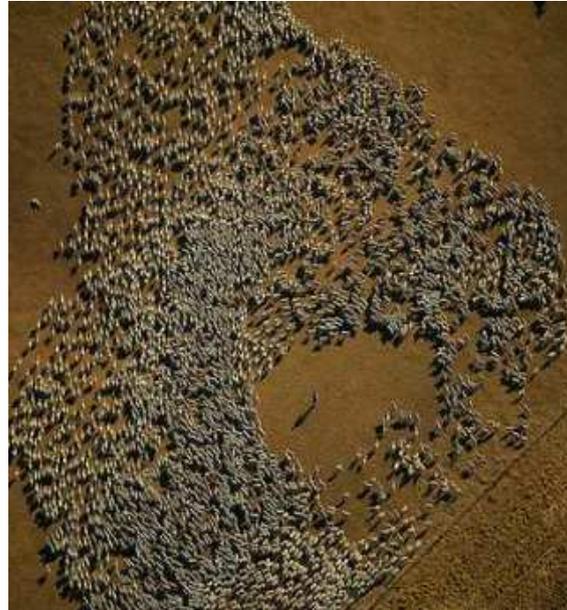


# Aggregation model and related topics



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# Aggregation model

We consider a simple model of particle interaction,

$$\frac{dx_j}{dt} = \frac{1}{N} \sum_{\substack{k=1, \dots, N \\ k \neq j}} F(|x_j - x_k|) \frac{x_j - x_k}{|x_j - x_k|}, \quad j = 1 \dots N \quad (1)$$

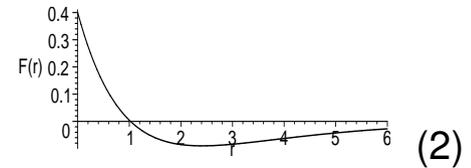
- Models insect aggregation [Edelstein-Keshet et al, 1998] such as locust swarms [Topaz et al, 2008]; robotic motion [Gazi, Passino, 2004].
- Interaction force  $F(r)$  is of **attractive-repelling type**: the insects repel each other if they are too close, but attract each-other at a distance.
- Note that acceleration effects are ignored as a first-order approximation.
- Mathematically  $F(r)$  is positive for small  $r$ , but negative for large  $r$ .
- Alternative formulation: (1) is a gradient flow of the minimization problem

$$\min E(x_1, \dots, x_N) \quad \text{where} \quad E = \sum \sum P(|x_i - x_j|) \quad \text{with} \quad F(r) = -P'(r).$$

# Confining vs. spreading

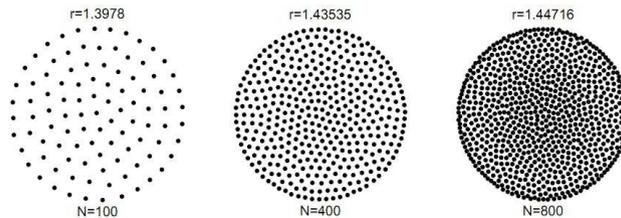
- Consider a **Morse interaction force**:

$$F(r) = \exp(-r) - G \exp(-r/L); \quad G < 1, L > 1$$



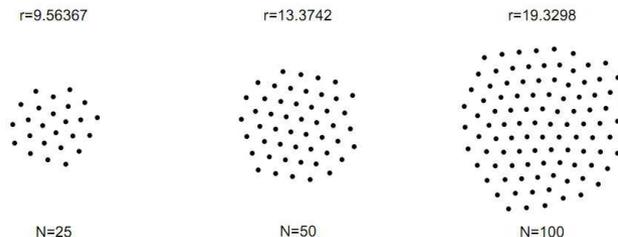
- If  $GL^3 > 1$ , the morse potential is **confining** (or catastrophic): doubling  $N$  doubles the density but cloud volume is unchanged:

$$G = 0.5, \quad L = 2$$



- If  $GL^3 < 1$ , the system is **non-confining** (or h-stable): doubling  $N$  doubles the cloud volume but density is unchanged:

$$G = 0.5, \quad L = 1.2$$



# Continuum limit

- For confining potentials, we can take the continuum limit as the number of particles  $N \rightarrow \infty$ .

- We define the **density**  $\rho$  as

$$\int_D \rho(x) dx \approx \frac{\text{\#particles inside domain } D}{N}$$

- The flow is then characterized by density  $\rho$  and velocity field  $v$ :

$$\rho_t + \nabla \cdot (\rho v) = 0; \quad v(x) = \int_{\mathbb{R}^n} F(|x - y|) \frac{x - y}{|x - y|} \rho(y) dy. \quad (3)$$

- Variational formulation: Let

$$E[\rho] := \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} \rho(x) \rho(y) P(|x - y|) dx dy; \quad P'(r) = -F(r) \quad (4)$$

Then (3) is the gradient flow of  $E$ ; minima of  $E$  are stable equilibria of (3).

- Questions

1. Describe the equilibrium cloud shape in the limit  $t \rightarrow \infty$
2. What about dynamics?

# Turing analysis in 1D:

$$\rho_t + \nabla \cdot (v\rho) = 0; \quad v = K * \rho, \quad K(x) = F(|x|) \text{sign}(x). \quad (5)$$

- Note that  $K * 1 = 0$  (since kernel  $K$  is odd) so that  $\rho \equiv 1$  is a steady state.
- Linearize around homogeneous state  $\rho = 1$  :

$$\begin{aligned} \rho(x, t) &= 1 + \phi(x, t), \quad \phi \ll 1 \\ \phi_t + (K * \phi)_x &= 0 \end{aligned}$$

- Plug in  $\phi = e^{\lambda t} e^{imx}$  :

$$\begin{aligned} K * \exp(imx) &= \int_{-\infty}^{\infty} F(|y|) \text{sign}(y) \exp(imx - imy) dy \\ &= \exp(imx) \int_{-\infty}^{\infty} \underbrace{F(|y|) \text{sign}(y)}_{\text{odd}} \left\{ \underbrace{\cos(imy)}_{\text{even}} - i \underbrace{\sin(imy)}_{\text{odd}} \right\} dy \\ &= -2i \exp(imx) \int_0^{\infty} F(y) \sin(my) dy \end{aligned}$$

$$\boxed{\lambda = -2m \int_0^{\infty} F(y) \sin(my) dy}$$

- **Conclusion: The homogeneous state is stable if and only if**  
 $\int_0^\infty F(y) \sin(my) dy > 0$  **for all**  $m > 0$ .
- In particular, **patterns form** (w.r.t. low frequencies) if  $\int_0^\infty F(y)y dy < 0$ .
- **Patterns form when the constant state is unstable!**
- In the case of the repulsive-attractive morse potential:

$$F(r) = \exp(-r) - G \exp(-r/L); \quad G < 1, L > 1$$

$$\lambda(m) = -2m^2 \left( \frac{1}{m^2 + 1} - \frac{G}{m^2 + \left(\frac{1}{L}\right)^2} \right)$$

$$\lambda(0) = -2(1 - GL^2)$$

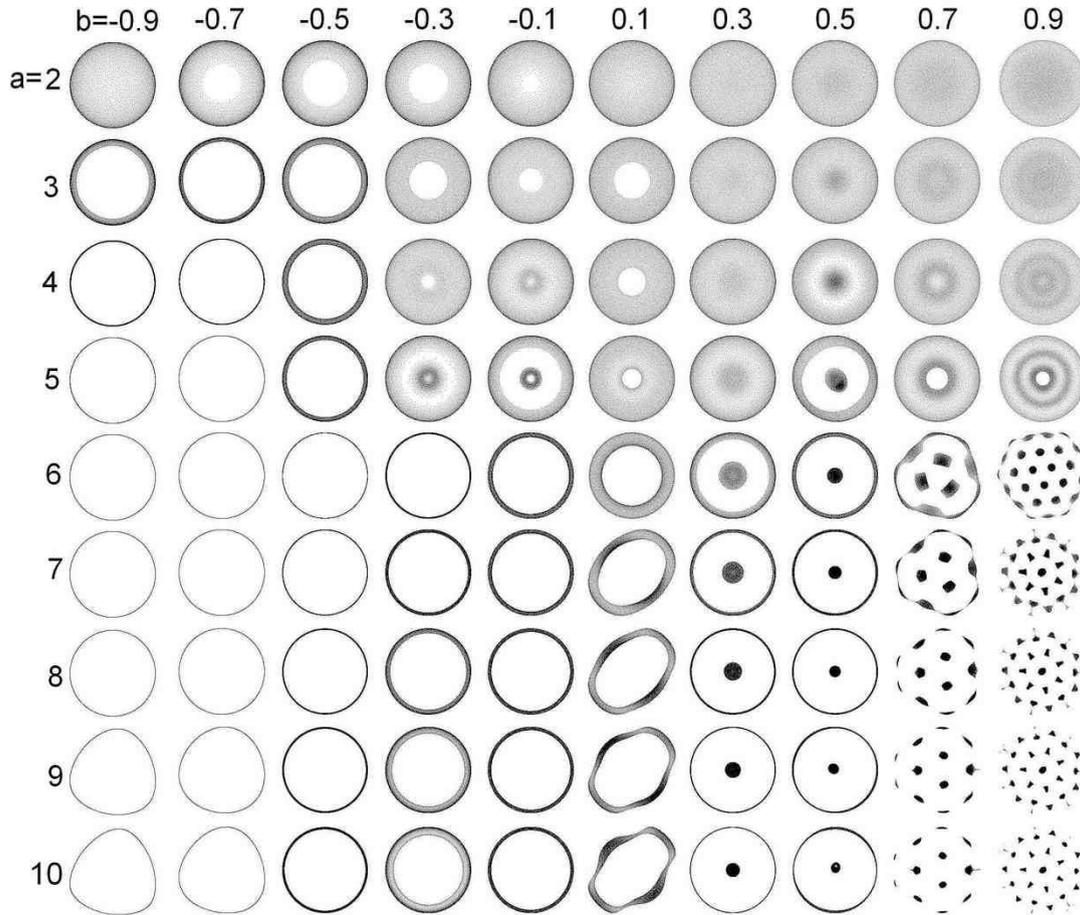
- Conclusions:
  - Homogenous state is unstable iff  $GL^2 > 1$
  - Confining potential [i.e. “catostrophic case” iff  $GL^2 > 1$ ].

## Turing in any dimension $d$

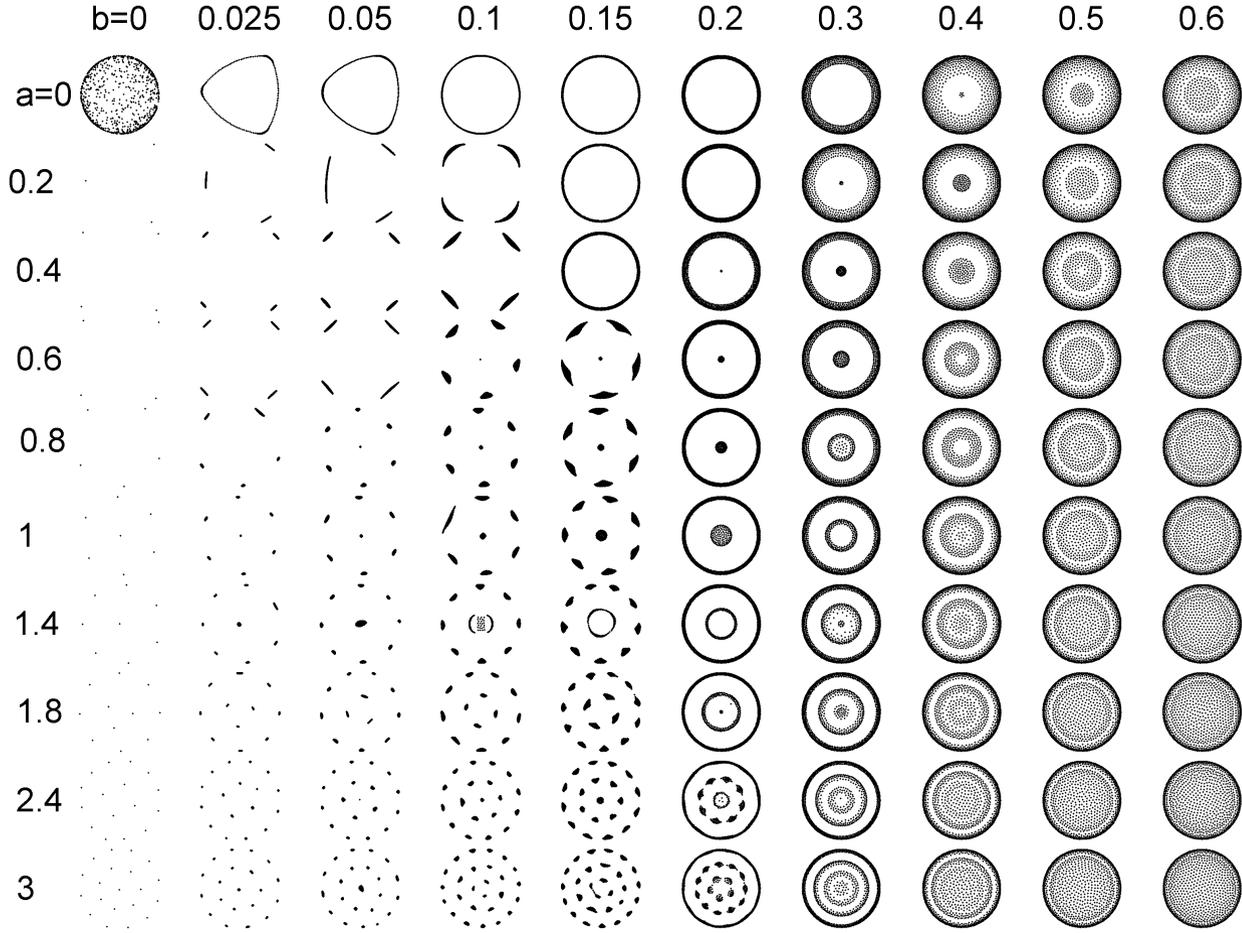
- Exercise: In dimension  $d$ , homogeneous state is unstable (wrt small  $m$ ) when  $\int_0^\infty F(r)r^d dr < 0$ .
- For Morse force, confining potential if  $GL^{d+1} > 1$ .

