (\lambda x.M)N \rightarrow M[x:=N] \quad x \notin FV(M)$$

$$(\eta) \quad \lambda x.Mx \rightarrow M$$

+ CONTEXTUAL + REFLEXIVE TRANSITIVE CLOSURE

NORMAL FORM: A TERM WHICH CONTAINS NO REDX (I.E. REDUCES NO FUZZY).
 HOW PROGRAMMING?

① DATA REPRESENTATION

BOOLEANS:

$T = \lambda xy. x$ $F = \lambda xy. y$

INTEGERS:

$0 = \lambda fx. x$
 $1 = \lambda fx. fx$
 $2 = \lambda fx. f(fx)$
 \vdots
 $n = \lambda fx. f^{(n)}x$

"CHURCH NUMERALS"
 "ITERATORS"

② FUNCTIONS

if = $\lambda abc. abc$ succ = $\lambda nfx. f(nfx)$
 and = $\lambda ab. abf$ plus = $\lambda nm. n \text{ succ } m$
 or = $\lambda ab. aTb$ times = $\lambda nm. n(\text{plus } m) 0$
 not = $\lambda a. aFT$ exp = $\lambda nm. nm$

EXERCISE:

FIND TERMS iszero AND pred SUCH THAT
 $\text{iszero } 0 = T, \text{ iszero } n+1 = F, \text{ pred } n+1 = n, \text{ pred } 0 = 0$

③ CONTROL STRUCTURES

LEMMA LET $A = \lambda af. f(aaf)$ AND LET

$\Theta = AA = (\lambda af. f(aaf)) (\lambda af. f(aaf))$

"TURING'S FIXPOINT COMBINATOR".

THEM FOR ANY TERM M:

$\Theta M \rightarrow M(\Theta M)$

THUS, ΘM IS A FIXPOINT OF M.

- EVERY FUNCTION HAS A FIXPOINT !
- FIXPOINTS ARE USED TO SOLVE EQUATIONS:

TO SOLVE

$X = \dots x \dots,$
 LET x BE A FIXPOINT OF
 $\lambda x. \dots x \dots$
 SO SET
 $x = \Theta(\lambda x. \dots x \dots)$

RECURSION IS AN EXAMPLE OF
SOME AN EQUATION.

FACTORIAL:

$$\text{fact } x = \text{if } (\text{iszero } x) \ 1 \ (\text{times } x \ (\text{fact } (\text{pred } x)))$$

\Leftrightarrow

$$\text{fact} = \lambda x. \text{if } (\text{iszero } x) \ 1 \ (\text{times } x \ (\text{fact } (\text{pred } x)))$$

~~\Leftarrow~~

$$\text{fact} = \Theta(\lambda f. \lambda x. \text{if } (\text{iszero } x) \ 1 \ (\text{times } x \ (f \ (\text{pred } x))))$$

EXERCISE: VERIFY THAT

$$\text{fact } 0 \rightarrow 1$$

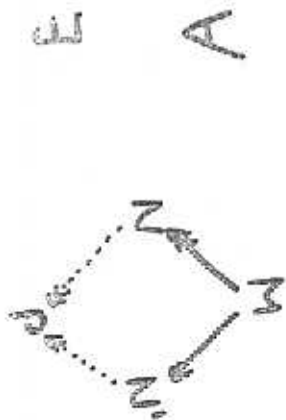
$$\text{fact } 1 \rightarrow 1$$

$$\text{fact } 2 \rightarrow 2$$

$$\text{fact } 3 \rightarrow 6$$

etc.

CHURCH-POSSIBLE PROPERTY, 1936:



CONSEQUENCES:

- IF $M =_{\beta\eta} N$ THEN THERE EXISTS P WITH $M \rightarrow_{\beta\eta} P$, $N \rightarrow_{\beta\eta} P$.
- NORMAL FORMS ARE UNIQUE.

TYPED LAMBDA CALCULUS

- HAS PRIMITIVE DATA + OPERATIONS BUILT IN
- USES TYPES TO ENSURE WELL-DEFINEDNESS OF OPERATIONS

SYNTAX

TYPES: $A, B ::=$ base types $| A \rightarrow B | A \times B | 1$

TERMS: $M, N ::= x | \lambda x.M | \langle M, N \rangle | \pi_i M | * | c_A$

TYPEING JUDGEMENT:

$$\Gamma : x_1:A_1, \dots, x_n:A_n \vdash M:B$$

TYPEING RULES:

$$\Gamma, x:A \vdash x:A$$

$$\frac{\Gamma \vdash M_1:A \rightarrow B \quad \Gamma \vdash N:A}{\Gamma \vdash M_1 N:B}$$

$$\Gamma \vdash MN:B$$

$$\frac{\Gamma, x:A \vdash M:B}{\Gamma \vdash \lambda x.AM:A \rightarrow B}$$

$$\frac{\Gamma \vdash N:A \quad \Gamma \vdash M:B}{\Gamma \vdash \langle N, M \rangle:A \times B}$$

$$\Gamma \vdash \langle M, N \rangle:A \times B$$

PLUS CONSTRAINTS, E.G.:

$Y : (A \rightarrow A) \rightarrow A$

$Q : \text{int}$

plus : $\text{int} \rightarrow \text{int} \rightarrow \text{int}$

if : $\text{bool} \rightarrow (A \rightarrow A \rightarrow A)$

OPERATIONAL SEMANTICS

PROGRAMMING LANGUAGE =

SYNTAX + OPERATIONAL SEMANTICS

REDUCION STRATEGY

CALL-BY-NAME (CBN):

SUBSTITUTE BEFORE EVALUATING THE ARGUMENT:

$$(\lambda x.M)N \rightarrow M[x:=N]$$

$$\pi_i \langle M_1, M_2 \rangle \rightarrow M_i$$

$$\frac{M \rightarrow M'}{MN \rightarrow M'N}$$

$$MN \rightarrow M'N$$

$$\frac{M \rightarrow M'}{\pi_i M \rightarrow \pi_i M'}$$

PLUS SOME RULES FOR CONSTRAINTS E.G.

$$YM \rightarrow M(YM)$$

$$\text{if } T \rightarrow \lambda xy.x$$

$$\frac{M \rightarrow M'}{\text{plus } MN \rightarrow \text{plus } M'N}$$

$$\text{if } E \rightarrow \lambda xy.y$$

$$\frac{N \rightarrow N'}{\text{plus } MN \rightarrow \text{plus } yN'}$$

etc.

$$\text{plus } m \ n \rightarrow \text{plus } m \ n$$

NOTE:

o NO CONSTRAINTS CLOSED, REDUCE AT TOP LEVEL

o DON'T REDUCE UNDER A λ OR PAIR REDUCTION IS DETERMINISTIC.

A RESULT IS A TERM OF THE FORM:

$$x, \lambda x.M, \langle M, N \rangle, *, c,$$

FB, ... Ni when $i < n = \text{arity}(f)$.

NOTE:

o A RESULT DOES NOT REDUCE

o A WELL-TYPED CLOSED TERM WHICH DOES NOT REDUCE IS A RESULT

o A WELL-TYPED CLOSED TERM (PROGRAM) DOES NOT GET STUCK

o A PROGRAM PRODUCES AT MOST ONE RESULT.

