

# Lecture 12

## Parametric Surfaces

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# Outline

- ▶ Text: section 16.6
- ▶ Review: parameterized curves
- ▶ Definition
- ▶ Example
- ▶ Normal vector and tangent plane
- ▶ Surface area
- ▶ Example

# Parameterization

- ▶ A curve embedded in the 2D Euclidean plane is described by an equation in 2 variables  $F(x, y) = 0$ .
- ▶ Similarly, a surface embedded in 3D Euclidean space is described by an equation in 3 variables:  $F(x, y, z) = 0$
- ▶ A parameterization of a curve is a 2-vector valued function of one variable

$$(x, y) = \mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j}$$

such that  $F(f(t), g(t)) = 0$

- ▶ Analogously, a parameterization of a surface is a 3-vector valued function of **two** variables

$$(x, y, z) = \mathbf{r}(u, v) = f(u, v)\mathbf{i} + g(u, v)\mathbf{j} + h(u, v)\mathbf{k}$$

such that  $F(f(u, v), g(u, v), h(u, v)) = 0$ .

## Examples

- ▶ A parametrized curve is commonly interpreted as a particle moving along the curve.
- ▶ By contrast, a parameterized surface may be regarded as a grid imposed on the surface. The grid lines are curves obtained by setting one of the parameters  $u$  and  $v$  to a.
- ▶ The unit circle  $x^2 + y^2 = 1$  can be parameterized as  $(x, y) = (\cos(t), \sin(t))$ . This represents a particle moving counter-clockwise around the circle with unit speed.
- ▶ The 2-sphere  $x^2 + y^2 + z^2 = 1$  may be parameterized using spherical coordinates:

$$(x, y, z) = (\sin \phi \cos \theta, \sin \phi \sin \theta, \cos \phi)$$

- ▶ The lines of latitude are the curves  $\phi = \phi_0$ . The meridians (lines of longitude) are the curves  $\theta = \theta_0$ . 3D demonstration

## Example 2

- ▶ Identify the parameterized surface

$$\mathbf{r}(u, v) = 2 \cos u \mathbf{i} + v \mathbf{j} + 2 \sin u \mathbf{k}.$$

- ▶ Rewrite the parameterization as

$$x = 2 \cos u, \quad y = v, \quad z = 2 \sin u,$$

and eliminate  $u$  and  $v$  to obtain an equation in  $x, y, z$ .

- ▶ Since  $y = v$ , we can eliminate  $v$  making the substitution  $v \rightarrow y$ .
- ▶ To eliminate  $u$ , we square and add the 1st and 3rd equations. The result is  $x^2 + z^2 = 4$ . There is no  $v$  in this equation, so we are done.
- ▶ The equation  $x^2 + z^2 = 4$  represents a cylinder of radius 2 in the direction of the  $y$ -axis. (Demonstration)

## Example 3

- ▶ Use polar coordinates to parameterize the half-cone surface  $z = 2\sqrt{x^2 + y^2}$
- ▶ Making the substitutions  $x = r \cos \theta$ ,  $y = r \sin \theta$ , and setting  $r = u$ ,  $\theta = v$  we obtain the parameterization

$$\mathbf{r}(u, v) = (u \cos v, u \sin v, 2u).$$

(Demonstration)

## Graph parameterizations

- ▶ One way to parameterize surface with equation  $F(x, y, z) = 0$  is to solve for one of the variables, say  $z = f(x, y)$ . The resulting graph represents a subset of the surface in question.
- ▶ Example. Consider the unit sphere  $x^2 + y^2 + z^2 = 1$ .
- ▶ Solving for  $z$  we obtain

$$\mathbf{r}(u, v) = (u, v, \sqrt{1 - u^2 - v^2}).$$

- ▶ That the above parameterization gives only the upper hemisphere. If we wanted to represent the lower hemisphere, we would use  $z = -\sqrt{1 - x^2 - y^2}$ .
- ▶ Note that the grid corresponding to this parameterization is very different from the spherical coordinate grid. (Demonstration)

# The tangent plane

- ▶ Recall that the tangent plane is the best approximating plane to a surface at a fixed point of that surface. A surface at high magnification resembles its tangent plane.
- ▶ To calculate the tangent plane to a parametric surface  $(x, y, z) = \mathbf{r}(u, v)$ , we use the fact that the vectors

$$\mathbf{r}_u = \frac{\partial x}{\partial u} \mathbf{i} + \frac{\partial y}{\partial u} \mathbf{j} + \frac{\partial z}{\partial u} \mathbf{k}, \quad \mathbf{r}_v = \frac{\partial x}{\partial v} \mathbf{i} + \frac{\partial y}{\partial v} \mathbf{j} + \frac{\partial z}{\partial v} \mathbf{k}$$

- ▶ This is true because the gridline curve  $U(t) = \mathbf{r}(t, v_0)$  is trapped inside the surface. Hence, the velocity vector  $U'(t_0) = \mathbf{r}_u(t_0, v_0)$  is tangent to the surface. Similarly,  $\mathbf{r}_v(u_0, t_0)$  is a tangent vector because it is the velocity of the gridline curve  $V(t) = \mathbf{r}(u_0, t)$ .
- ▶ Therefore, the equation of the tangent plane at the point  $(x_0, y_0, z_0) = \mathbf{r}(u_0, v_0)$  is given by

$$((X, Y, Z) - \mathbf{r}(u_0, v_0)) \cdot \mathbf{N}(u_0, v_0) = 0,$$

where  $\mathbf{N} = \mathbf{r}_u \times \mathbf{r}_v$  is a normal vector of the given surface.