# Complex patterns:

$$F(r) = \tanh((1-r)a) + b; \quad 0 < a; \quad -1 < b < 1.$$



**PW-linear force:**  $F(r) = \min(ar + b, 1 - r)$



# Ring-type steady states

- Seek steady state of the form  $x_j = r (\cos (2\pi j/N), \sin (2\pi j/N))$ ,  $j = 1 \dots N$ .
- In the limit  $N \rightarrow \infty$  **the radius of the ring must be the root of**

$$I(r) := \int_0^{\pi/2} F(2r \sin \theta) \sin \theta d\theta = 0. \quad (6)$$

- For Morse force  $F(r) = \exp(-r) - G \exp(-r/L)$ , such root exists whenever  $GL^2 > 1$  [coincides with 1D catastrophic regime]
- For general repulsive-attractive force  $F(r)$ , a ring steady state exists if  $F(r) \leq C < 0$  for all large  $r$ .
- Even if the ring steady-state exists, the time-dependent problem can be ill-posed!

# Continuum limit for curve solutions

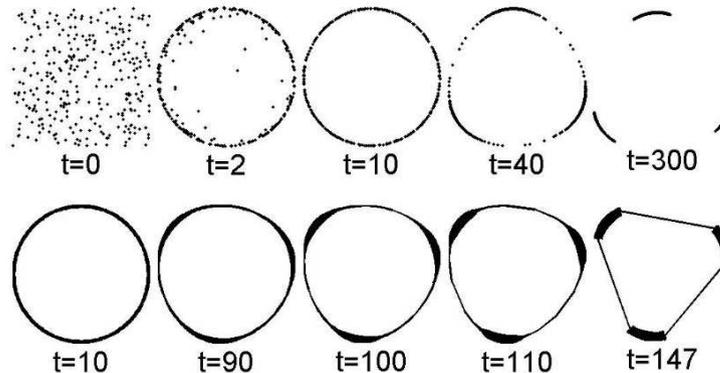
- If particles concentrate on a curve, in the limit  $N \rightarrow \infty$  we obtain

$$\rho_t = \rho \frac{\langle z_\alpha, z_{\alpha t} \rangle}{|z_\alpha|^2}; \quad z_t = K * \rho \quad (7)$$

where  $z(\alpha; t)$  is a parametrization of the solution curve;  $\rho(\alpha; t)$  is its density and

$$K * \rho = \int F(|z(\alpha') - z(\alpha)|) \frac{z(\alpha') - z(\alpha)}{|z(\alpha') - z(\alpha)|} \rho(\alpha', t) dS(\alpha'). \quad (8)$$

- Depending on  $F(r)$  and initial conditions, the curve evolution may be **ill-defined!**
  - For example a circle can degenerate into an annulus, gaining a dimension.
- We used a Lagrange particle-based numerical method to resolve (7).
  - Agrees with direct simulation of the ODE system (1):



# Local stability of a ring

- Turing-type analysis (linearization around the ring solution)
- Direct approach for ODE linearization:

$$x_k = r_0 \exp(2\pi i k/N) (1 + \exp(t\lambda)\phi_k), \quad \phi_k \ll 1.$$

- After some algebra:

$$\lambda\phi_j = \frac{1}{N} \sum_{k \neq j} G_+ \left( \frac{\pi(k-j)}{N} \right) \left( \phi_j - \phi_k \exp \left( \frac{2\pi i(k-j)}{N} \right) \right) \\ + G_- \left( \frac{\pi(k-j)}{N} \right) \left( \bar{\phi}_k - \bar{\phi}_j \exp \left( \frac{2\pi i(k-j)}{N} \right) \right),$$

$$G_+ = \frac{1}{2} F'(2r_0 |\sin \theta|) + \frac{F(2r_0 |\sin \theta|)}{4r_0 |\sin \theta|}; \quad G_- = \frac{1}{2} F'(2r_0 |\sin \theta|) - \frac{F(2r_0 |\sin \theta|)}{4r_0 |\sin \theta|}.$$

- Ansatz:

$$\phi_j = b_+ e^{2m\pi i j/N} + b_- e^{-2m\pi i j/N}$$

$$\lambda \begin{pmatrix} b_+ \\ b_- \end{pmatrix} = M(m) \begin{pmatrix} b_+ \\ b_- \end{pmatrix}, \quad M(m) := \begin{bmatrix} I_1(m) & I_2(m) \\ I_2(m) & I_1(-m) \end{bmatrix}; \quad m = 1, 2, \dots; \quad (9)$$

$$I_1(m) = \frac{4}{N} \sum_{l=1}^{N/2} G_+ \left( \frac{\pi l}{N} \right) \sin^2 \left( (m+1) \frac{\pi l}{N} \right);$$

$$I_2(m) = \frac{4}{N} \sum_{l=1}^{N/2} G_- \left( \frac{\pi l}{N} \right) \left[ \sin^2 \left( \frac{\pi l}{N} \right) - \sin^2 \left( m \frac{\pi l}{N} \right) \right].$$

- Taking the limit  $N \rightarrow \infty$ , we obtain

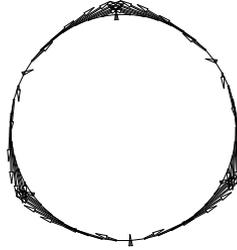
$$I_1(m) = \frac{2}{\pi} \int_0^{\frac{\pi}{2}} \left[ \frac{F(2r \sin \theta)}{2r \sin \theta} + F'(2r \sin \theta) \right] \sin^2((m+1)\theta) d\theta; \quad (10a)$$

$$I_2(m) = \frac{2}{\pi} \int_0^{\frac{\pi}{2}} \left[ \frac{F(2r \sin \theta)}{2r \sin \theta} - F'(2r \sin \theta) \right] [\sin^2(m\theta) - \sin^2(\theta)] d\theta. \quad (10b)$$

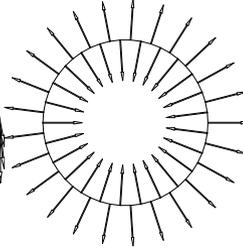
- Eigenfunction is a pure fourier mode when projected to the curvilinear coordinates of

the circle.

$m=3, N=50, \lambda=0.05$



$m=25, N=50, \lambda=-1.17$



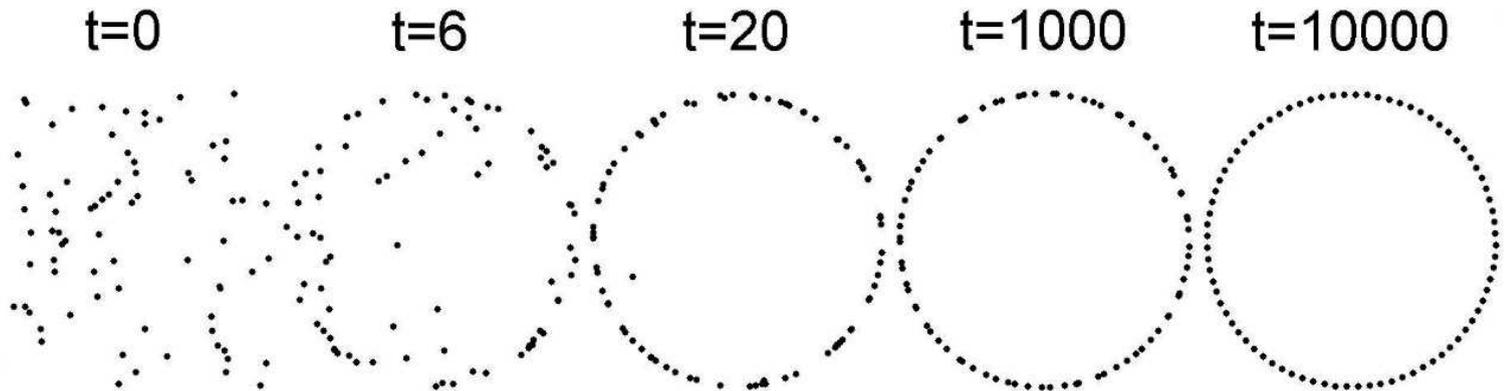
# Quadratic force $F(r) = r - r^2$

- Computing explicitly,

$$\text{tr } M(m) = -\frac{(4m^4 - m^2 - 9)}{(4m^2 - 1)(4m^2 - 9)} < 0, \quad m = 2, 3, \dots$$

$$\det M(m) = \frac{3m^2(2m^2 + 1)}{(4m^2 - 9)(4m^2 - 1)^2} > 0, \quad m = 2, 3, \dots$$

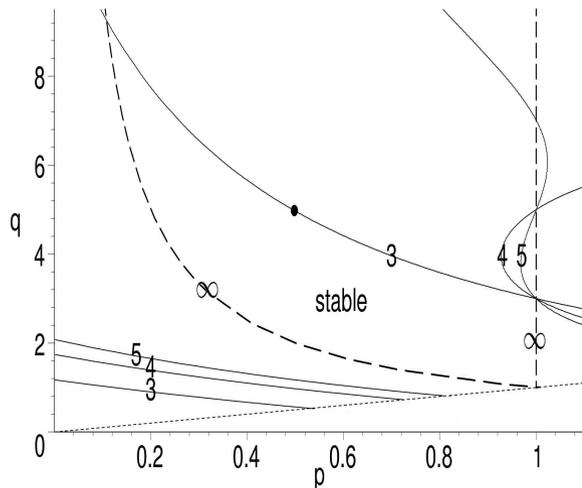
- Conclusion: **ring pattern corresponding to  $F(r) = r - r^2$  is locally stable**
- For large  $m$ , the two eigenvalues are  $\lambda \sim -\frac{1}{4}$  and  $\lambda \sim -\frac{3}{8m^2} \rightarrow 0$  as  $m \rightarrow \infty$ . The presence of arbitrary small eigenvalues implies the existence of very slow dynamics near the ring equilibrium.



# General power force

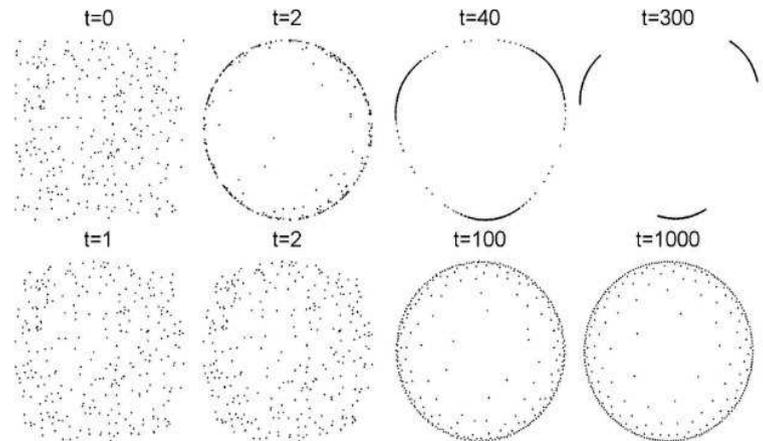
$$F(r) = r^p - r^q, \quad 0 < p < q$$

- The mode  $m = \infty$  is stable if and only if  $pq > 1$  and  $p < 1$ .
- Stability of other modes can be expressed in terms of Gamma functions.
- The dominant unstable mode corresponds to  $m = 3$ ; the boundary is given by
 
$$0 = 723 - 594(p + q) - 27(p^2 + q^2) - 431pq + 106(pq^2 + p^2q) + 19(p^3q + pq^3) + 10(p^3q^2 + p^2q^3) + 6(p^3 + q^3) + p^3q^3;$$
- Boundaries for  $m = 4, 5, \dots$  are similarly expressed in terms of higher order polynomials in  $p, q$ .