Lemma

SUBJECT REDUCTION

$$\Gamma \vdash M : A, M \rightarrow M' \Rightarrow \Gamma \vdash M' : A$$

CALL-BY-VALUE (CBV):

SUBSTITUTE ARG. EVALUATING THE ARGUMENT

VALUES

$$V ::= x \mid \lambda x.M \mid \langle V, V' \rangle \mid * \mid c \mid f_1 \dots f_n$$

when $i < n$

REDUCTION RULES:

$$(\lambda x.M)V \rightarrow M[x := V]$$

$$\pi_i \langle V_1, V_2 \rangle \rightarrow V_i$$

$$\frac{M \rightarrow M'}{MN} \quad \frac{N \rightarrow N'}{VN} \rightarrow VN'$$

$$\frac{M \rightarrow M'}{\langle M, N \rangle} \rightarrow \langle M', N \rangle \quad \frac{N \rightarrow N'}{\langle M, N \rangle} \rightarrow \langle M, N' \rangle$$

$$\frac{M \rightarrow M'}{\pi_i M} \rightarrow \pi_i M'$$

~~Other rules~~

PUS SOME RULES FOR CONSTRAINTS E.C.

plus $\beta \rightarrow$ ~~rule~~

$$Y(\lambda f x.M)z \rightarrow M[f := Y(\lambda f x.M), x := z].$$

$$Y: ((A \rightarrow B) \rightarrow (A \rightarrow B)) \rightarrow A \rightarrow B$$

NOTE: COMPARE WITH PHIL SCOTT'S LECTURES:

NNO (NATURAL NUMBERS OBJECT):

- PRIMITIVE RECURSION
- ALL FUNCTIONS ARE TOTAL
- STRONG NORMALIZATION
- EVALUATIONAL WORLD

FIXPOINT OPERATORS:

- GENERAL RECURSION
- FUNCTIONS ARE PARTIAL
- DIVERGENCE
- OPERATIONAL WORLD

OPERATIONAL EQUIVALENCE

A PROGRAM IS A CLOSED TERM OF GROUND TYPE (E.G. OF TYPE Bool)

TERMS M, N ARE OPERATIONALY EQUIVALENT IF THEY BEHAVE "THE SAME" AS PART OF ANY PROGRAM.

FORMALLY:

TERMS M, N ARE OPERATIONALY

EQUIVALENT ($M \approx N$) IF FOR ALL GROUND-TYPE, CLOSING CONTEXTS $C[\]$, AND ALL GROUND TYPE VALUES (CONSTANTS c ,

$$C[M] \rightarrow c \Leftrightarrow C[N] \rightarrow c$$

NOTES: • CONTEXT $C[\]$ REPRESENTS WHAT CAN BE OBSERVED ABOUT A TERM

- GENERALLY, $C[\]$ IS FROM THE SAME LANGUAGE AS M, N.
- HOWEVER, IT COULD BE FROM A LARGER LANGUAGE, LEADING TO LEFS OPERATIONAL EQ.

THE NOTION OF OPERATIONAL EQUIV. DEPENDS ON THE LANGUAGE OF THE CONSTANTS ALLOWED.

LAGER LANGUAGES HAVE LESS OPERAT. EQUIVALENCE.

EXAMPLE: $\underline{a}d_1 = \lambda a b$. if $a b \in$

$$\underline{a}d_2 = \lambda a b. \text{ if } b a \in$$

IN A LANGUAGE WITHOUT DIVERGENCE (OR SIDE EFFECTS), HAVE

$$\underline{a}d_1 =_{op} \underline{a}d_2$$

HOWEVER, IF DIVERGENCE IS ADDED (E.G. A TERM Ω S.T. $\Omega \rightarrow \Omega$), THEN

$$\underline{a}d_1 \neq_{op} \underline{a}d_2$$

BECAUSE THE CONTEXT $C[\] = [] \Omega$ DISMISSES THEM.

RELATIONSHIP BETWEEN $=_{\beta\eta}$ AND OPERATIONAL SEMANTICS.

CALL-BY-NAME

LEMMA (SOUNDNESS)

$$M =_{\beta\eta} N \Rightarrow M =_{op} N$$

• THUS $\beta\eta$ -EQUIVALENCE IS A CONSERVATIVE APPROXIMATION TO OPERATIONAL EQUIVALENCE

- MOREOVER, THIS HOLDS W.R.T. ALL REASONABLE LANGUAGE EXTENSIONS
- COMPILER OPTIMIZATIONS AND PROGRAM TRANSFORMATIONS.

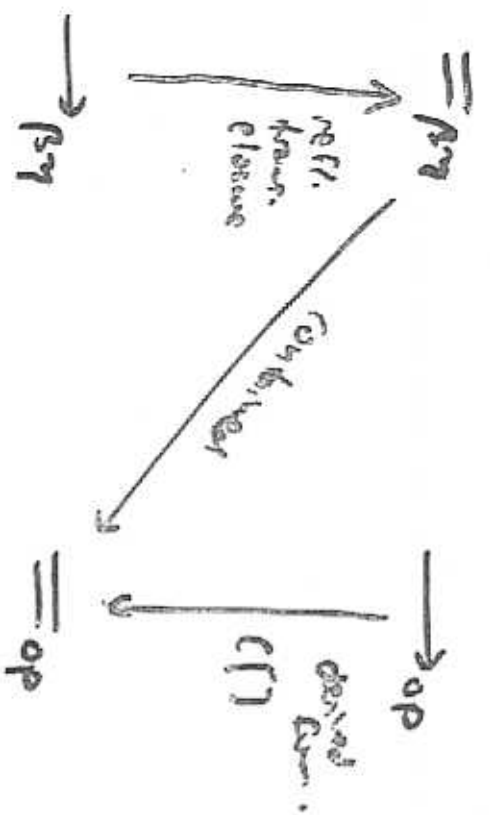
CALL BY VALUE

WE DO NOT HAVE $M=y, N \Rightarrow M=opN$.

EXAMPLE $(\lambda x.I)\Omega$ DIVERGES

$(\lambda x.I)(\lambda y.\Omega y) \rightarrow I$

- Thus $\Omega \neq_{op} \lambda y.\Omega y$
- (η -Law is UNSOUND)
- ALSO $(\lambda x.I)\Omega \neq_{op} I$
- (β -Law is UNSOUND).



CALL-BY-VALUE EQUIVALENCE

(= NOCCI'S COMPUTATIONAL λ -CALCULUS)

WRITE $\text{LET } x=N \text{ in } M$ FOR $(\lambda x.M)N$

$$(\lambda x.M)V = M[V/x]$$

$$\lambda x.Vx = V \quad x \notin FV(V)$$

$$\pi_i \langle V_1, V_2 \rangle = V_i$$

$$\langle \pi_1 V, \pi_2 V \rangle = V$$

$$* = V : 1$$

$$\text{let } x=M \text{ in } x = M$$

$$\text{let } y=C \text{ (let } x=M \text{ in } N) \text{ in } P =$$

$$\text{let } x=M \text{ in let } y=N \text{ in } P$$

$$MN = \text{let } x=M \text{ in let } y=N \text{ in } xy$$

$$\langle \pi_1 M \rangle = \text{let } x=M \text{ in let } y=N \text{ in } Cx.y$$

$$\pi_1 M = \text{let } x=M \text{ in } \pi_1 x$$

THE DISJUNCTIVE λ -CALCULUS

CONTROL OPERATORS: ALTER THE

"NORMAL" FLOW OF CONTROL.

