

Canada Research Chairs

Towards a Data Assimilative Physical-Biogeochemical Ocean Model

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COMPLEX DATA

Motivation

Chaires de recherche du Canada

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The use of High Performance Computing (HPC) facilities allows for the implementation of computationally intensive statistical data assimilation techniques. We want to employ some of these techniques to assimilate temporal/spatial observations into a realistic one-dimensional ocean model. The model is based on partial differential equations (PDEs) and simulates physical and biogeochemical ocean properties.

Our goals:

· creating a biogeochemical model for the Bermuda region in the North Atlantic Ocean embedded within a ocean turbulence model,

 using ensemble-based statistical data assimilation techniques to incorporate physical. biological and chemical data into the model,

 making use of HPC techniques that allow an ensemble of model simulations and a data assimilation procedure to be run in parallel on an HPC cluster.

Observations

The Bermuda Atlantic Time-series Study (BATS) is a long-term monitoring program at a site in the western gyre of the Sargasso Sea, 50 nautical miles southeast of Bermuda. The observational data may be retrieved from the world-wide-web at http://bats.bbsr.edu/. For overview of the BATS study, see Steinberg et al. (2001).

Currently we examine the 183 available core cruises. These encompass the period from October 1988 to December 2003 with approximately one cruise per month. We consider measurements at depths ranging from 0 to 4300 m. Our variables of interest are physical and optical measurements from sensors like CTD, and biological and chemical variables measured on water samples that have been collected in Niskin bottles.



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Physical Model

In order to simulate fluid motion and the effects of turbulent mixing on the distribution of the biological state variables we use the General Ocean Turbulence Model (GOTM, http://www.gotm.net). GOTM is written in Fortran 90/95. It includes different turbulence parameterizations as options for dynamic, spatially one-dimensional simulations of the upper ocean.

The core set of PDEs in GOTM describes transport of momentum, temperature and salinity as follows:



Here u and v are the current velocities in east-west and north-south directions, respectively. T denotes temperature and S salinity. The terms fu and fv denote the influence of the Coriolis force on current velocities. Fu and Fu represent pressure gradients and surface wind forcing. F_{τ} and F_{s} are the sources and sinks for T and S due to heating and cooling and precipitation and evaporation at the sea surface. K, is the turbulent viscosity for u and v, and K, is the turbulent diffusivity for T and S. GOTM includes a variety of turbulence model options to compute these diffusivities.

Biological state variables that are integrated into GOTM become subject to turbulent mixing as follows:

(5)
$$\frac{\partial X}{\partial t} - \frac{\partial}{\partial z} \left(K_t' \frac{\partial X}{\partial z} \right) = SMS(X)$$

Where $X \in \{Phy, Det, DIN, Chl\}$ denotes one of the biological state variables. SMS(X) models the sources and sinks of X and has the same functional form as the right hand side of the biological equations (6)-(9).

Our biological model is a simplified version of the model of Fennel et al. (2006) and includes 4 state variables in a system of PDEs: phytoplankton biomass (Phy), phytoplankton chlorophyll (Chl), detritus (Det) and dissolved inorganic nitrogen (DIN). The biological equations (6) - (9) describe the sources and sinks of our bio-chemical variables due to bio-chemical transformations. They are coupled with our physical model through equation (5) above.

(6)
$$\frac{\partial Phy}{\partial t} = \mu Phy - m_p Phy - w_p \frac{\partial Phy}{\partial z}$$

(7) $\frac{\partial Det}{\partial t} = m_p Phy - r_p Det - w_p \frac{\partial Det}{\partial z}$

∂t

Variable	Description	Units
Phy	Phytoplankton	mmol N m ⁻³
Det	Detritus	mmol N m ⁻³
DIN	Dissolved Inorganic Nitrogen	mmol N m ⁻³
Chl	Chlorophyll	mg m ⁻³
r _D	Remineralization rate	d-1
w _D , w _P	Sinking Velocity	m/d



Biological Model

(8)
$$\frac{\partial DIN}{\partial t} = -\mu Phy + r_D Det$$

(9) $\frac{\partial Chl}{\partial t} = \rho_{Chl} \mu Chl - m_p Chl - w_p \frac{\partial Chl}{\partial \tau}$

Here μ is a parameterization for photosynthetic growth of phytoplankton that depends in the availability of light and nutrients.



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Idea: combine measurements and dynamical models to estimate model state and model parameters

Examples: Optimize

- biological parameters like phytoplankton growth and mortality
- dynamical terms like the vertical flux of organic matter initial or boundary conditions
- Estimate and Forecast
 - · the time evolving physical and biogeochemical state.

Framework: nonlinear and nonGaussian state space models

Approach: sampling-based solutions using sequential Monte Carlo methods, e.g. ensemble Kalman filter, particle filters (see Dowd 2007).

Computational Issues

Ensemble-based methods require many numerical model integrations (>10²-10³), hence, they are computationally expensive for realistic applications.

BUT: Ensemble-based methods should scale extremely well in massive parallel computing environments, especially when compared to iterative variational optimization methods (the most commonly used approach for assimilation in biological and physical ocean modelling at present).

Possible computational model: each of the 10² - 10³ simulations are assigned to one CPU core.

Communication between cores is only necessary during analysis steps, when observations are ingested and the state of ensemble members is updated (i.e. assimilation steps).

References and Acknowledgments

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