(0.5, 6)

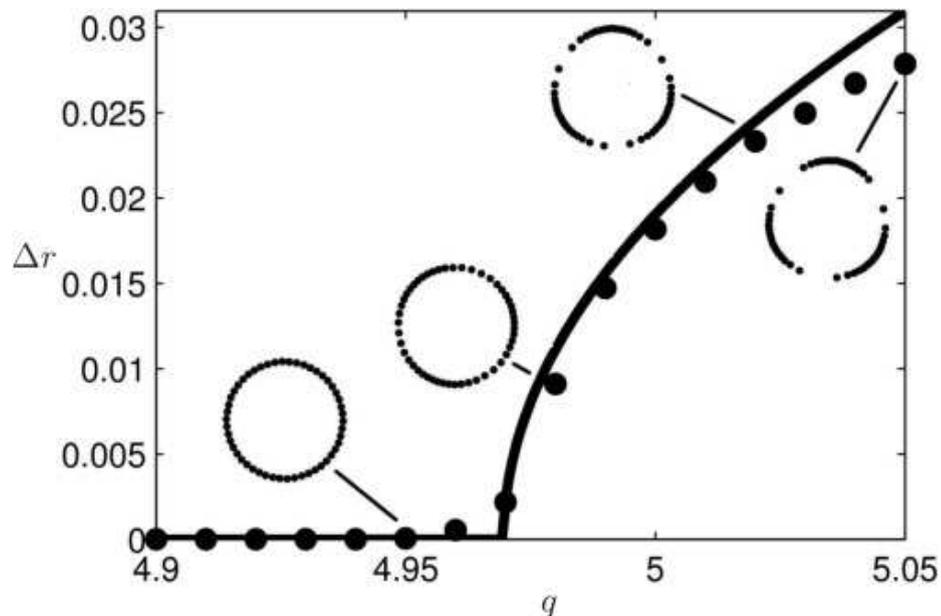
(0.5, 1.5)



# Weakly nonlinear analysis

- Near the instability threshold, higher-order analysis shows a **supercritical pitchfork bifurcation**, whereby a ring solution bifurcates into an  $m$ -symmetry breaking solution
- This shows existence of nonlocal solutions.
- Example:  $F(r) = r^{1.5} - r^q$ ; bifurcation  $m = 3$  occurs at  $q = q_c \approx 4.9696$ ; nonlinear analysis predicts

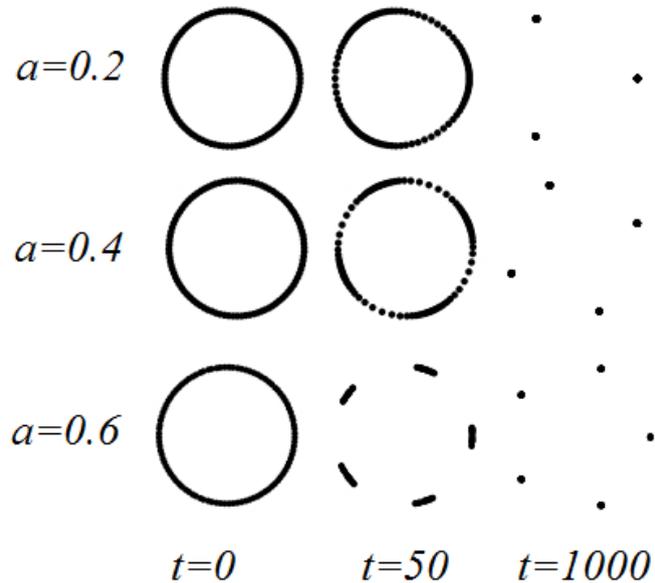
$$\max_i |x_i| - \min_i |x_i| = \sqrt{\max(0, \tau(q - q_c))}; \quad \tau \approx 0.109.$$



# Point-concentration (hole) solutions

$$F(r) = \min(ar, r - r^2)$$

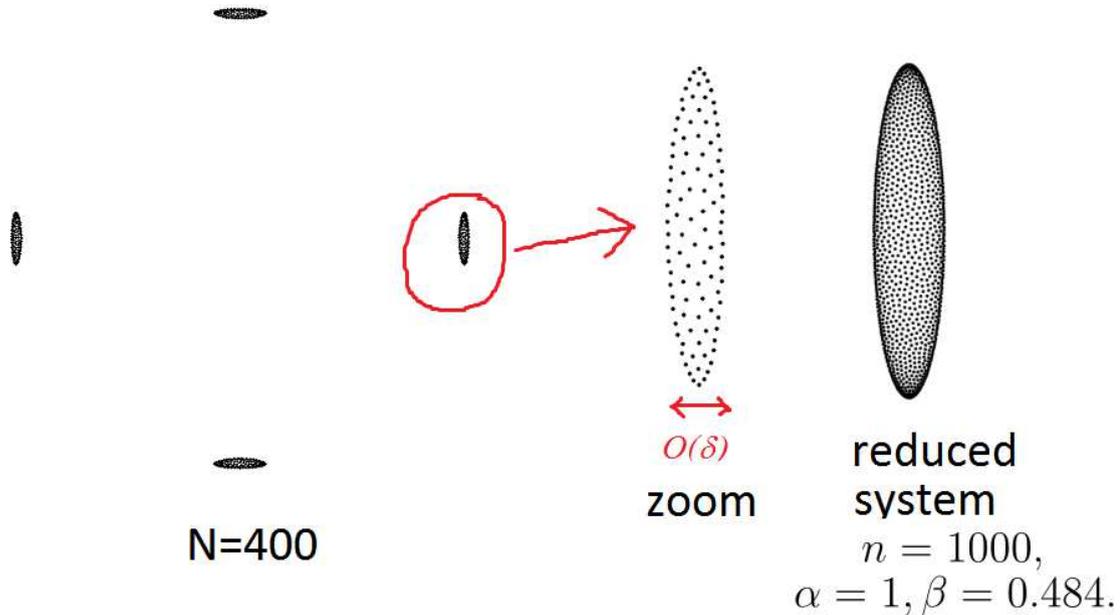
Solutions consist of  $K$  “clusters”, where each cluster has  $N/K$  points inside. The number  $K$  depends on  $a$  :



# Spots: “degenerate” holes

$$F(r) = \min(ar + \delta, 1 - r); \quad \delta \ll 1$$

- Points degenerate into spots of size  $O(\delta)$ . eg.  $a = 0.3, \delta = 0.05$  :



- Inside each of the cluster, the **reduced** problem is:

$$\phi'_l = \sum_{j \neq l}^n \frac{\phi_l - \phi_j}{|\phi_l - \phi_j|} - n \begin{bmatrix} \alpha & 0 \\ 0 & \beta \end{bmatrix} \phi_l$$

- $\alpha, \beta$  depend only on  $F(r)$  not on  $N$ .

## (In)stability of $m \gg 1$ modes

- If  $\lambda(m) > 0$  for all sufficiently large  $m$ , then we call the ring solution **ill-posed**. Otherwise we call it **well-posed**.
- For ill-posed problems, the ring can degenerate into either an annulus (eg.  $F(x) = 0.5 + x - x^2$ ) or discrete set of points (eg  $F(x) = x^{1.3} - x^2$ )
- , if  $F(r)$  is  $C^4$  on  $[0, 2r]$ , then the necessary and sufficient conditions for well-posedness of a ring are:

$$F(0) = 0, \quad F''(0) < 0 \quad \text{and} \quad (11)$$

$$\int_0^{\pi/2} \left( \frac{F(2r \sin \theta)}{2r \sin \theta} - F'(2r \sin \theta) \right) d\theta < 0. \quad (12)$$

- Ring solution for the morse force  $F(r) = \exp(-r) - G \exp(-r/L)$  is always ill-posed since  $F(0) > 0$ .

# Bifurcation to annulus:

Consider

$$F(r) = r - r^2 + \delta, \quad 0 \leq \delta \ll 1.$$

- A ring is stable of radius  $R \sim \frac{3\pi}{16} + \frac{2}{\pi}\delta + O(\delta^2)$  if  $\delta = 0$  but **high modes** become unstable for  $\delta > 0$
- The most unstable mode in the **discrete** system is  $m = N/2$  and can be stable even if the continuous model is ill-posed!

- **Proposition: Let**

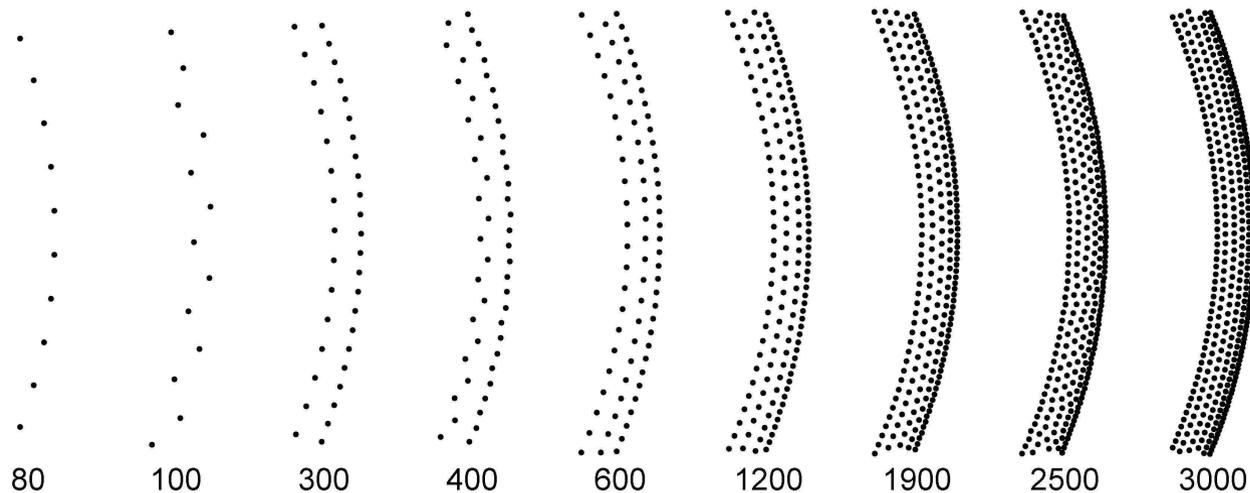
$$N_c \sim \frac{\pi}{4} e^{4-\gamma} \exp\left(\frac{3\pi^2}{64\delta}\right).$$

The ring is stable if  $N < N_c$ .

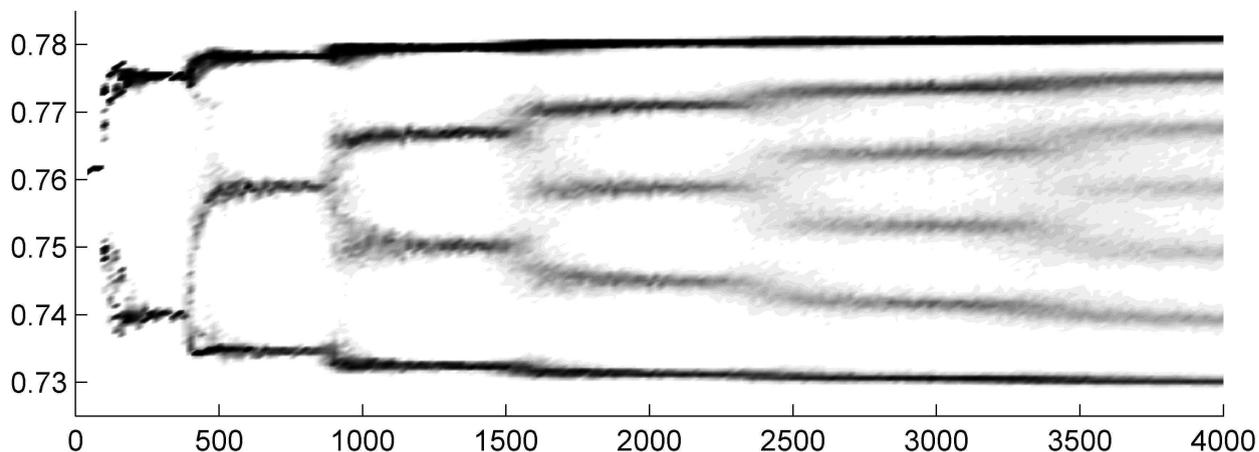
- For  $N > N_c$  but  $N \sim N_c$ , solution consists of two radii  $R \pm \varepsilon$  where

$$R = \frac{3\pi}{32} \left( 1 + \sqrt{1 + \frac{128}{3\pi^2}\delta} \right); \quad \varepsilon \sim 4Re^{-2} \exp\left(\frac{-4R^2 + R\pi/2}{\delta}\right)$$

- Example:  $\delta = 0.35 \implies N_c \sim 90$ ,  $2\varepsilon \sim 0.033$ . Numerically, we obtain  $2\varepsilon \approx 0.036$ . Good agreement!