"JUMP" TO SOME OTHER PART OF THE PROGRAM.

TO THE SIMPLY-TYPED λ -CALCULUS, ADD:

- A TYPE \perp
(EMPTY TYPE, TYPE OF A "FUNCTION WHICH DOES NOT RETURN")
- A SET OF "CHANNEL NAMES" $\alpha, \beta, \gamma, \dots$
("CHANNELS", "SIGNALS", "LARGES"...)
- A TERM CONSTRUCTOR $[c]M$
("COMPUTE M , THEN SEND THE RESULT ON CHANNEL c ")
- A TERM CONSTRUCTOR $\text{put}.M$
(SIGNALER. "COMPUTE M WHILE LISTENING ON α . ANY VALUE RECEIVED ON α IMMEDIATELY BECOMES THE VALUE OF $\text{put}.M$ ")

CHANNELS α, β, γ ARE TYPED:
 THE TYPE OF α IS THE TYPE OF VALUES
 THAT CAN BE "SENT" ON α .

Typing Judgments

$x_1 : B_1, \dots, x_n : B_n \vdash M : A \mid \Delta, \alpha : A, \dots, \alpha_n : A_n$
 OR BRIEFLY: $\Gamma \vdash M : A \mid \Delta$

$$\frac{\Gamma \vdash M : A \mid \Delta, \alpha : A}{\Gamma \vdash [\alpha]M : A \mid \Delta, \alpha : A}$$

$$\frac{\Gamma \vdash M : L \mid \Delta, \alpha : A}{\Gamma \vdash \mu \alpha^A.M : A \mid \Delta}$$

ADD DISJUNCTION TYPES $A \vee B$

AND TERMS $[\alpha, \beta]M, \mu(\alpha, \beta).M$

$$\frac{\Gamma \vdash M : A \vee B \mid \Delta, \alpha : A, \beta : B}{\Gamma \vdash [\alpha, \beta]M : L \mid \Delta, \alpha : A, \beta : B}$$

$$\frac{\Gamma \vdash M : L \mid \Delta, \alpha : A, \beta : B}{\Gamma \vdash \mu(\alpha^A, \beta^B).M : A \vee B \mid \Delta}$$

NOTE: NOT THE SAME AS "SUM TYPE"
 $A + B$ DERIVED VIA $\text{inl}, \text{inr}, \text{case}$.

CONTROL OPERATORS GIVE

CLASSICAL LOGIC. [GRIFFIN '90]

WHY ?



EVIL KING



POOR SHEPHERD

A : PHILOSOPHER'S STONE

L : GOLD

$A \vee (A \rightarrow L)$?

$A \vee (A \rightarrow L)$

$\mu(d^A, \nu^{A \rightarrow L}). [[R] (\lambda x^A. [d] x)]]$

$A \rightarrow L$
machine

EQUATIONAL THEORY.

THERE ARE SEPARATE EQUATIONAL THEORIES FOR THE CALL-BY-NAME AND FOR THE CALL-BY-VALUE λ -CALC.:

CBN [PARIGOT '92?]

$$\mu\alpha^{A \rightarrow B}. M)N = \mu\beta^B. M \left[\frac{[\beta](-)N}{[\alpha](-)} \right]$$

AND OTHERS...

CBV [ONG, STEWART '92?]

$$\mu\alpha^{A \rightarrow B}. N = \mu\beta^B. N \left[\frac{[\beta]V(-)}{[\alpha](-)} \right]$$

AND OTHERS...

A, B, C CATEGORIES.

A BIBIDIAL FUNCTOR F FROM A, B TO C IS GIVEN BY TWO FUNCTORS

$$F_0: A \times B \rightarrow C$$

$$F_1: A \times B \rightarrow C$$

SUCH THAT $F_0(A, B) = F_1(A, B)$ FOR ALL OBJECTS A, B .

HAVE $F(A, B), F(f, g), F(A, g)$ BUT NOT $F(f, g)$

THE FOLLOWING MAY NOT COMPUTE:

$$F(A, B) \xrightarrow{F(f, g)} F(A', B)$$

$$F(A, g) \downarrow \# \int F(A', g)$$

$$F(A, g') \xrightarrow{F(f, g')} F(A', g')$$

EXAMPLE "CATEGORY OF CONTINUATIONS"

LET C BE A CATEGORY WITH FINITE PRODUCTS, A DISTINGUISHED OBJECT R , AND EXPONENTIALS OF THE FORM R^A .

LET R^C DENOTE THE FULL SUBCATEGORY OF C OF OBJECTS OF THE FORM R^A .

DEFINE AN OBJECT MAP $R^A \times R^B := R^{A \times B}$

FUNCTORIAL IN R^A VIA $R^{A \times B} \cong (R^A)^B$ FUNCTORIAL IN R^B VIA $R^{A \times B} \cong (R^B)^A$

BUT NOT JOINTLY.

HAVE $\perp := R^1$

$$\perp \times R^A = R^1 \times R^A = R^{1 \times A} \cong R^A$$

$$(R^A \times R^B) \times R^C \cong R^{A \times B \times C} \cong R^A \times (R^B \times R^C)$$

ETC.

CONTROL CATEGORIES

DEFINITION

A CONTROL CATEGORY IS A CARTESIAN-CLOSED CATEGORY \mathcal{P} TOGETHER WITH A SYMMETRIC PRETENSOR \otimes, \perp AND A MONOID

$$\begin{aligned} \nabla_A &: A \otimes A \rightarrow A \\ \iota_A &: \perp \rightarrow A \end{aligned}$$

ON EACH OBJECT A , SUCH THAT

1. DISTRIBUTIVITY

$$(A \times B) \otimes C \cong (A \otimes C) \times (B \otimes C)$$

$$\perp \otimes C \cong \perp$$

AND

2. EXPONENTIAL STRENGTH

$$B^A \otimes C \cong (B \otimes C)^A \quad \leftarrow \text{CLASSICAL LOGIC}$$

SATISFYING A NUMBER OF COHERENCE AND NATURALITY CONDITIONS.

