

A PRIMER FOR THE FIBONACCI NUMBERS — PART IV

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1. INTRODUCTION

In the primer, Part III, it was noted that if $V = (x, y)$ is a two-dimensional vector and A is a 2 by 2 matrix, $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, then $V' = AV$ is a two-dimensional vector, $V' = (x', y') = (ax + by, cx + dy)$. Here, V and consequently V' , are expressed as column vectors. The matrix A is said to transform, or map, the vector V onto the vector V' . The matrix A is called the mapping matrix or transformation matrix.

2. SOME MAPPING MATRICES

The zero matrix, $Z = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$, maps every vector V onto the zero vector $\phi = (0, 0)$.

The identity matrix, $I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ maps every vector V onto itself; that is, $IV = V$.

The matrix $B = \begin{pmatrix} 1 & 1 \\ 2 & 2 \end{pmatrix}$ maps vectors $V = (k, -k)$, (k any real number), onto the zero vector ϕ . Such a mapping as determined by B is called a many-to-one mapping.

If the only vector mapped onto ϕ is the vector ϕ itself, the mapping is a one-to-one mapping. A matrix A determines a one-to-one mapping of two-dimensional vectors onto two-dimensional vectors if, and only if, $\det A \neq 0$. If $\det A \neq 0$, for each vector U , there exists a vector V such that $AV = U$. Note, however, that for matrix B above, $B \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x + y \\ 2x + 2y \end{pmatrix}$. There is no vector V such that $BV = (0, 1)$.

3. GEOMETRIC INTERPRETATIONS OF 2x2 MATRICES AND 2-DIMENSIONAL VECTORS

As in Primer III, the vector $V = (x, y)$ is interpreted as a point in a rectangular coordinate system. Thus the geometric concepts of length, direction, slope and angle are associated with the vector V .

A non-zero scalar multiple of the identity matrix, kI , maps the vector $U = (a, b)$ onto the vector $V = (ka, kb)$. The length of V , $|V|$, is equal to $|k| |U|$. There is no change in slope but if $k < 0$ the sense or direction is reversed.

The matrix $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ maps a vector onto the reflection vector with respect to the line through the origin with slope one. Note that different vectors may be rotated through different angles!

The matrix $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ preserves the first component of a vector while annihilating the second component. Every vector $U = (x,y)$ is mapped into a vector on the x-axis.

The matrix $R = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ rotates all vectors through the same angle θ (theta), in a counterclockwise direction if theta is a positive angle. There is no change in length. This seems to contradict the notion of a matrix having vectors whose slopes are not changed but in this case the characteristic values are complex; thus, there are no real characteristic vectors.

4. THE CHARACTERISTIC VECTORS OF THE Q-MATRIX

The Q matrix $\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$ does not generally preserve the length of a vector $U = (x,y)$. Also, different vectors are in general rotated through different angles.

The characteristic equation of the Q matrix is

$$\lambda^2 - \lambda - 1 = 0$$

with roots

$$\lambda_1 = \frac{1 + \sqrt{5}}{2} \quad \text{and} \quad \lambda_2 = \frac{1 - \sqrt{5}}{2} \quad ,$$

which are the characteristic roots, or eigenvalues, for Q.

To solve for a pair of corresponding characteristic vectors consider

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \lambda \begin{pmatrix} x \\ y \end{pmatrix} , \quad x^2 + y^2 \neq 0 \quad .$$