- Increasing  $N$  further, more rings appear until we get a thin annulus of width  $O(\varepsilon)$ .



# Annulus: continuum limit $N \gg N_c$ :

- $F(r) = r - r^2 + \delta$ ,  $0 < \delta \ll 1$
- **Main result:** In the limit  $\delta \rightarrow 0$ , the annulus inner and outer radii  $R_1, R_2$  are given by

$$R \sim \frac{3\pi}{16} + \frac{2}{\pi}\delta; \quad R_1 \sim R - \beta, \quad R_2 \sim R + \beta$$

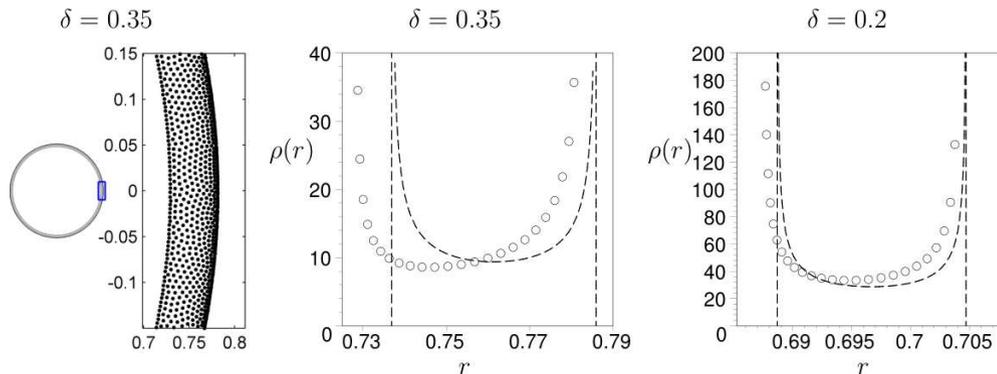
where

$$\beta \sim 3\pi e^{-5} \exp\left(-\frac{3\pi^2}{64} \frac{1}{\delta}\right) \ll \delta \ll 1.$$

The radial density profile inside the annulus is

$$\rho(x) \sim \begin{cases} \frac{c}{\sqrt{\beta^2 - (R - |x|)^2}}, & |R - x| < \beta \ll 1 \\ 0, & \text{otherwise} \end{cases}$$

- Annulus is **exponentially thin in**  $\delta$ ... note the 1/sqrt singularity near the edges!



# Key steps for computing annulus profile

- For radially symmetric density, the velocity field reduces to a 1D problem:

$$v(r) = \int_0^{\infty} K(s, r) \rho(s) s ds$$

where

$$K(s, r) := \int_0^{2\pi} (r - s \cos \theta) f\left(\sqrt{r^2 + s^2 - 2rs \cos \theta}\right) d\theta; \quad f(r) = 1 - r + \frac{\delta}{r}$$

- Assume thin annulus; expand all integrals. **It boils down to** integral equation

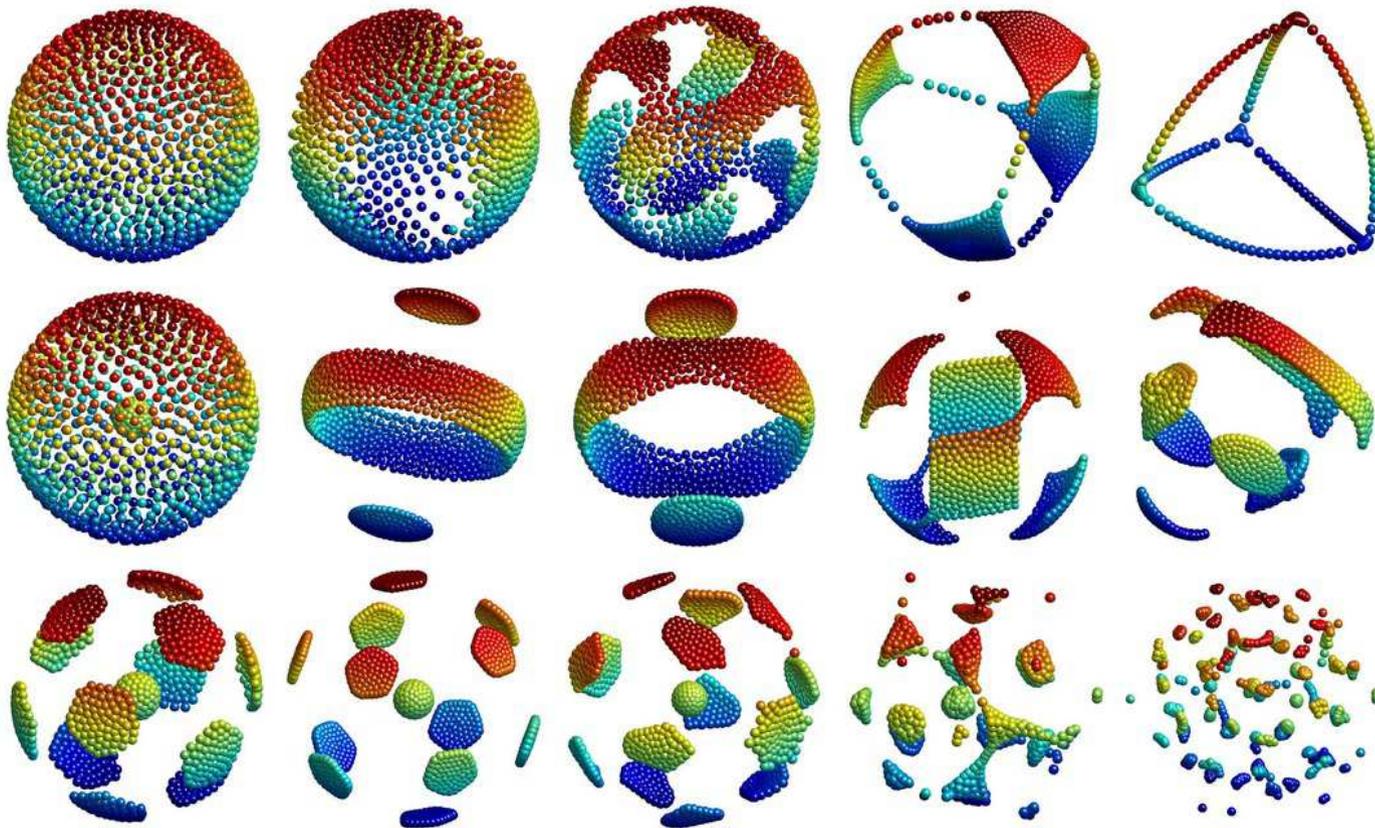
$$\int_{-\beta}^{\beta} \ln |\eta - \xi| \varrho(\eta) d\eta = 1 \quad \text{for all } \xi \in (\alpha, \beta)$$

- **Explicit solution** is a special case of Formula 3.4.2 from “Handbook of integral equations” A.Polyanin and A.Manzhirov:

$$\varrho(\xi) = \frac{C}{\sqrt{\beta^2 - \xi^2}}$$

# 3D sphere instabilities

- Radius satisfies:  $\int_0^\pi F(2r_0 \sin \theta) \sin \theta \sin 2\theta = 0$
- Instability can be done using spherical harmonics



# Stability of a spherical shell

Define

$$g(s) := \frac{F(\sqrt{2s})}{\sqrt{2s}};$$

The spherical shell has a radius given implicitly by

$$0 = \int_{-1}^1 g(R^2(1-s))(1-s)ds.$$

Its stability is given by a sequence of 2x2 eigenvalue problems

$$\lambda \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} \alpha + \lambda_l(g_1) & l(l+1)\lambda_l(g_2) \\ \lambda_l(g_2) & \frac{l(l+1)}{R^2}\lambda_l(g_3) \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}, \quad l = 2, 3, 4, \dots$$

where

$$\lambda_l(f) := 2\pi \int_{-1}^1 f(s)P_l(s) ds;$$

with  $P_l(s)$  the Legendre polynomial and

$$\begin{aligned} \alpha &:= 8\pi g(2R^2) + \lambda_0(g(R^2(1-s^2))) \\ g_1(s) &:= R^2 g'(R^2(1-s))(1-s)^2 - g(R^2(1-s))s \\ g_2(s) &:= g(R^2(1-s))(1-s); & g_3(s) &:= \int_0^{R^2(1-s)} g(z)dz. \end{aligned}$$

# Well-posedness in 3D

Suppose that  $g(s)$  can be written in terms of the generalized power series as

$$g(s) = \sum_{i=1}^{\infty} c_i s^{p_i}, \quad p_1 < p_2 < \dots \quad \text{with } c_1 > 0.$$

Then the ring is **well-posed** [i.e.  $\lambda < 0$  for all sufficiently large  $l$ ] if

$$(i) \ \alpha < 0 \quad \text{and} \quad (ii) \ p_1 \in (-1, 0) \cup (1, 2) \cup (3, 4) \dots$$

The ring is **ill-posed** [i.e.  $\lambda > 0$  for all sufficiently large  $l$ ] if either  $\alpha > 0$  or  $p_1 \notin [-1, 0] \cup [1, 2] \cup [3, 4] \dots$

## Key identity to prove well-posedness:

$$\int_{-1}^1 (1-s)^p P_l(s) ds = \frac{2^{p+1}}{p+1} \frac{\Gamma(l-p)\Gamma(p+2)}{\Gamma(l+p+2)\Gamma(-p)}$$

$$\sim -\frac{1}{\pi} \sin(\pi p) \Gamma^2(p+1) 2^{p+1} l^{-2p-2} \quad \text{as } l \rightarrow \infty.$$

Proof:

- Use hypergeometric representation:  $P_l(s) = {}_2F_1 \left( \begin{matrix} l+1, -l \\ 1 \end{matrix} ; \frac{1-s}{2} \right)$ .

- Use **generalized Euler transform**:

$${}_{A+1}F_{B+1} \left( \begin{matrix} a_1, \dots, a_A, c \\ b_1, \dots, b_B, d \end{matrix} ; z \right) = \frac{\Gamma(d)}{\Gamma(c)\Gamma(d-c)} \int_0^1 t^{c-1} (1-t)^{d-c-1} {}_A F_B \left( \begin{matrix} a_1, \dots, a_A, c \\ b_1, \dots, b_B, d \end{matrix} ; z \right) dt$$

to get  $\int_{-1}^1 (1-s)^p P_l(s) ds = \frac{2\pi 2^{p+1}}{p+1} {}_3F_2 \left( \begin{matrix} p+1, l+1, -l \\ p+2, 1 \end{matrix} ; 1 \right)$ .

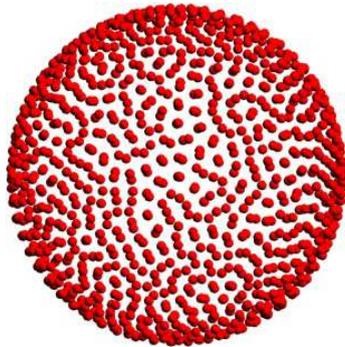
- Apply the **Saalschütz Theorem** to simplify

$${}_3F_2 \left( \begin{matrix} p+1, l+1, -l \\ p+2, 1 \end{matrix} ; 1 \right) = \frac{\Gamma(l-p)\Gamma(p+2)}{\Gamma(l+p+2)\Gamma(-p)}.$$

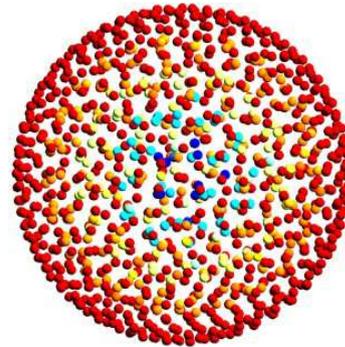
# Generalized Lennard-Jones interaction

$$g(s) = s^{-p} - s^{-q}; \quad 0 < p, q < 1; \quad p > q$$

- Well posed if  $q < \frac{2p-1}{2p-2}$ ; ill-posed if  $q > \frac{2p-1}{2p-2}$ .