N.B.: ALGEBRAIC STRUCTURE

Table 1. The signature of control categories

Nullary multiplication constructors:	Object constructors:
$\circ: A \rightarrow A$	$\perp, A \times B, A \rightarrow B, A \otimes B$
$\circ: A \rightarrow \perp$	
$\tau: A \times B \rightarrow A$	
$\eta: A \times B \rightarrow B$	
$\epsilon: B^A \times A \rightarrow B$	$f: A \rightarrow B, g: B \rightarrow C$
$\mu: (A \otimes B) \otimes C \rightarrow A \otimes (B \otimes C)$	$f: A \rightarrow B, h: A \rightarrow C$
$\iota: A \rightarrow A \otimes \perp$	$(f, g): A \rightarrow B \times C$
$\epsilon: A \otimes B \rightarrow B^A$	$f: A \times B \rightarrow C$
$\iota: \perp \rightarrow A$	$f: A \rightarrow C^B$
$\nabla: A \otimes A \rightarrow A$	$f: A \rightarrow B$
$\mu: (A \otimes C) \times (B \otimes C) \rightarrow (A \times B) \otimes C$	$f \otimes g: A \otimes B \rightarrow C$
$\tau: (B \otimes C) \rightarrow B \otimes C$	$f \otimes g: A \otimes C \rightarrow B \otimes C$

Table 2. The typing rules for the λ -calculus

(var)	$\frac{}{\Gamma \vdash x : A \mid \Delta} \text{ If } x \in A \subseteq \Gamma$	(cop)	$\frac{\Gamma \vdash M : A \rightarrow B \mid \Delta \quad \Gamma \vdash N : A \mid \Delta}{\Gamma \vdash MN : B \mid \Delta}$
(const)	$\frac{}{\Gamma \vdash c^A : A \mid \Delta}$	(abs)	$\frac{\Gamma \vdash x : A \mid \Delta \quad \Gamma \vdash M : B \mid \Delta}{\Gamma \vdash \lambda x. M : A \rightarrow B \mid \Delta}$
(*)	$\frac{}{\Gamma \vdash * : \perp \mid \Delta}$	(const)	$\frac{\Gamma \vdash M : A \mid \Delta \quad \text{If } c \in A \subseteq \Delta}{\Gamma \vdash [c]M : \perp \mid \Delta}$
(prod)	$\frac{\Gamma \vdash M : A \mid \Delta \quad \Gamma \vdash N : B \mid \Delta}{\Gamma \vdash (M, N) : A \times B \mid \Delta}$	(b)	$\frac{\Gamma \vdash M : \perp \mid \Delta \quad \text{If } c \in A \subseteq \Delta}{\Gamma \vdash [c]M : \perp \mid \Delta}$
(t)	$\frac{}{\Gamma \vdash M : A \wedge B \mid \Delta}$	(const)	$\frac{\Gamma \vdash M : A \mid \Delta \quad \text{If } c \in \Gamma', \Delta \subseteq \Delta'}{\Gamma \vdash [c]M : A \mid \Delta'}$
(imp)	$\frac{}{\Gamma \vdash M : A \rightarrow B \mid \Delta}$	(const)	$\frac{\Gamma \vdash M : A \wedge B \mid \Delta \quad \text{If } c \in A, \beta \in B, \Delta \subseteq \Delta'}{\Gamma \vdash [c, \beta]M : \perp \mid \Delta'}$
		(*)	$\frac{}{\Gamma \vdash M : \perp \mid \Delta}$
			$\frac{}{\Gamma \vdash [c, \beta]M : A \wedge B \mid \Delta'}$

EXAMPLE (CONTINUED):

LET \mathcal{C} AND $\mathcal{R}^{\mathcal{C}}$ BE AS BEFORE; ASSUME
IN ADDITION THAT \mathcal{C} HAS FINITE (DISTRIBUTIVE)
SUMS.

$$\mathcal{R}^A \times \mathcal{R}^B = \mathcal{R}^{A+B}$$

$$1 = \mathcal{R}^1$$

$$\mathcal{R}^A \times \mathcal{R}^B = \mathcal{R}^{A+B}$$

$$1 = \mathcal{R}^0$$

$$(\mathcal{R}^B)_{\mathcal{R}^A} = \mathcal{R}^{B \times \mathcal{R}^A}$$

$$\nabla : \mathcal{R}^A \times \mathcal{R}^A \rightarrow \mathcal{R}^A \quad \text{IS} \quad \mathcal{R}^A : \mathcal{R}^{A \times A} \rightarrow \mathcal{R}^A$$

$$i : 1 \rightarrow \mathcal{R}^A \quad \text{IS} \quad \mathcal{R}^* : \mathcal{R}^1 \rightarrow \mathcal{R}^A$$

$$\text{DISTRIBUTIVITY: } \mathcal{R}^{(A+B) \times C} \cong \mathcal{R}^{A \times C + B \times C}$$

$$\mathcal{R}^{0 \times C} \cong \mathcal{R}^0$$

$$\text{EXP. STRUCTURE: } \mathcal{R}^{(B \times \mathcal{R}^A) \times C} \cong \mathcal{R}^{(B \times C) \times \mathcal{R}^A}$$

$\mathcal{R}^{\mathcal{C}}$ IS A CONTROL CATEGORY.

MAIN THEOREM OF
CONTROL CATEGORIES
(STRUCTURE THEOREM)

EVERY CONTROL CATEGORY \mathcal{P}
IS EQUIVALENT TO A CATEGORY
OF CONTINUATIONS $\mathcal{R}^{\mathcal{C}}$.

[cf. HOFMANN '95, FÜRNBERG '98]

THE INTERPRETATION OF THE CALL-BY-NAME λ -CALCULUS IN A CONTROL CATEGORY.

TYPES:

$$\begin{aligned} \llbracket I \rrbracket &= 1 \\ \llbracket \lambda x.B \rrbracket &= \llbracket \lambda \rrbracket \times \llbracket B \rrbracket \\ \llbracket \perp \rrbracket &= \perp \\ \llbracket \lambda v.B \rrbracket &= \llbracket \lambda \rrbracket \otimes \llbracket B \rrbracket \\ \llbracket A \rightarrow B \rrbracket &= \llbracket B \rrbracket^{\llbracket A \rrbracket} \end{aligned}$$

TERMS:

$$\llbracket x_i : B_i, \dots, x_n : B_n \triangleright M : A \triangleright d : A_1, \dots, d_m : A_m \rrbracket$$

E.G.

$$\begin{aligned} \llbracket \Gamma \triangleright MN : B \triangleright \Delta \rrbracket &= \Gamma \xrightarrow{\langle M, N \rangle} (B^A \otimes \Delta) \times (A \otimes \Delta) \xrightarrow{\epsilon} B \otimes \Delta \\ \llbracket \Gamma \triangleright \lambda x.A.M : B \triangleright \Delta \rrbracket &= \Gamma \xrightarrow{M^A} (B \otimes \Delta)^A \subseteq B^A \otimes \Delta \\ \llbracket \Gamma \triangleright \lambda x.M : \perp \triangleright d : A, \Delta \rrbracket &= \Gamma \xrightarrow{M} A \otimes \Delta \otimes \Delta \xrightarrow{\perp} \text{point} \\ \llbracket \Gamma \triangleright \text{snd}.A.M : A \triangleright \Delta \rrbracket &= \Gamma \xrightarrow{M} \perp \otimes \Delta \otimes \Delta \cong A \otimes \Delta \end{aligned}$$