Then

$$(1 - \lambda)x + y = 0 \quad .$$

Thus, a pair of characteristic vectors are

$$X_1 = (\lambda_1 x, x) \quad , \quad |X_1| \neq 0 \quad ,$$

with slope

$$m_1 = \frac{\sqrt{5} - 1}{2} \quad \text{and} \quad X_2 = (\lambda_2 x, x) \quad , \quad |X_2| \neq 0 \quad ,$$

with slope

$$m_2 = - \left(\frac{\sqrt{5} + 1}{2} \right) \quad .$$

What happens when the matrix Q^2 is applied to the characteristic vectors X_1 and X_2 of matrix Q ? Since

$$Q^2 X_1 = Q(QX_1) = Q(\lambda X_1) = \lambda QX_1 = \lambda^2 X_1 \quad ,$$

clearly X_1 is a characteristic vector of the matrix Q^2 as well as a characteristic vector of matrix Q . The characteristic roots of Q^2 are the squares of the characteristic roots of matrix Q . In general if λ_1 and λ_2 are the characteristic roots of Q then λ_1^n and λ_2^n are the characteristic roots of Q^n . But the characteristic equation for Q^n is

$$\lambda^2 - (F_{n+1} + F_{n-1})\lambda + (F_{n+1}F_{n-1} - F_n^2) = 0 \quad .$$

Recalling that $L_n = F_{n+1} + F_{n-1}$, $F_{n+1}F_{n-1} - F_n^2 = (-1)^n$, and $L_n^2 = 5F_n^2 + 4(-1)^n$, it follows that, since $\lambda_1 = \alpha = (1 + \sqrt{5})/2$ and $\lambda_2 = \beta = (1 - \sqrt{5})/2$,

$$\alpha^n = \lambda_1^n = (L_n + \sqrt{5}F_n)/2 \quad \text{and} \quad \beta^n = \lambda_2^n = (L_n - \sqrt{5}F_n)/2 \quad .$$

5. FIBONACCI AND LUCAS VECTORS AND THE Q MATRIX

Let $U_n = (F_{n+1}, F_n)$ and $V_n = (L_{n+1}, L_n)$ be denoted as Fibonacci and Lucas vectors, respectively. We note

$$\begin{aligned} |U_n|^2 = F_{n+1}^2 + F_n^2 = F_{2n+1} \quad \text{and} \quad |V_n|^2 = L_{n+1}^2 + L_n^2 &= (5F_{n+1}^2 + (-1)^{n+1}4 + 5F_n^2 \\ &+ (-1)^n 4) = 5(F_{n+1}^2 + F_n^2) = 5F_{2n+1}. \end{aligned}$$

It is well known that the slopes of the vectors U_n and V_n (the ratios F_n/F_{n+1} and L_n/L_{n+1}) approach the slope, $(\sqrt{5} - 1)/2$, of the characteristic vector, X_1 .

Since $Q^m Q^n = Q^{m+n}$, it is easy to verify that

$$F_{m+1}F_{n+1} + F_m F_n = F_{m+n+1}$$

by equating elements in the upper left in the above matrix equation. In a similar manner it follows that

$$F_{m+1}F_{n+2} + F_m F_{n+1} = F_{m+n+2}$$

$$F_{m+1}F_n + F_m F_{n-1} = F_{m+n}$$

Adding these two equations and using $L_{n+1} = F_{n+2} + F_n$ it follows that

$$F_{m+1}L_{n+1} + F_m L_n = L_{m+n+1} \quad .$$

From the above identities it is easy to verify that

$$\begin{aligned} Q^{n+1}V_0 &= QV_n = V_{n+1} \quad , \\ Q^{n+1}U_0 &= QU_n = U_{n+1} \quad , \\ Q^nV_m &= V_{m+n+1} \quad , \\ Q^nU_m &= U_{m+n+1} \quad . \end{aligned}$$

6. A SPECIAL MATRIX

Let $P = \begin{pmatrix} 1 & 2 \\ 2 & -1 \end{pmatrix}$, then from

$$\begin{aligned} L_{n+1} &= F_{n+1} + 2F_n \quad , \quad L_n = 2F_{n+1} - F_n \quad , \\ 5F_{n+1} &= L_{n+1} + 2L_n \quad , \quad 5F_n = 2L_{n+1} - L_n \quad , \end{aligned}$$

it follows that

$$\begin{aligned} PU_n &= (F_{n+1} + 2F_n, 2F_{n+1} - F_n) = V_n \\ PV_n &= (L_{n+1} + 2L_n, 2L_{n+1} - L_n) = 5U_n \end{aligned}$$