(a)



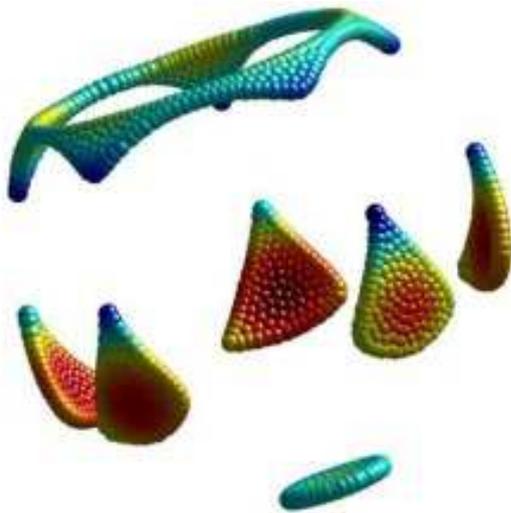
(b)

Example: steady state with  $N = 1000$  particles. (a)  $(p, q) = (1/3, 1/6)$ . Particles concentrate uniformly on a surface of the sphere, with no particles in the interior. (b)  $(p, q) = (1/2, 1/4)$ . Particles fill the interior of a ball. The particles are color-coded according to their distance from the center of mass.

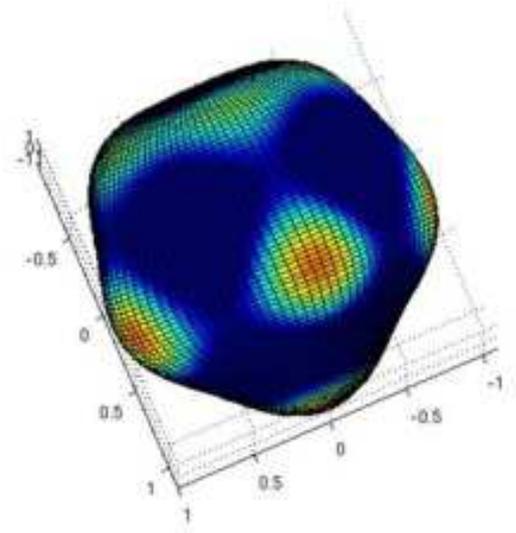
# Custom-designed kernels

- In 3D, we can design force  $F(r)$  which is stable for all modes except specified mode.
- EXAMPLE: Suppose we want only mode  $m = 5$  to be unstable. Using our algorithm, we get

$$F(r) = \left\{ 3 \left( 1 - \frac{r^2}{2} \right)^2 + 4 \left( 1 - \frac{r^2}{2} \right)^3 - \left( 1 - \frac{r^2}{2} \right)^4 \right\} r + \varepsilon; \quad \varepsilon = 0.1.$$



Particle simulation



Linearized solution

## Part II: Constant-density swarms

- Biological swarms have sharp boundaries, relatively **constant internal population**.
- Question: *What interaction force leads to such swarms?*
- More generally, can we deduce an interaction force from the swarm density?



# Bounded states of constant density

**Claim.** Suppose that

$$F(r) = \frac{1}{r^{n-1}} - r, \quad \text{where } n \equiv \text{dimension}$$

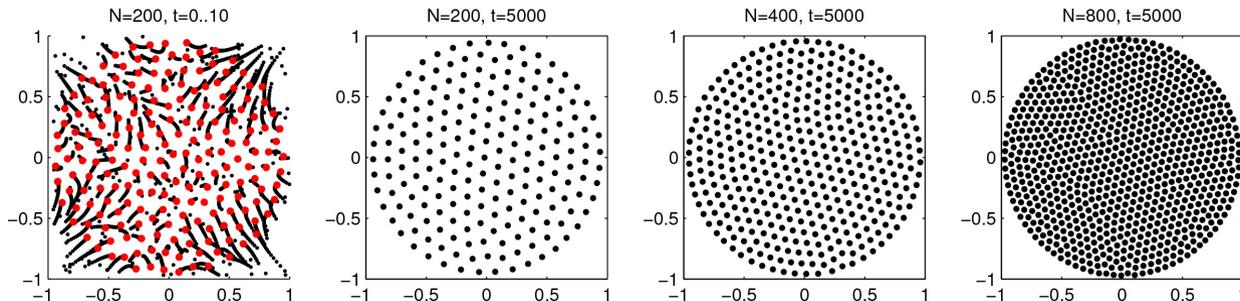
Then the aggregation model

$$\rho_t + \nabla \cdot (\rho v) = 0; \quad v(x) = \int_{\mathbb{R}^n} F(|x - y|) \frac{x - y}{|x - y|} \rho(y) dy.$$

admits a steady state of the form

$$\rho(x) = \begin{cases} 1, & |x| < R \\ 0, & |x| > R \end{cases}; \quad v(x) = \begin{cases} 0, & |x| < 1 \\ -ax, & |x| > 1 \end{cases}.$$

where  $R = 1$  for  $n = 1, 2$  and  $a = 2$  in one dimension and  $a = 2\pi$  in two dimensions.



# Proof for two dimensions

Define

$$G(x) := \ln |x| - \frac{|x|^2}{2}; \quad M = \int_{\mathbb{R}^n} \rho(y) dy$$

Then we have:

$$\nabla G = F(|x|) \frac{x}{|x|} \quad \text{and} \quad \Delta G(x) = 2\pi\delta(x) - 2.$$

so that

$$v(x) = \int_{\mathbb{R}^n} \nabla_x G(x - y) \rho(y) dy.$$

Thus we get:

$$\begin{aligned} \nabla \cdot v &= \int_{\mathbb{R}^n} (2\pi\delta(x - y) - 2)\rho(y) dy \\ &= 2\pi\rho(x) - 2M \\ &= \begin{cases} 0, & |x| < R \\ -2M, & |x| > R \end{cases} \end{aligned}$$

The steady state satisfies  $\nabla \cdot v = 0$  inside some ball of radius  $R$  with  $\rho = 0$  outside such a ball but then  $\rho = M/\pi$  inside this ball and  $M = \int_{\mathbb{R}^n} \rho(y) dy = MR^2 \implies R = 1$ .

# Dynamics in 1D with $F(r) = 1 - r$

Assume WLOG that

$$\int_{-\infty}^{\infty} x\rho(x) dx = 0; \quad M := \int_{-\infty}^{\infty} \rho(x) dx$$

Then

$$\begin{aligned} v(x) &= \int_{-\infty}^{\infty} F(|x-y|) \frac{x-y}{|x-y|} \rho(y) dy \\ &= \int_{-\infty}^{\infty} (1 - |x-y|) \operatorname{sign}(x-y) \rho(y) dy \\ &= 2 \int_{-\infty}^x \rho(y) dy - M(x+1). \end{aligned}$$

and continuity equations become

$$\begin{aligned} \rho_t + v\rho_x &= -v_x\rho \\ &= (M - 2\rho)\rho \end{aligned}$$

Define the characteristic curves  $X(t, x_0)$  by

$$\frac{d}{dt}X(t; x_0) = v; \quad X(0, x_0) = x_0$$

Then along the characteristics, we have  $\rho = \rho(X, t)$ ;

$$\frac{d}{dt}\rho = \rho(M - 2\rho)$$

Solving we get:

$$\rho(X(t, x_0), t) = \frac{M}{2 + e^{-Mt}(M/\rho_0 - 2)}; \quad \rho(X(t, x_0), t) \rightarrow M/2 \text{ as } t \rightarrow \infty$$

# Solving for characteristic curves

Let

$$w := \int_{-\infty}^x \rho(y) dy$$

then

$$v = 2w - M(x + 1); \quad v_x = 2\rho - M$$

and integrating  $\rho_t + (\rho v)_x = 0$  we get:

$$w_t + vw_x = 0$$

Thus  $w$  is constant along the characteristics  $X$  of  $\rho$ , so that characteristics  $\frac{d}{dt}X = v$  become

$$\frac{d}{dt}X = 2w_0 - M(X + 1); \quad X(0; x_0) = x_0$$

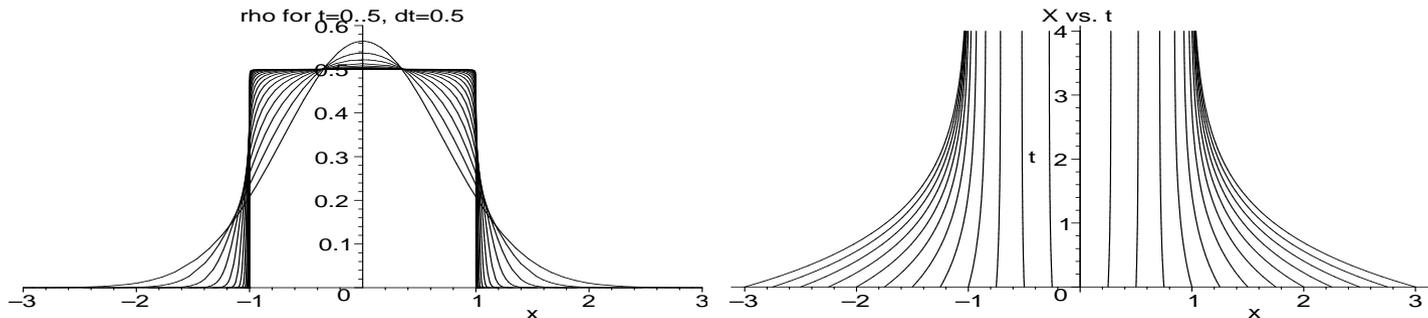
## Summary for $F(r) = 1 - r$ in 1D:

$$X = \frac{2w_0(x_0)}{M} - 1 + e^{-Mt} \left( x_0 + 1 - \frac{2w_0(x_0)}{M} \right)$$

$$w_0(x_0) = \int_{-\infty}^{x_0} \rho_0(z) dz; \quad M = \int_{-\infty}^{\infty} \rho_0(z) dz$$

$$\rho(X, t) = \frac{M}{2 + e^{-tM}(M/\rho_0(x_0) - 2)}$$

Example:  $\rho_0(x) = \exp(-x^2) / \sqrt{\pi}$ ;  $M = 1$  :



# Global stability

In limit  $t \rightarrow \infty$  we get:

$$X = \frac{2w_0}{M} - 1; \quad w_0 = 0 \dots M; \quad \rho(X, \infty) = \frac{M}{2}$$

We have shown that as  $t \rightarrow \infty$ , the steady state is

$$\rho(x, \infty) = \begin{cases} M/2, & |x| < 1 \\ 0, & |x| > 1 \end{cases} \quad (13)$$

- This **proves the global stability of (13)!**
- Characteristics intersect at  $t = \infty$ ; solution forms a shock at  $x = \pm 1$  at  $t = \infty$ .

## Dynamics in 2D, $F(r) = \frac{1}{r} - r$

- Similar to 1D,

$$\nabla \cdot v = 2\pi\rho(x) - 4\pi M;$$

$$\begin{aligned}\rho_t + v \cdot \nabla \rho &= -\rho \nabla \cdot v \\ &= -\rho(\rho - 2M) 2\pi\end{aligned}$$

- Along the characteristics:

$$\frac{d}{dt}X(t; x_0) = v; \quad X(0, x_0) = x_0$$

we still get

$$\begin{aligned}\frac{d}{dt}\rho &= 2\pi\rho(2M - \rho); \\ \rho(X(t; x_0), t) &= \frac{2M}{1 + \left(\frac{2M}{\rho(x_0)} - 1\right) \exp(-4\pi Mt)}\end{aligned}\tag{14}$$

- Continuity equations yield:

$$\rho(X(t; x_0), t) \det \nabla_{x_0} X(t; x_0) = \rho_0(x_0)$$

- Using (14) we get

$$\det \nabla_{x_0} X(t; x_0) = \frac{\rho_0(x_0)}{2M} + \left(1 - \frac{\rho_0(x_0)}{2M}\right) \exp(-4\pi M t).$$

- If  $\rho$  is **radially symmetric**, characteristics are also radially symmetric, i.e.

$$X(t; x_0) = \lambda(|x_0|, t) x_0$$

then

$$\det \nabla_{x_0} X(t; x_0) = \lambda(t; r) (\lambda(t; r) + \lambda_r(t; r)r), \quad r = |x_0|$$

so that

$$\lambda^2 + \lambda_r \lambda r = \frac{\rho_0(x_0)}{2M} + \left(1 - \frac{\rho_0(x_0)}{2M}\right) \exp(-4\pi M t)$$

$$\lambda^2 r^2 = \frac{1}{M} \int_0^r s \rho_0(s) ds + 2 \exp(-4\pi M t) \int_0^r s \left(1 - \frac{\rho(s)}{2M}\right) ds$$

**So characteristics are fully solvable!!**

- This proves **global stability in the space of radial initial conditions**  $\rho_0(x) = \rho_0(|x|)$ .
- More general global stability is still open.