Table 3. The CPS translation of the call-by-name λ -calculus

$\lambda x. B$	$\lambda x. \lambda \beta. B$	where $x : A$
\perp	$\lambda \beta. \beta$	
M	$\lambda \beta. \lambda \alpha. M$	where $M : A, N : B$
$\lambda x.M$	$\lambda \beta. \lambda \alpha. \lambda \gamma. M$	where $M : A \wedge B$
$\lambda v.M$	$\lambda \beta. \lambda \alpha. M$	where $M : A \wedge B$
$\lambda v.M$	$\lambda \beta. \lambda \alpha. M$	where $M : A \rightarrow B, N : A$
$\lambda v.M$	$\lambda \beta. \lambda \alpha. M$	where $M : B$
$\lambda v.M$	$\lambda \beta. \lambda \alpha. M$	where $M : A$
$\lambda v.M$	$\lambda \beta. \lambda \alpha. M$	where $M : \perp$
$\lambda v.M$	$\lambda \beta. \lambda \alpha. M$	where $M : A \vee B$
$\lambda v.M$	$\lambda \beta. \lambda \alpha. M$	where $M : \perp$

Table 4. The interpretation of the call-by-name λ -calculus in a control category

$\llbracket \Gamma \triangleright x_i : B_i \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{M_i} B_i \xrightarrow{\Delta} \Delta$
$\llbracket \Gamma \triangleright c^d : A \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{c} \perp \xrightarrow{A} A \xrightarrow{\Delta} \Delta$
$\llbracket \Gamma \triangleright \cdot : \tau \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{\cdot} \perp \xrightarrow{\tau} \tau \xrightarrow{\Delta} \Delta$
$\llbracket \Gamma \triangleright (M, N) : A \wedge B \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{\langle M, N \rangle} (A \otimes B) \times (B \otimes \Delta) \xrightarrow{\epsilon} (A \otimes B) \otimes \Delta$
$\llbracket \Gamma \triangleright \lambda x.M : A \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{M^A} (A \otimes B) \otimes \Delta \xrightarrow{\pi_1 \otimes \Delta} A \otimes \Delta$
$\llbracket \Gamma \triangleright \lambda x.M : B \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{M^B} (A \otimes B) \otimes \Delta \xrightarrow{\pi_2 \otimes \Delta} B \otimes \Delta$
$\llbracket \Gamma \triangleright \lambda x.M : B \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{\langle M, \perp \rangle} (B \otimes \Delta) \times (A \otimes \Delta) \xrightarrow{\Delta} (B \otimes \Delta) \otimes \Delta$
$\llbracket \Gamma \triangleright \lambda x^d.M : A \rightarrow B \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{M^A} (B \otimes \Delta)^A \xrightarrow{\Delta} B \otimes \Delta$
$\llbracket \Gamma \triangleright [\text{snd}.M] : \perp \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{M} \perp \otimes \Delta \otimes \Delta \xrightarrow{\perp} \text{point}$
$\llbracket \Gamma \triangleright [\text{fst}.M] : A \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{M} \perp \otimes \Delta \otimes \Delta \xrightarrow{\pi_1} A \otimes \Delta$
$\llbracket \Gamma \triangleright [\text{snd}.M] : B \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{M} \perp \otimes \Delta \otimes \Delta \xrightarrow{\pi_2} B \otimes \Delta$
$\llbracket \Gamma \triangleright [\text{fst}.M] : A \vee B \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{M} \perp \otimes \Delta \otimes \Delta \xrightarrow{\Delta} \Delta \otimes \Delta \xrightarrow{\Delta} \Delta$
$\llbracket \Gamma \triangleright [\text{fst}.M] : A \vee B \mid \Delta \rrbracket_n$	$\Gamma \xrightarrow{M} \perp \otimes \Delta \otimes \Delta \xrightarrow{\Delta} \Delta \otimes \Delta \xrightarrow{\Delta} \Delta$

THEOREM

THE INTERPRETATION OF THE CALL-BY-NAME
 λ -CALCULUS IN A CONTROL CATEGORY IS
 SOUND AND COMPLETE.

MOREOVER, THE CATEGORICAL STRUCTURE
IS DEFINABLE BY SYNTAX, AND SO THE
CBM λ -CALCULUS IS AN INTERNAL LANGUAGE
FOR CONTROL CATEGORIES.

INTERPRETATION IN A CAT OF CONTINUOUS
R.C. YIELDS HOFFMAN-STREICHER CPS
TRANSFORM FOR CALL-BY-NAME.

CONTROL CATEGORIES



CPS TRANSLATION:



KRIVINE'S ABSTRACT MACHINE



IMPLEMENTATION: (ASSEMBLY LANGUAGE)

CPS → ABSTRACT MACHINES

KRIVINE MACHINE :

STATES $\langle M, \sigma, k \rangle$, WHERE :

M : A TERM

σ : AN ENVIRONMENT (MAPS VARIABLES TO CLOSURES, NAMES TO STACKS)

k : A STACK.

CPS

$\llbracket x \rrbracket k \rightarrow \tilde{x} k$

$\llbracket MN \rrbracket k \rightarrow \llbracket M \rrbracket \langle \llbracket N \rrbracket, k \rangle$

$\llbracket \lambda x.M \rrbracket \langle \llbracket N \rrbracket, k \rangle \rightarrow \llbracket M \rrbracket \langle \llbracket N \rrbracket, k \rangle$

$\llbracket [x]M \rrbracket k \rightarrow \llbracket M \rrbracket \alpha$

$\llbracket \mu \alpha.M \rrbracket k \rightarrow \llbracket M \rrbracket \langle \alpha, k \rangle \#$

$\llbracket [a, \beta]M \rrbracket k \rightarrow \llbracket M \rrbracket \langle \alpha, \beta \rangle$

$\llbracket \mu(\alpha, \beta).M \rrbracket \langle k, k' \rangle \rightarrow \llbracket M \rrbracket \langle k, k'/\beta \rangle \#$

MACHINE

$\langle x, \sigma, k \rangle \rightarrow \langle M, \sigma', k \rangle \quad (\sigma(x) = M \sigma')$

$\langle MN, \sigma, k \rangle \rightarrow \langle M, \sigma, N \sigma \rangle$

$\langle \lambda x.M, \sigma, N \sigma \rangle \rightarrow \langle M, \sigma(x \mapsto N \sigma) \rangle$

$\langle [a]M, \sigma, k \rangle \rightarrow \langle M, \sigma, k' \rangle \quad (\sigma(a) = k)$

$\langle \mu \alpha.M, \sigma, k \rangle \rightarrow \langle M, \sigma(\alpha \mapsto k), nil \rangle$

$\langle [a, \beta]M, \sigma, k \rangle \rightarrow \langle M, \sigma, k' \rangle$

$\langle \mu(\alpha, \beta).M, \sigma, k' \rangle \rightarrow \llbracket M \rrbracket \langle k, k'/\beta \rangle \#$
 $(\sigma(\alpha) = k; \sigma(\beta) = k)$