Also

$$\begin{aligned} PQ^n &= \begin{pmatrix} 1 & 2 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} F_{n+1} & F_n \\ F_n & F_{n-1} \end{pmatrix} = \begin{pmatrix} L_{n+1} & L_n \\ L_n & L_{n-1} \end{pmatrix} \\ P^2Q^n &= 5Q^n \\ D \begin{pmatrix} L_{n+1} & L_n \\ L_n & L_{n-1} \end{pmatrix} &= D(P)D(Q^n) = 5(-1)^{n+1} \end{aligned}$$

We now discuss two geometric properties of matrix P . Let $U = (x, y)$, $|U|^2 = x^2 + y^2 \neq 0$.

$$PU = (x + 2y, 2x - y) \quad |PU|^2 = 5(x^2 + y^2) = 5|U|^2$$

Thus matrix P magnifies each vector length by $\sqrt{5}$.

If $\tan \alpha = y/x$, we say $\alpha = \text{Tan}^{-1} y/x$, read " α is an angle whose tangent is y/x ." Let $\tan \alpha = y/x$ and $\tan \beta = (2x - y)/(x + 2y)$. From $\tan(\alpha + \beta) = (\tan \alpha + \tan \beta)/(1 - \tan \alpha \tan \beta)$ we may now see what effect P has on the slope of vector $U = (x, y)$.

Now (recalling $x^2 + y^2 \neq 0$ says x and y are not both zero at the same time.)

$$\tan(\alpha + \beta) = \tan\left(\tan^{-1} \frac{y}{x} + \tan^{-1} \frac{2x - y}{x + 2y}\right) = \frac{2(x^2 + y^2)}{x^2 + y^2}$$

Thus, since $x^2 + y^2 \neq 0$, then

$$\tan(\alpha + \beta) = 2.$$

What does this mean? Consider two vectors A and B , the first inclined at an angle α with the positive x -axis and the second inclined at an angle β with the positive x -axis and the angles are measured positively in the counterclockwise direction. The angle bisector, ψ , of the angle between vectors A and B is such that $\alpha - \psi = \psi - \beta$ whether or not α is greater than β or the other way around. Solving for ψ yields

$$\psi = (\alpha + \beta)/2.$$

Thus ψ is the arithmetic average of α and β . Also we note that $\alpha + \beta = 2\psi$. The tangent of double the angle is given by

$$\tan 2\psi = (2 \tan \psi)/(1 - \tan^2 \psi).$$

Let

$$\tan \psi = \frac{\sqrt{5} - 1}{2},$$

then it is an easy exercise in algebra to find $\tan 2\psi = 2$, but $\tan(\alpha + \beta) = 2$, therefore we would like to conclude that the angle bisector between vectors U and PU is precisely one whose slope is $(\sqrt{5} - 1)/2$, but this is the slope of X_1 , the characteristic vector of Q . Can you show that X_1 is also a characteristic vector of P ?

We have shown

Theorem 1. The matrix $P = \begin{pmatrix} 1 & 2 \\ 2 & -1 \end{pmatrix}$ maps a vector $U = (x, y)$ into a vector PU such that

$$(1) \quad |P(U)| = \sqrt{5} |U|$$

and

(2) The angle bisector of the angle between the vector U and the vector PU is X_1 , a characteristic vector of Q and P . Thus Matrix P reflects vector U across vector X_1 .

Theorem 2. The vectors U_n and V_n are equally inclined to the vector X_1 whose slope is $(\sqrt{5} - 1)/2$.

Corollary. The vectors V_n are mapped into vectors $\sqrt{5} U_n$ by P and the vectors U_n are mapped into V_n by P .