## The force $F(r) = \frac{1}{r} - r^{q-1}$ in 2D

- If  $q = 2$ , we have explicit ode and solution for characteristics.
- For other  $q$ , no explicit solution is available but we have **differential inequalities**:

Define

$$\rho_{\max} := \sup_x \rho(x, t); \quad R(t) := \text{radius of support of } \rho(x, t)$$

Then

$$\begin{aligned} \frac{d\rho_{\max}}{dt} &\leq (aR^{q-2} - b\rho_{\max})\rho_{\max} \\ \frac{dR}{dt} &\leq c\sqrt{\rho_{\max}} - dR^{q-1}; \end{aligned}$$

where  $a, b, c, d$  are some [known] positive constants.

- It follows that if  $R(0)$  is sufficiently big, then  $R(t), \rho_{\max}(t)$  remain bounded for all  $t$ .  
[using bounding box argument]
- **Theorem:** For  $q \geq 2$ , there exists a bounded steady state [uniqueness??]

# Inverse problem: Custom-designer kernels: 1D

**Theorem.** In one dimension, consider a radially symmetric density of the form

$$\rho(x) = \begin{cases} b_0 + b_2x^2 + b_4x^4 + \dots + b_{2n}x^{2n}, & |x| < R \\ 0, & |x| \geq R \end{cases} \quad (15)$$

Define the following quantities,

$$m_{2q} := \int_0^R \rho(r)r^{2q}dr. \quad (16)$$

Then  $\rho(r)$  is the steady state corresponding to the kernel

$$F(r) = 1 - a_0r - \frac{a_2}{3}r^3 - \frac{a_4}{5}r^5 - \dots - \frac{a_{2n}}{2n+1}r^{2n+1} \quad (17)$$

where the constants  $a_0, a_2, \dots, a_{2n}$ , are computed from the constants  $b_0, b_2, \dots, b_{2n}$  by solving the following linear problem:

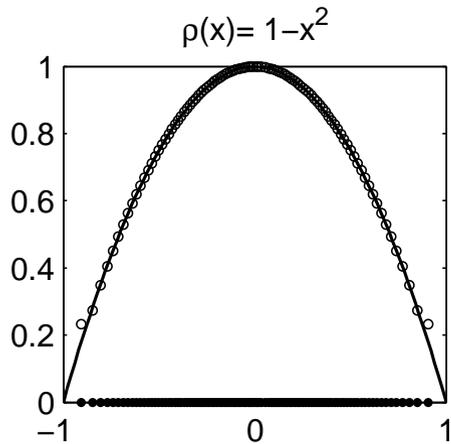
$$b_{2k} = \sum_{j=k}^n a_{2j} \binom{2j}{2k} m_{2(j-k)}, \quad k = 0 \dots n. \quad (18)$$

# Example: custom kernels 1D

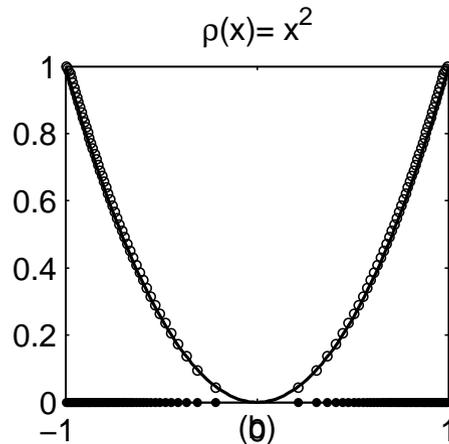
**Example 1:**  $\rho = 1 - x^2$ ,  $R = 1$ , then  $F(r) = 1 - 9/5r + 1/2r^3$ .

**Example 2:**  $\rho = x^2$ ,  $R = 1$ , then  $F(r) = 1 + 9/5r - r^3$ .

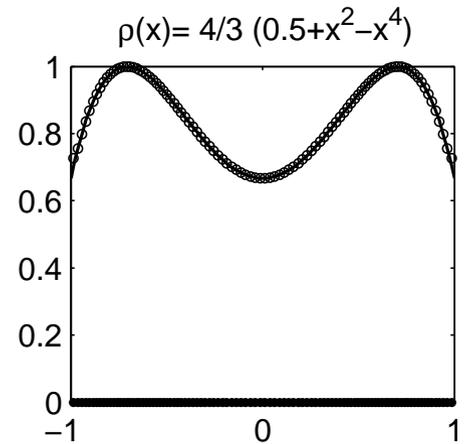
**Example 3:**  $\rho = 1/2 + x^2 - x^4$ ,  $R = 1$ ; then  $F(r) = 1 + \frac{209425}{336091}r - \frac{4150}{2527}r^3 + \frac{6}{19}r^5$ .



Ex.1



Ex.2



Ex.3

# Inverse problem: Custom-designer kernels: 2D

**Theorem.** In two dimensions, consider a radially symmetric density  $\rho(x) = \rho(|x|)$  of the form

$$\rho(r) = \begin{cases} b_0 + b_2 r^2 + b_4 r^4 + \dots + b_{2n} r^{2n}, & r < R \\ 0, & r \geq R \end{cases} \quad (19)$$

Define the following quantities,

$$m_{2q} := \int_0^R \rho(r) r^{2q} dr. \quad (20)$$

Then  $\rho(r)$  is the steady state corresponding to the kernel

$$F(r) = \frac{1}{r} - \frac{a_0}{2} r - \frac{a_2}{4} r^3 - \dots - \frac{a_{2n}}{2n+2} r^{2n+1} \quad (21)$$

where the constants  $a_0, a_2, \dots, a_{2n}$ , are computed from the constants  $b_0, b_2, \dots, b_{2n}$  by solving the following linear problem:

$$b_{2k} = \sum_{j=k}^n a_{2j} \binom{j}{k}^2 m_{2(j-k)+1}; \quad k = 0 \dots n. \quad (22)$$

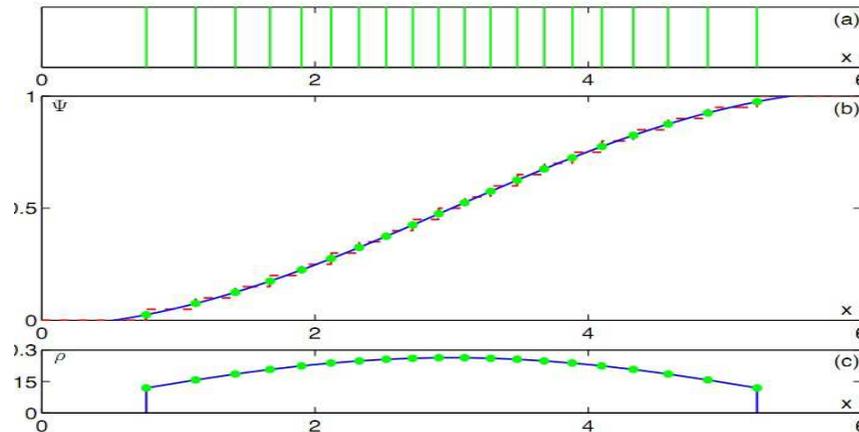
This system always has a unique solution for provided that  $m_0 \neq 0$ .

# Numerical simulations, 1D

- First, use standard ODE solver to integrate the corresponding discrete particle model,

$$\frac{dx_j}{dt} = \frac{1}{N} \sum_{\substack{k=1, \dots, N \\ k \neq j}} F(|x_j - x_k|) \frac{x_j - x_k}{|x_j - x_k|}, \quad j = 1 \dots N.$$

- How to compute  $\rho(x)$  from  $x_i$ ? [Topaz-Bernoff, 2010]
  - Use  $x_i$  to approximate the cumulative distribution,  $w(x) = \int_{-\infty}^x \rho(z) dz$ .
  - Next take derivative to get  $\rho(x) = w'(x)$



[Figure taken from Topaz+Bernoff, 2010 preprint]

# Numerical simulations, 2D

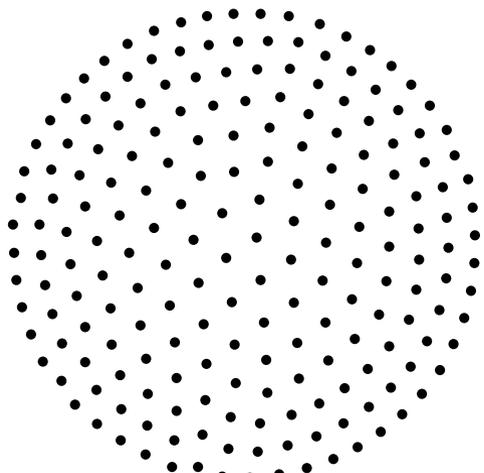
- Solve for  $x_i$  using ODE particle model as before [ $2N$  variables]
- Use  $x_i$  to compute **Voronoi diagram**;
- Estimate  $\rho(x_j) = 1/a_j$  where  $a_j$  is the area of the voronoi cell around  $x_j$ .
- Use **Delanay triangulation** to generate smooth mesh.
- **Example:** Take

$$\rho(r) = \begin{cases} 1 + r^2, & r < 1 \\ 0, & r > 0 \end{cases}$$

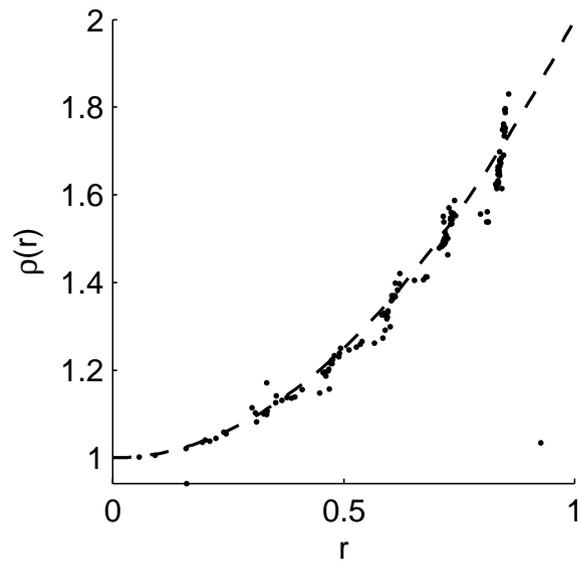
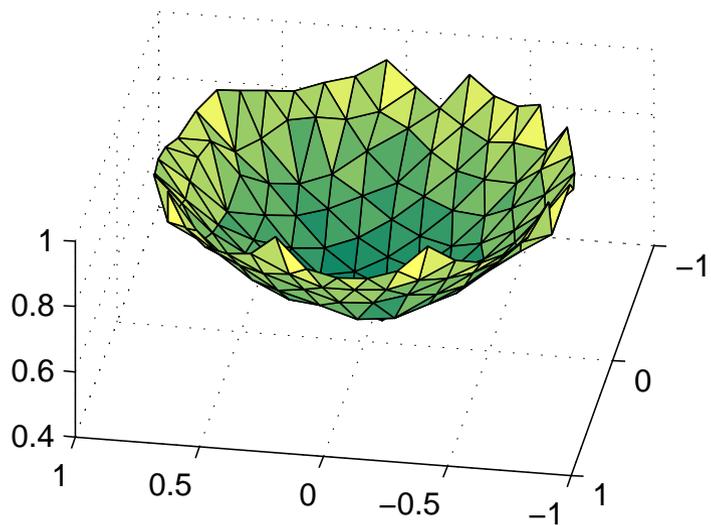
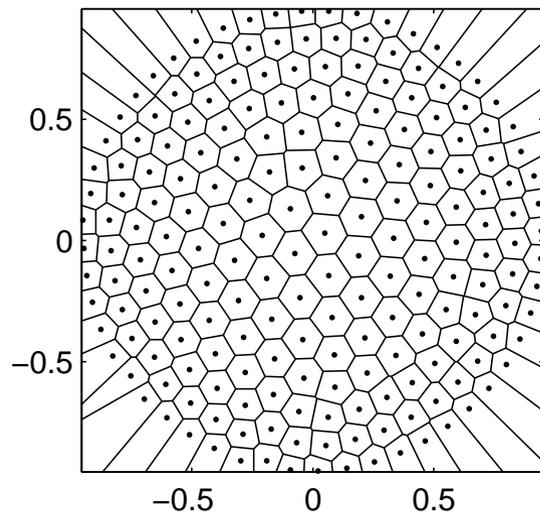
Then by Custom-designed kernel in 2D is:

$$F(r) = \frac{1}{r} - \frac{8}{27}r - \frac{r^3}{3}.$$

Running the particle method yeids...