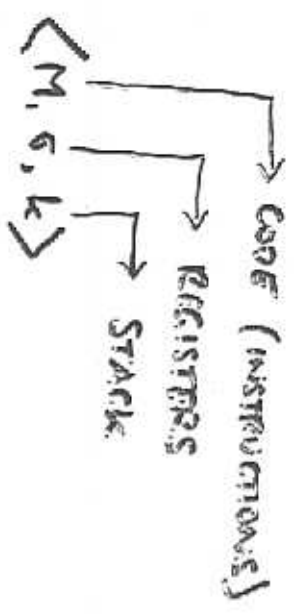
$\langle \mu(\alpha, \beta).M, \sigma, k' \rangle \rightarrow \langle M, \sigma(\alpha \mapsto k, \beta \mapsto k), nil \rangle$

After having changed the notation for continuations, we will now also change the notation for computations, i.e., for translated terms. In order to avoid having to do substitutions, we introduce the notion of a closure. A closure is a pair M^σ of a term M and an environment σ . An environment for M is a map from the free variables of M to closures, and from the free names of M to continuations i.e. stacks. An environment

Table 4: The transitions of the abstract machine

Abstract Machine		CPS	
$\langle x, \sigma, k \rangle$	$\rightarrow \tilde{x} k$	$\langle x, \sigma, k \rangle$	$\rightarrow \tilde{x} k$
$\langle MN, \sigma, k \rangle$	$\rightarrow \langle M, \sigma, N \sigma \rangle$	$\langle MN, \sigma, k \rangle$	$\rightarrow \langle M, \sigma, N \sigma \rangle$
$\langle \lambda x.M, \sigma, N \sigma \rangle$	$\rightarrow \langle M, \sigma(x \mapsto N \sigma) \rangle$	$\langle \lambda x.M, \sigma, N \sigma \rangle$	$\rightarrow \langle M, \sigma(x \mapsto N \sigma) \rangle$
$\langle [x]M, \sigma, k \rangle$	$\rightarrow \langle M, \sigma \rangle$	$\langle [x]M, \sigma, k \rangle$	$\rightarrow \langle M, \sigma \rangle$
$\langle \mu \alpha.M, \sigma, k \rangle$	$\rightarrow \langle M, \sigma(\alpha \mapsto k), nil \rangle$	$\langle \mu \alpha.M, \sigma, k \rangle$	$\rightarrow \langle M, \sigma(\alpha \mapsto k), nil \rangle$
$\langle [a, \beta]M, \sigma, k \rangle$	$\rightarrow \langle M, \sigma, k' \rangle$	$\langle [a, \beta]M, \sigma, k \rangle$	$\rightarrow \langle M, \sigma, k' \rangle$
$\langle \mu(\alpha, \beta).M, \sigma, k' \rangle$	$\rightarrow \langle M, \sigma(\alpha \mapsto k, \beta \mapsto k), nil \rangle$	$\langle \mu(\alpha, \beta).M, \sigma, k' \rangle$	$\rightarrow \langle M, \sigma(\alpha \mapsto k, \beta \mapsto k), nil \rangle$

ABSTRACT MACHINE → IMPLEMENTATION



TRANSLATION: $\llbracket M \rrbracket_{\sigma} =$ CODE FOR M WHERE S MAPS FREE VARS TO REGISTERS.

E.G. $\llbracket \lambda x.M \rrbracket_{\sigma} =$ CMP STACKPTR, #0
 GL EXIT
 POP R
 $\llbracket M \rrbracket_{S(x \mapsto R)}$

$\llbracket MN \rrbracket_{\sigma} =$ λ (Build closure for N)
 Alloc $A, \#(n+1)$
 LOAD $[A, 0], LABEL n$
 LOAD $[A, 1], REG_1$
 LOAD $[A, n], REG_n$
 PUSH A
 $\llbracket M \rrbracket_{\sigma}$

WHERE $FV(N) = x_1, \dots, x_n$ and $S(x_i) = REG_i, \dots, S(x_n) = REG_n$.

There are infinitely many registers R_1, R_2, \dots , as well as four distinguished registers $SP, SS, C,$ and V , each of which can hold a word. We assume that there are infinitely many addressable memory cells, each of which holds a word. A memory reference takes the form $[R, n]$, where R is a register and n is a literal integer. The expression R, n refers to the contents of the memory cell at

Table 5: Instruction set of the idealized assembly language

Instruction	Meaning
MOVE w, v	Store the value v in location w
ADD w, v	Add v to w
PUSH v	Push the value v onto the stack
POP w	Pop a value from the stack and store it in w
CMP v_1, v_2	Compare the two values, and remember the result
HNE v	If previous CMP resulted in not equal, jump to location v
BGE v	If previous CMP resulted in greater than or equal jump to location v
JUMP v	Jump to address v
CALL v	Call subroutine at address v
ALLOC w, v	Allocate v words of memory and store a pointer to them in w
SAVE w	Make a stack closure from the current stack, and store a pointer to it in w
RESTORE v	Replace the current stack by a copy of the stack closure pointed to by v
EXIT v	Exit with result v

Lambda calculus

$[x]_s =$

MOVE $C, s(x)$
JUMP $[C, 0]$

$[\lambda x.M]_s =$

CMP $SS, \#0$
BNE l
EXIT "function"
 l : POP R
 $[M]_{s(x \rightarrow R)}$

(where l is a fresh label and R is a fresh register.)

$[[M]N]_s =$

: build closure for N
ADD OC $R, \#(n + 1)$
MOVE $[R, 0], \#l$
MOVE $[R, 1], s(x)$
...
MOVE $[R, n], s(x_n)$
PUSH R

l : $[N]_{[s(x_1 \rightarrow [C, 1], \dots, x_n \rightarrow [C, n])]}$

(where l is a fresh label, R is a fresh register, and $\{V(N) \cup FN(N)\} = \{x_1, \dots, x_n\}$.)

$[(\lambda M, N)]_s =$

CMP $SS, \#0$
BNE l_1
EXIT "pair"
 l_1 : POP R
CMP $R, \#1$
BNE l_2
 $[M]_s$
 $[N]_s$

(where l_1, l_2 are fresh labels, and R is a fresh register.)

$[\pi_i.M]_s =$

PUSH $\#i$
 $[M]_s$
EXIT "quit"

$[*]_s =$

Ac-Calculus
 $[\mu x.M]_s =$

: build a stack closure
SAVE R
: clear the stack
MOVE $SP, \#0$
 $[M]_{s(x \rightarrow R)}$

(where R is a fresh register.)

$[(\alpha)M]_s =$

RESTORE $s(\alpha)$
 $[M]_s$

Classical disjunction (Ac-calculus)

$[(\vee)M]_s =$

CMP $SS, \#0$
BNE l
EXIT "disjunction"
 l : POP R
 $[M]_{s(\alpha \rightarrow R)}$

(where l is a fresh label and R is a fresh register.)

$[(\circ)M]_s =$

PUSH $s(\alpha)$
 $[M]_s$

Basic constants

$[true]_s =$

MOVE $V, \#n$
CMP $SS, \#0$
BNE l
EXIT V
 l : POP R
JUMP R

(where l is a fresh label and R is a fresh register.)

$[true]_s = [1]_s$.

$[false]_s = [0]_s$.