7. SOME INTERESTING ANGLES

An interesting theorem is

Theorem 3.

$$\begin{aligned} \text{Tan} \left\{ \text{Tan}^{-1} \frac{L_n}{L_{n+1}} - \text{Tan}^{-1} \frac{L_{n+1}}{L_{n+2}} \right\} &= \frac{(-1)^n}{F_{2n+2}} \\ \text{Tan} \left\{ \text{Tan}^{-1} \frac{F_n}{F_{n+1}} - \text{Tan}^{-1} \frac{F_{n+1}}{F_{n+2}} \right\} &= \frac{(-1)^{n+1}}{F_{2n+2}} \end{aligned}$$

Theorem 4.

$$\text{Tan}^{-1} \frac{F_n}{F_{n+1}} = \sum_{m=1}^n (-1)^{m+1} \text{Tan}^{-1} \frac{1}{F_{2m}} .$$

We proceed by mathematical induction. For $n = 1$, it is easy to verify $\text{Tan}^{-1} 1 = \text{Tan}^{-1}(1/F_2)$.

Assume true for $n = k$, that is

$$\text{Tan}^{-1} \frac{F_k}{F_{k+1}} = \sum_{m=1}^k (-1)^{m+1} \text{Tan}^{-1} \frac{1}{F_{2m}}$$

But, by Theorem 3,

$$\text{Tan}^{-1} \frac{F_{k+1}}{F_{k+2}} = \text{Tan}^{-1} \frac{F_k}{F_{k+1}} + \text{Tan}^{-1} \frac{(-1)^k}{F_{2k+2}}$$

Thus, if

$$\text{Tan}^{-1} \frac{F_k}{F_{k+1}} = \sum_{m=1}^k (-1)^{m+1} \text{Tan}^{-1} \frac{1}{F_{2m}}$$

then

$$\begin{aligned} \text{Tan}^{-1} \frac{F_{k+1}}{F_{k+2}} &= \sum_{m=1}^k (-1)^{m+1} \text{Tan}^{-1} \frac{1}{F_{2m}} + \text{Tan}^{-1} \frac{(-1)^k}{F_{2k+2}} \\ &= \sum_{m=1}^{k+1} (-1)^{m+1} \text{Tan}^{-1} \frac{1}{F_{2m}} \end{aligned}$$

because $\text{Tan}^{-1}(-X) = -\text{Tan}^{-1}X$ and $(-1)^k = (-1)^{k+2}$ and the proof is complete.

8. AN EXTENDED RESULT

Theorem 5. The series

$$A = \sum_{m=1}^{\infty} (-1)^{m+1} \tan^{-1} \frac{1}{F_{2m}}$$

converges and $A = \tan^{-1} (\sqrt{5} - 1)/2$.

Proof: Since the series is an alternating series, and, since $\tan^{-1} X$ is a continuous increasing function, then

$$\tan^{-1} \frac{1}{F_{2n}} > \tan^{-1} \frac{1}{F_{2n+2}} \text{ and } \tan^{-1} 0 = 0 .$$

The angle A must lie between the partial sums S_N and S_{N+1} for every $N > 2$ by the error bound in the alternating series, but $S_N = \tan^{-1} (F_N / F_{N+1})$. Thus the angles of U_N and U_{N+1} lie on opposite sides of A . By the continuity of $\tan^{-1} X$ then

$$\lim_{n \rightarrow \infty} \tan^{-1} (F_n / F_{n+1}) = A = \tan^{-1} (\sqrt{5} - 1)/2 .$$

Comment: The same result can be obtained simply from

$$\tan \left\{ \tan^{-1} \frac{F_n}{F_{n+1}} - \frac{\sqrt{5} - 1}{2} \right\} = (-1)^{n+1} \left(\frac{\sqrt{5} - 1}{2} \right)^{2n+1} .$$

Which slope gives a better numerical approximation to $\frac{\sqrt{5} - 1}{2}$, F_n / F_{n+1} or L_n / L_{n+1} ? Hmmm?

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