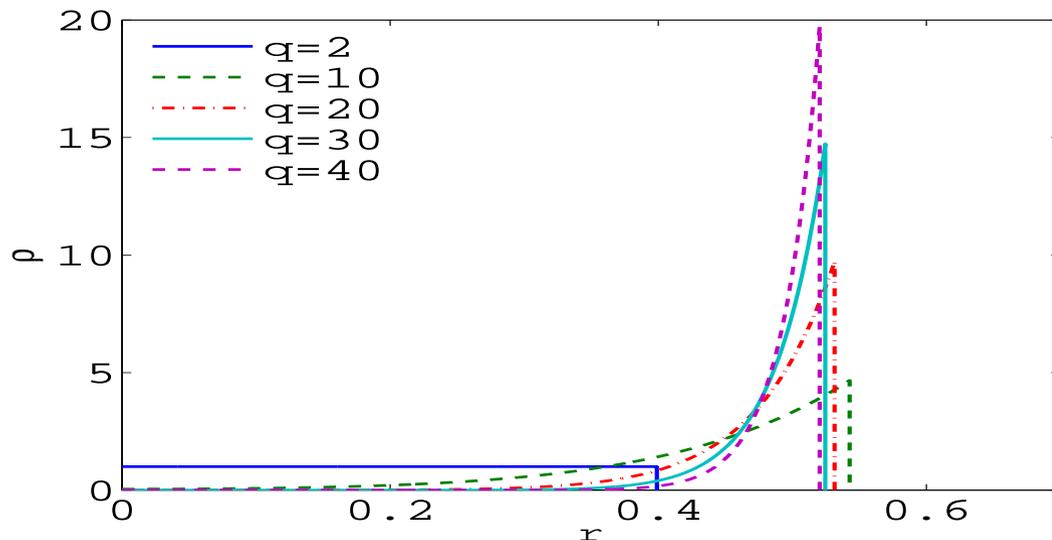


$R=0.955484$



# Numerical solutions for radial steady states for $F(r) = \frac{1}{r} - r^{q-1}$

- Radial steady states of radius  $R$  satisfy  $\rho(r) = 2q \int_0^R (r' \rho(r')) I(r, r') dr'$   
 where  $c(q)$  is some constant and  $I(r, r') = \int_0^\pi (r^2 + r'^2 - 2rr' \sin \theta)^{q/2-1} d\theta$ .
- To find  $\rho$  and  $R$ , we adjust  $R$  until the operator  $\rho \rightarrow c(q) \int_0^R (r' \rho(r')) K(r, r') dr'$  has eigenvalue 1; then  $\rho$  is the corresponding eigenfunction.



# Vortex dynamics

- Equations first given by Helmholtz (1858): each vortex generates a rotational velocity field which advects all other vortices. **Vortex model:**

$$\frac{dz_j}{dt} = i \sum_{k \neq j} \gamma_k \frac{z_j - z_k}{|z_j - z_k|^2}, \quad j = 1 \dots N.$$

- Classical problem; observed in many physical experiments: floating magnetized needles (Meyer, 1876); Malmberg-Penning trap (Durkin & Fajans, 2000), Bose-Einstein Condensates (Ketterle et.al. 2001); magnetized rotating disks (Whitesides et.al, 2001)
- Conservative, hamiltonian system
- General initial conditions lead to chaos: *movie – chaos*
- Certain special configurations are “stable” in hamiltonian sense: *movie – stable*
- Rigidly rotating steady states are called **relative equilibria**:

$$z_j(t) = e^{\omega i t} \xi_j \iff 0 = \sum_{k \neq j} \gamma_k \frac{\xi_j - \xi_k}{|\xi_j - \xi_k|^2} - \omega \xi_j$$

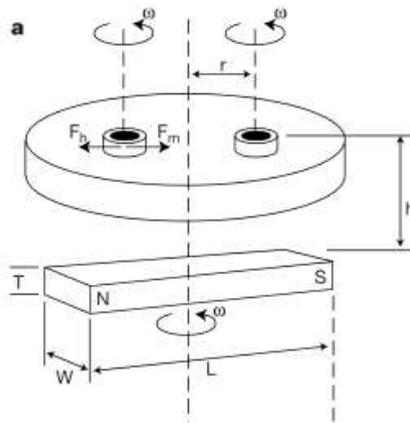
**Dynamic, self-assembled aggregates of magnetized, millimeter-sized objects rotating at the liquid-air interface: Macroscopic, two-dimensional classical artificial atoms and molecules**

Bartosz A. Grzybowski,<sup>1</sup> Xingyu Jiang,<sup>1</sup> Howard A. Stone,<sup>2</sup> and George M. Whitesides<sup>1,\*</sup>

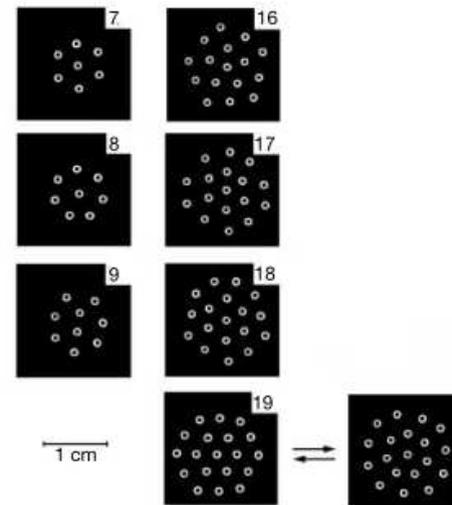
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**Figure 1** Experimental set-up and magnetic force profiles. **a**, A scheme of the experimental set-up. A bar magnet rotates at angular velocity  $\omega$  below a dish filled with liquid (typically ethylene glycol/water or glycerine/water solutions). Magnetically doped disks are placed on the liquid-air interface, and are fully immersed in the liquid except for their top surface. The disks spin at angular velocity  $\omega$  around their axes. A magnetic force attracts the disks towards the centre of the dish, and a hydrodynamic force  $F_h$  pushes



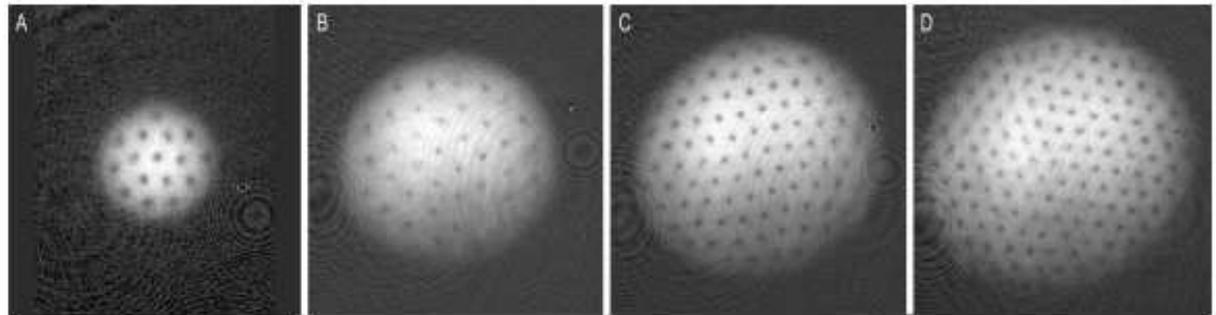
**Figure 2** Dynamic patterns formed by various numbers ( $n$ ) of disks rotating at the ethylene glycol/water-air interface. This interface is 27 mm above the plane of the external magnet. The disks are composed of a section of polyethylene tube (white) of outer diameter 1.27 mm, filled with poly(dimethylsiloxane), PDMS, doped with 25 wt% of magnetite (black centre). All disks spin around their centres at  $\omega = 700$  r.p.m., and the entire aggregate slowly ( $\Omega < 2$  r.p.m.) precesses around its centre. For  $n < 5$ , the aggregates do not have a 'nucleus'—all disks are precessing on the rim of a circle. For  $n > 5$ , nucleated structures appear. For  $n = 10$  and  $n = 12$ , the patterns are bistable in the sense that the two observed patterns interconvert irregularly with time. For  $n = 19$ , the hexagonal pattern (left) appears only above  $\omega \approx 800$  r.p.m., but can be 'annealed' down

# Observation of Vortex Lattices in Bose-Einstein Condensates

20 APRIL 2001 VOL 292 SCIENCE

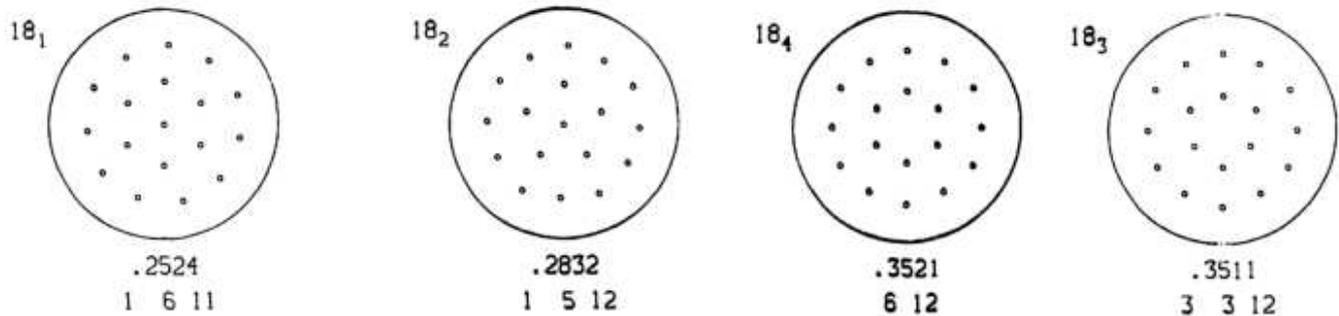
J. R. Abo-Shaeer, C. Raman, J. M. Vogels, W. Ketterle

**Fig. 1.** Observation of vortex lattices. The examples shown contain approximately (A) 16, (B) 32, (C) 80, and (D) 130 vortices. The vortices have "crystallized" in a triangular pattern. The diameter of the cloud in (D) was 1 mm after ballistic expansion, which represents a magnification of 20.



Slight asymmetries in the density distribution were due to absorption of the optical pumping light.

- Campbell and Ziff (1978) classified many stable configurations for **small** (eg.  $N = 18$ ) number of vortices of equal strength.



- Goal: describe the stable configuration in the continuum limit of a **large** number of vortices  $N$  (eg.  $N = 100, 1000 \dots$ ). These have been observed in several recent experiments: Bose Einstein Condensates, magnetized disks

# Key observation

$$\text{Vortex model: } \frac{dz_j}{dt} = i \sum_{k \neq j} \gamma_k \frac{z_j - z_k}{|z_j - z_k|^2}, \quad j = 1 \dots N. \quad (\text{V})$$

$$\text{Relative equilibrium: } z_j(t) = e^{\omega i t} \xi_j \iff 0 = \sum_{k \neq j} \gamma_k \frac{\xi_j - \xi_k}{|\xi_j - \xi_k|^2} - \omega \xi_j$$

$$\text{Aggregation model: } \frac{dx_j}{dt} = \sum_{k \neq j} \gamma_k \frac{x_j - x_k}{|x_j - x_k|^2} - \omega x_j. \quad (\text{A})$$

- One-to-one correspondence between the steady states  $x_j(t) = \xi_j$  of (A) and the relative equilibrium  $z_j(t) = e^{\omega i t} \xi_j$  of (V).
- **Spectral equivalence of (V) and (A):** The equilibrium  $x_j(t) = \xi_j$  is asymptotically stable for the aggregation model (A) if and only if the relative equilibrium  $z_j(t) = e^{\omega i t} \xi_j$  is stable (neutrally, in the Hamiltonian sense) for the vortex model (V)!
- Aggregation model fully describes relative equilibria and their linear stability in the vortex model.
- Aggregation model is easier to study than the vortex model.