"Pure" basic functions

$[I]_s =$

: check for sufficient arguments
CMP $SS, \#n$
BGE f_0
EXIT "function"
 f_0 : MOVE $C, [SP, 1]$
PUSH $\#f_1$
JUMP $[C, 0]$

(repeat following code for $j = 1, \dots, n - 1$)

f_j : MOVE $[SP, j], V$

MOVE $C, [SP, j + 1]$

PUSH $\#f_{j+1}$

JUMP $[C, 0]$

f_n : MOVE $[SP, n], V$
: n values are now on top of stack
CALL native f_j
POP V
CMP $SS, \#0$
BNE l
EXIT V
 f_{n+1} : POP R
JUMP R

(where $n \geq 1$ is the arity of f , f_0, \dots, f_{n+1} are fresh labels, and R is a fresh register.)

Some "impure" basic functions

$[!M]_s =$

CMP $SS, \#1$
BGE $\#f_0$
EXIT "function"
 f_0 : POP C
PUSH $\#f_1$
JUMP $[C, 0]$
 f_1 : CMP $V, \#0$
BNE f_2
 $[!x.y.z]_0$
 $[!x.y.z]_0$

(where f_0, \dots, f_{n+1} are fresh labels.)

$[print]_s =$

CMP $SS, \#1$
BGE $print_0$
EXIT "function"
 $print_0$: POP C
PUSH $\#print_1$
JUMP $[C, 0]$
 $print_1$: PUSH V
CALL native $print$
 $[!x.s]_0$

(where $print_0, print_1$ are fresh labels.)

Table 6: The compilation of terms

Table 7: The compilation of terms, continued

TOWARDS DUALITY: CO-CONTROL CATEGORIES.

DEFINITION A co-control category is the dual of a control category. We write:

$$\begin{array}{ccc} \text{Control CAT} & & \text{Co-control CAT} \\ \hline 1 & \cong & 0 \\ A \times B & \cong & A + B \\ \perp & \cong & \top \\ A \wp B & \cong & A \otimes B \\ B^A & \cong & B_A \\ B \multimap A & \cong & A \multimap B = \top(A \otimes \neg B) \end{array}$$

IN A CO-CONTROL CATEGORY, WE WRITE $\neg A$ FOR \top_A .

REMARK

A CO-CONTROL CATEGORY IS A \top -CATEGORY OF THIELOCKE, ENHANCED WITH FINITE COPRODUCTS.

Let $(A, \otimes, \top, \perp, \wp, \multimap)$ be a control category with unit I , and a weak closed structure $A \multimap B$. The following table lists some notation that we are going to use for objects and morphisms of a co-control category:

On objects		On morphisms	
Control	Co-control	Control categories	Co-control categories
1	0	$\diamond : A \rightarrow 1$	$\square : 0 \rightarrow A$
$A \times B$	$A + B$	$i : \perp \rightarrow A$	$t : A \rightarrow \top$
\perp	\top	$\nabla : A \wp A \rightarrow A$	$\Delta : A \rightarrow A \otimes A$
$A \wp B$	$A \otimes B$	$\epsilon : B^A \times A \rightarrow B$	$\varepsilon : B \rightarrow B_A + A$
B^A	B_A	$f^* : C \rightarrow B^A$	$f_! : B_A \rightarrow C$
$B \multimap A$	$A \multimap B$	$\text{coapp} : B \rightarrow (B \multimap A) \wp A$	$\text{app} : (A \multimap B) \otimes A \rightarrow B$
		$\text{cocurry}(f) : (B \multimap A) \rightarrow C$	$\text{curry}(f) : C \rightarrow (A \multimap B)$

We use the usual notation for coproducts. Following Thielecke (1997), the dual of the map ∂ is called *think*, and the dual of ∂ is called *force*. The remaining structural maps keep the same names as their duals.

Every co-control category is a \wp -category in the sense of Thielecke (1997), where $\neg A$ is defined as $\top_A \cong A \multimap 0$. Notice that one has $B_A \cong (\neg A) \otimes B$ and $A \multimap B \cong \neg(A \otimes \neg B)$; thus each two of the constructs B_A , $A \multimap B$, and $\neg A$ can be defined in terms of the third. Conversely, one can show that every \wp -category can be fully and faithfully embedded in a co-control category. Thus, co-control categories can be seen as a natural extension of \wp -categories with finite coproducts. The presence of finite coproducts is important for the duality result in Section 8.

THE INTERPRETATION OF THE CALL-BY-VALUE
 $\lambda\mu$ -CALCULUS IN A CO-CONTROL CATEGORY.

Types: $[\cdot] = \mathcal{I}$

$$[A \times B] = [A] \otimes [B]$$

$$[\perp] = 0$$

$$[A \vee B] = [A] + [B]$$

$$[A \rightarrow B] = [A] \multimap [B]$$

Terms:

$$[\lambda_i: B_i, \dots, \lambda_n: B_n \triangleright M: A \triangleright d_i: A_i, \dots, d_n: A_n]$$

$$: B_1 \otimes \dots \otimes B_n \rightarrow A + A_1 + \dots + A_n$$

E.g.

$$* [\Gamma \circ \mu \triangleright \Delta] = \Gamma_{\Delta} \xrightarrow{\Delta} \Gamma_{\Delta} \otimes \Gamma_{\Delta} \xrightarrow{[\mu] \otimes id} (A \multimap B) \otimes A$$

$$\xrightarrow{id \otimes [\mu]} (A \multimap B) \otimes A \xrightarrow{app} B$$

$$* [\Gamma \circ \lambda x^A. M \triangleright \Delta] = \Gamma_{\Delta} \xrightarrow{curry^f} A \multimap B$$

$$\text{where } f = \Gamma_{\Delta} \otimes A \xrightarrow{id} (\Gamma \otimes A)_{\Delta} \xrightarrow{[\mu]} B$$

$$[\Gamma \circ [\alpha] M: \perp \triangleright \Delta] = \Gamma \xrightarrow{M} A + A + \Delta \xrightarrow{\circ} A + \Delta$$

$$[\Gamma \circ \mu \triangleright \Delta] = \Gamma \xrightarrow{M} 0 + A + \Delta \xrightarrow{\circ} A + \Delta$$

Table 8. The interpretation of the call-by-value $\lambda\mu$ -calculus in a co-control category