## Example 4

- ▶ Find the equation of the tangent planes to the unit sphere  $x^2 + y^2 + z^2 = 1$  using spherical coordinates.
- ▶ We are parameterizing the sphere  $S$  as

$$\mathbf{r}(\phi, \theta) = (\sin \phi \cos \theta, \sin \phi \sin \theta, \cos \phi), \quad 0 \leq \phi \leq \pi, \quad 0 \leq \theta \leq 2\pi,$$

$$\mathbf{r}_\phi = \cos \phi \cos \theta \mathbf{i} + \cos \phi \sin \theta \mathbf{j} - \sin \phi \mathbf{k}$$

$$\mathbf{r}_\theta = -\sin \phi \sin \theta \mathbf{i} + \sin \phi \cos \theta \mathbf{j}$$

- ▶ Taking the cross product gives

$$\begin{aligned} \mathbf{N} = \mathbf{r}_\phi \times \mathbf{r}_\theta &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \cos \phi \cos \theta & \cos \phi \sin \theta & -\sin \phi \\ -\sin \phi \sin \theta & \sin \phi \cos \theta & 0 \end{vmatrix} \\ &= \sin^2 \phi \cos \theta \mathbf{i} + \sin^2 \phi \sin \theta \mathbf{j} + \cos \phi \sin \phi \mathbf{k} \\ &= \sin \phi \mathbf{r}(\phi, \theta) \end{aligned}$$

- ▶ This makes sense geometrically, because on a sphere the normal at  $x, y, z$  points in the same direction as  $(x, y, z)$
- ▶ Therefore, the tangent plane at  $(x_0, y_0, z_0) \in S$  has the equation

$$x_0(X - x_0) + y_0(Y - y_0) + z_0(Z - z_0) = 0.$$

## Surface area of a graph

- ▶ Recall the formula for surface area of a graph  $z = f(x, y)$  raised above a region  $D$  in the  $xy$  plane:

$$A = \iint_D \sqrt{1 + f_x^2 + f_y^2} dA.$$

- ▶ The above integrand represents the area of a small parallelogram at position  $(x, y, f(x, y))$  lying above a small rectangle in the  $xy$  plane.
- ▶ The unit vector  $\mathbf{i}$  lifts to the vector  $\mathbf{i} + f_x\mathbf{k}$ , while the unit vector  $\mathbf{j}$  lifts to the vector  $\mathbf{j} + f_y\mathbf{k}$ .
- ▶ Therefore, the rectangle spanned by  $\Delta x\mathbf{i}$  and  $\Delta y\mathbf{j}$  lifts to the parallelogram spanned by  $\Delta x(\mathbf{i} + f_x\mathbf{k})$  and  $\Delta y(\mathbf{j} + f_y\mathbf{k})$ .
- ▶ The area of a parallelogram is equal to the magnitude of the cross product of the generating vectors. For the parallelogram in question,

$$(\mathbf{i} + f_x\mathbf{k}) \times (\mathbf{j} + f_y\mathbf{k}) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 0 & f_x \\ 0 & 1 & f_y \end{vmatrix} = (-f_x\mathbf{i} - f_y\mathbf{j} + \mathbf{k})$$

$$|(\mathbf{i} + f_x\mathbf{k}) \times (\mathbf{j} + f_y\mathbf{k})| = \sqrt{1 + f_x^2 + f_y^2}.$$

- ▶ Therefore, the area of each small parallelogram is  $\sqrt{1 + f_x^2 + f_y^2} \Delta A$  where  $\Delta A = \Delta x \Delta y$ . In the limit, as  $\Delta x, \Delta y \rightarrow 0$  we obtain the above integral.

## Surface area of a parameterized surface

- ▶ We generalize the preceding formula to an arbitrary parameterized surface  $(x, y, z) = \mathbf{r}(u, v)$ ,  $(u, v) \in D$ .
- ▶ The parameterization maps a small square with sides  $\Delta u \mathbf{i}$  and  $\Delta v \mathbf{j}$  to a parallelogram generated by the vectors  $\Delta u \mathbf{r}_u$  and  $\Delta v \mathbf{r}_v$ . This parallelogram has area  $|\mathbf{r}_u \times \mathbf{r}_v| \Delta A$  where  $\Delta A = \Delta u \Delta v$ .
- ▶ Taking the limit as  $\Delta u, \Delta v \rightarrow 0$  we obtain the following formula for the area of the parameterized surface:

$$A = \iint_D |\mathbf{r}_u \times \mathbf{r}_v| dA(u, v).$$

## Example 4 cont.

- ▶ Let's apply the formula  $A = \iint_D |\mathbf{r}_u \times \mathbf{r}_v| dA(u, v)$  to calculate the area of a sphere of radius  $R$  by using the spherical coordinate parameterization.

$$\mathbf{r}(\phi, \theta) = R(\sin \phi \cos \theta, \sin \phi \sin \theta, \cos \phi), \quad 0 \leq \phi \leq \pi, \quad 0 \leq \theta \leq 2\pi,$$

- ▶ In a preceding slide, we calculated

$$\mathbf{N} = \mathbf{r}_\phi \times \mathbf{r}_\theta = R^2 \sin \phi (\sin \phi \cos \theta \mathbf{i} + \sin \phi \sin \theta \mathbf{j} + \cos \phi \mathbf{k}).$$

- ▶ It follows that

$$\begin{aligned} |\mathbf{N}| &= R^2 \sin \phi \\ A &= R^2 \int_{\theta=0}^{2\pi} \int_{\phi=0}^{\pi} \sin \phi \, d\phi \, d\theta \\ &= 2\pi R^2 \times \left[ -\cos \phi \right]_0^\pi = 4\pi R^2 \end{aligned}$$