$[\Gamma \vdash x_i: B_i \mid \Delta]_v$	$= \Gamma \xrightarrow{x_i} B_i \xrightarrow{id} B_i + \Delta$
$[\Gamma \vdash c: A \mid \Delta]_v$	$= \Gamma \xrightarrow{c} I \xrightarrow{\varepsilon} A \xrightarrow{id} A + \Delta$
$[\Gamma \vdash \ast: T \mid \Delta]_v$	$= \Gamma \xrightarrow{\ast} I \xrightarrow{id} I + \Delta$
$[\Gamma \vdash \langle M, N \rangle: A \wedge B \mid \Delta]_v$	$= \Gamma_{\Delta} \xrightarrow{\Delta} \Gamma_{\Delta} \otimes \Gamma_{\Delta} \xrightarrow{[M]_v \otimes id} A \otimes \Gamma_{\Delta} \xrightarrow{id \otimes [N]_v} A \otimes B$
$[\Gamma \vdash \pi_1 M: A \mid \Delta]_v$	$= \Gamma \xrightarrow{[M]_v} (A \otimes B) + \Delta \xrightarrow{w+id} A + \Delta$
$[\Gamma \vdash \pi_2 M: B \mid \Delta]_v$	$= \Gamma \xrightarrow{[M]_v} (A \otimes B) + \Delta \xrightarrow{w+id} B + \Delta$
$[\Gamma \vdash MN: B \mid \Delta]_v$	$= \Gamma_{\Delta} \xrightarrow{\Delta} \Gamma_{\Delta} \otimes \Gamma_{\Delta} \xrightarrow{([M]_v \otimes id); (id \otimes [N]_v)} (A \multimap B) \otimes A \xrightarrow{app} B$
$[\Gamma \vdash \lambda x^A. M: A \rightarrow B \mid \Delta]_v$	$= \Gamma_{\Delta} \xrightarrow{curry(f)} A \multimap B$, where $f = \Gamma_{\Delta} \otimes A \xrightarrow{id} (\Gamma \otimes A)_{\Delta} \xrightarrow{[M]_v} B$
$[\Gamma \vdash [\alpha_i] M: \perp \mid \Delta]_v$	$= \Gamma \xrightarrow{[M]_v} A_i + \Delta \xrightarrow{id_i + \Delta} \Delta + \Delta \xrightarrow{\nabla} \Delta \xrightarrow{\cong} 0 + \Delta$
$[\Gamma \vdash \mu \alpha^A. M: A \mid \Delta]_v$	$= \Gamma \xrightarrow{[M]_v} 0 + A + \Delta \xrightarrow{\cong} A + \Delta$
$[\Gamma \vdash [\alpha_i, \alpha_j] M: \perp \mid \Delta]_v$	$= \Gamma \xrightarrow{[M]_v} A_i + A_j + \Delta \xrightarrow{id_i + id_j + \Delta} \Delta + \Delta + \Delta \xrightarrow{\nabla + \Delta; \nabla} \Delta \xrightarrow{\cong} 0 + \Delta$
$[\Gamma \vdash \mu(\alpha^A, \beta^B). M: A \vee B \mid \Delta]_v$	$= \Gamma \xrightarrow{[M]_v} 0 + A + B + \Delta \xrightarrow{\cong} (A + B) + \Delta$

THEOREM SOUND + COMPLETE AND:

THE CALL-BY-VALUE λ -CALCULUS IS
 AN INTERNAL LANGUAGE FOR
CO-CONTROL CATEGORIES.

AGAIN, BY INTERPRETING THE LANGUAGE
 IN A CAT OF COMPUTATIONS \mathcal{RC} ,
 WE OBTAIN A CPS TRANSLATION.

Table 7. The CPS translation of the call-by-value λ -calculus

λ^{K_A, K_B}	$=$	$\frac{\lambda^A}{\lambda^B}$
λ^{K_A, K_B}	$=$	λ^{K_A, K_B}
λ^{K_T, K_*}	$=$	$*$
$\lambda^{K_{A \wedge B}, M}(\lambda^M \lambda^N \lambda^V \lambda^k(m, n))$	$=$	$\frac{\lambda^M \lambda^N}{\lambda^V}$
$\lambda^{K_A, M}(\lambda^M \lambda^N \lambda^V \lambda^k(m))$	$=$	$\frac{\lambda^M \lambda^N}{\lambda^V}$
$\lambda^{K_B, M}(\lambda^M \lambda^N \lambda^V \lambda^k(m))$	$=$	$\frac{\lambda^M \lambda^N}{\lambda^V}$
$\lambda^{K_B, M}(\lambda^M \lambda^N \lambda^V \lambda^k(m))$	$=$	$\frac{\lambda^M \lambda^N}{\lambda^V}$
$\lambda^{K_B, M}(\lambda^M \lambda^N \lambda^V \lambda^k(m))$	$=$	$\frac{\lambda^M \lambda^N}{\lambda^V}$
$\lambda^{K_{A \rightarrow B}, K}(\lambda^{\lambda^{\varepsilon, \rho}} \lambda^V \lambda^k(m))$	$=$	$\frac{\lambda^V \lambda^M}{\lambda^A}$
$\lambda^{K_T, M}$	$=$	$\frac{\lambda^M}{\lambda^A}$
$\lambda^{K_A, M}$	$=$	$\frac{\lambda^M \lambda^N}{\lambda^A}$
$\lambda^{K_T, M}[\alpha, \beta]$	$=$	$\frac{\lambda^M \lambda^N}{\lambda^A}$
$\lambda^{K_T, M}[\alpha, \beta]$	$=$	$\frac{\lambda^M \lambda^N}{\lambda^A}$
$\lambda^{K_{A \vee B}, M}$	$=$	$\frac{\lambda^M \lambda^N}{\lambda^A}$

where $\alpha : A$

where $M : A, N : B$

where $M : A \wedge B$

where $M : A \wedge B$

where $M : A \wedge B$

where $M : A \rightarrow B, N : A$

where $M : B$

where $M : A$

where $M : \perp$

where $M : A \vee B$

where $M : A$

Table 8. The interpretation of the call-by-value λ -calculus in a co-control category

SOME REMARKS.

a) IN PRESENCE OF FIRST-CLASS
 CONTINUANTS, FUNCTION TYPES
 ARE DEFINABLE FROM NEGATION:

$$\text{CBV: } A \rightarrow B \cong \neg(A \wedge \neg B)$$

$$\text{CBN: } A \rightarrow B \cong \neg A \vee B$$

b) COMPARE WITH "INTUITIONISTIC" SUM
 TYPE $A+B$ DEFINED VIA INL/INR/CASE:

$$\text{CBV: } A+B \cong A \vee B$$

$$\text{CBN: } A+B \cong \neg\neg A \vee \neg\neg B$$

$$\cong \neg(\neg A \wedge \neg B)$$

c) "NAMES" VS. VARIABLES:

$$\text{CBV: } \frac{\text{X:}\neg A, \Gamma \vdash M: B \mid \Delta}{\Gamma \vdash M: B \mid \Delta} \mid \Delta, \alpha: A$$

$$\text{CBN: } \frac{\text{X:A, } \Gamma \vdash M: B \mid \Delta}{\Gamma \vdash M: B \mid \Delta, \alpha: \neg A}$$

SOME RECENT WORK:

- LAURENT [‘00]:
 CONTROL CATS \Leftrightarrow
 PROOF NETS FOR POLARIZED LINEAR LOGIC
- HASEGAWA, KAKUTANI [‘01];
 BASED ON FILINSKI [‘89]:
 CBV RECURSION \Leftrightarrow CBV ITERATION
 \Leftrightarrow CBN RECURSION
- MELLIÉS, SEJINGER [‘01]:
 CONTROL CATS FROM GAME
 SEMANTICS VIA "POLARIZED CATEGORIES"
 (ALSO EXPLAINS GLASS GAMES).