## Vortices of equal strength $\gamma_k = \gamma$

Corresponding aggregation model:

$$\frac{dx_j}{dt} = \sum_{k \neq j} \gamma \frac{x_j - x_k}{|x_j - x_k|^2} - \omega x_j. \quad (23)$$

- Coarse-grain by defining the particle density to be

$$\rho(x) = \sum_{k=1 \dots N} \delta(x - x_k). \quad (24)$$

Then (23) is equivalent to  $\dot{x}_j = v(x_j)$  where

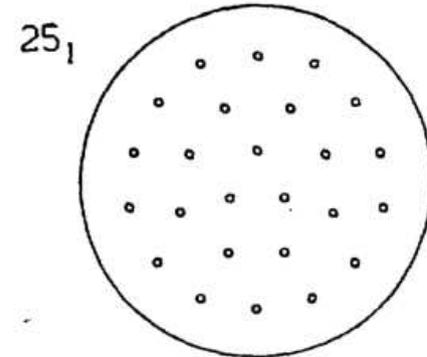
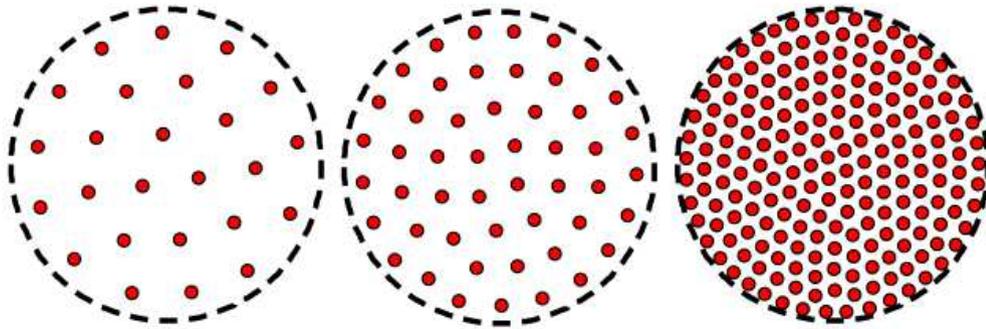
$$v(x) \equiv -\omega x + \gamma \int_{\mathbb{R}^2} \frac{x - y}{|x - y|^2} \rho(y) dy, \quad (25)$$

and density is subject to conservation of mass

$$\rho_t + \nabla \cdot (\rho v) = 0. \quad (26)$$

- [Fetecau&Huang&Kolokolnikov2011]: In the limit  $N \rightarrow \infty$ , the steady state density of (A) is constant inside the ball of radius

$$R_0 = \sqrt{N\gamma/\omega}.$$



**Fig. 1.** Stable relative equilibria of  $N = 25, 50$  and  $200$  vortices of equal strength. The dashed line shows the analytical prediction  $R_0 = \sqrt{N\gamma/\omega}$  of the swarm radius in the  $N \rightarrow \infty$  limit (see (6)).

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3 8 14

# Crystallization

$$\text{Vortex model: } \frac{dz_j}{dt} = i \sum_{k \neq j} \gamma_k \frac{z_j - z_k}{|z_j - z_k|^2}, \quad j = 1 \dots N. \quad (\text{V})$$

$$\text{Relative equilibria: } z_j(t) = e^{i\omega t} \xi_j \iff 0 = \sum_{k \neq j} \gamma_k \frac{\xi_j - \xi_k}{|\xi_j - \xi_k|^2} - \omega \xi_j$$

$$\text{Vortex with dissipation: } \frac{dz_j}{dt} = i \sum_{k \neq j} \gamma_k \frac{z_j - z_k}{|z_j - z_k|^2} + \mu \left( \sum_{k \neq j} \gamma_k \frac{z_j - z_k}{|z_j - z_k|^2} - \omega z_j \right) \quad (\text{D})$$

- In many physical experiments of BEC there is damping or dissipation involved.
- **Spectral equivalence:** Relative equilibria **and their stability** are the same for (V) and (D)
- Both the vortex model and the “aggregation model” model are limiting cases of (D).
- Taking  $\mu > 0$  **stabilizes vortex dynamics!** *chaos damped stable*
- This allows us to find stable relative equilibria numerically.

# Vortex dynamics in BEC with trap

- For BEC, dynamics have extra term corresponding to precession around the trap:

$$\dot{z}_j = \underbrace{i \frac{a}{1-r^2} z_j}_{\text{trap-interaction}} + \underbrace{ic \sum_{k \neq j} \frac{z_j - z_k}{|z_j - z_k|^2}}_{\text{self-interaction}}, \quad j = 1 \dots N. \quad (27)$$

- Large  $N$  limit:

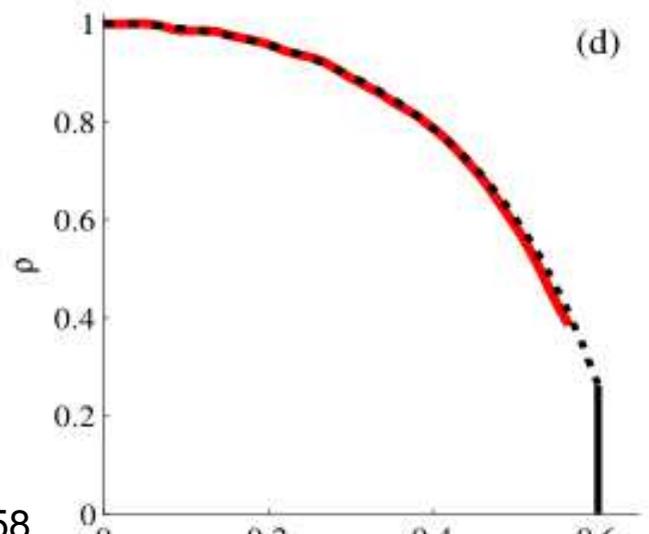
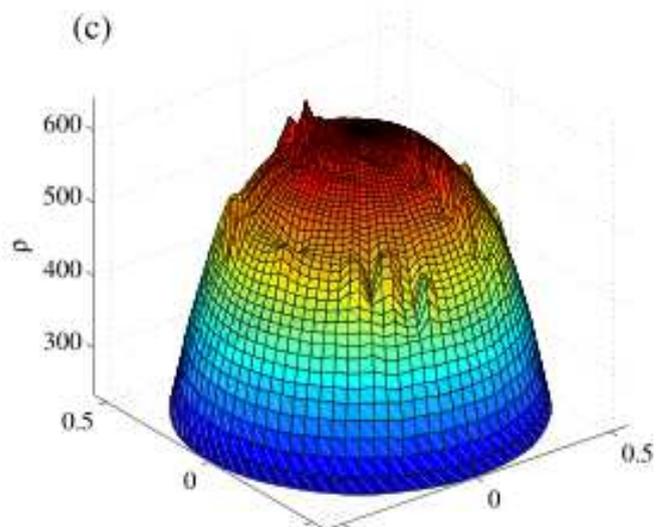
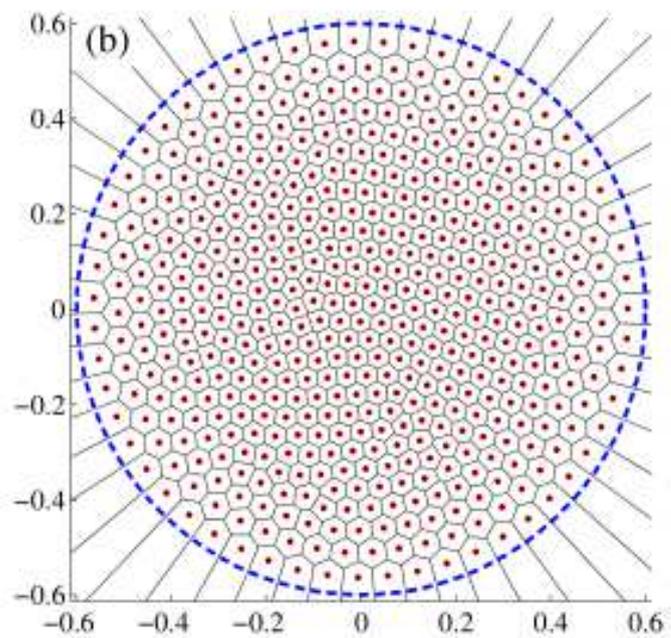
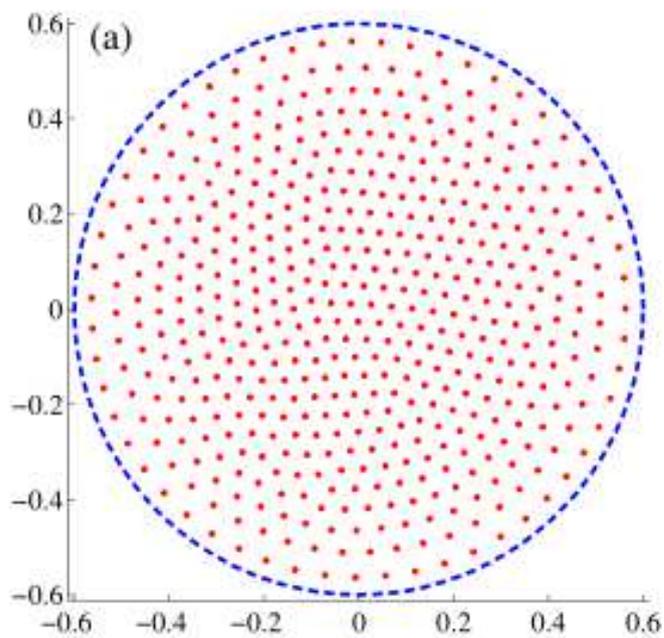
$$v(x) \equiv (f(r) - \omega) x + c \int_{\mathbb{R}^2} \frac{x - y}{|x - y|^2} \rho(y) dy.$$

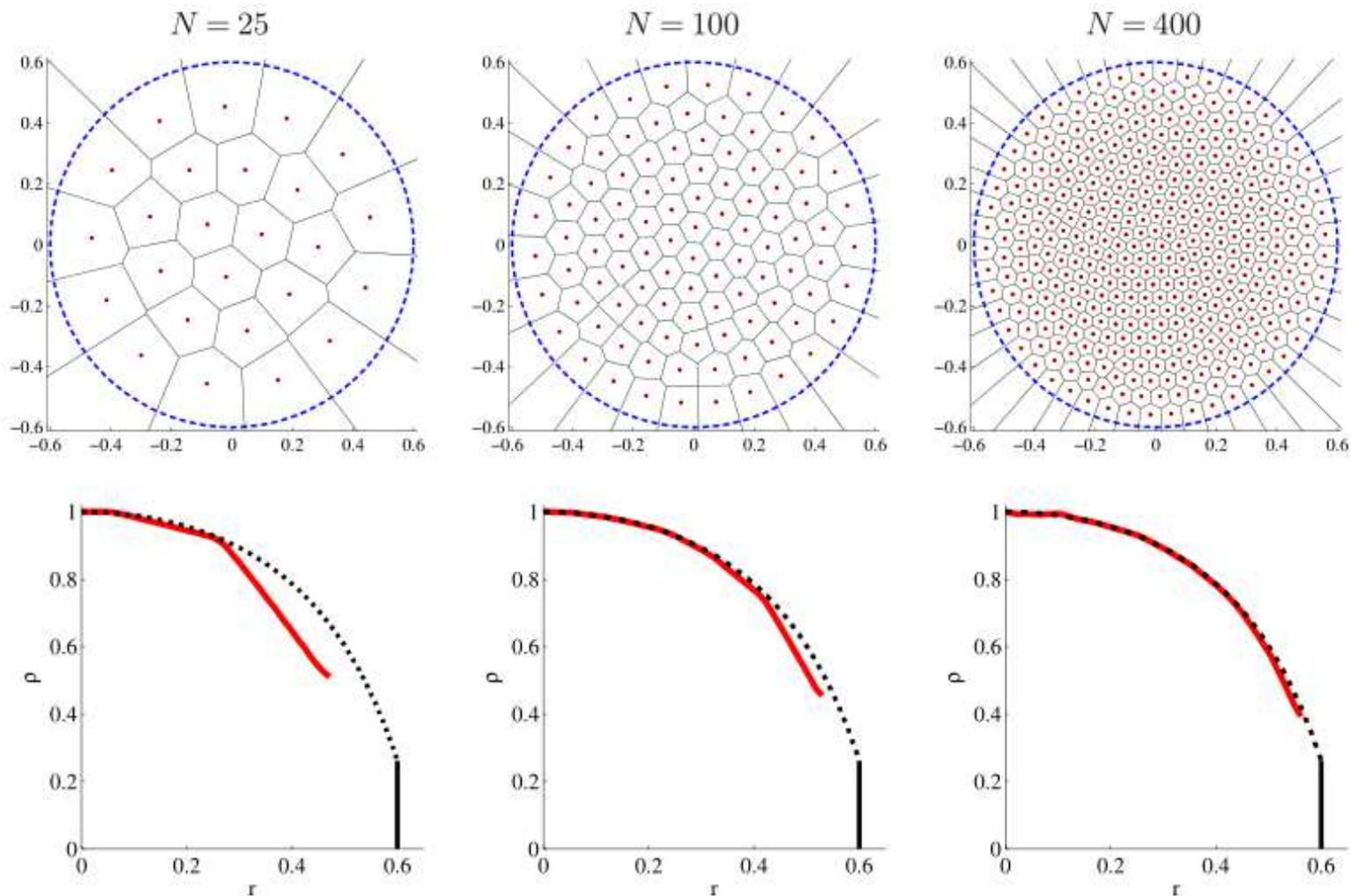
$$\int_{\mathbb{R}^2} \rho(x) dx = N,$$

- **Non-uniform** vortex lattice state:

$$\rho \sim \frac{1}{\pi c} \left( \omega - \frac{a}{(1-r^2)^2} \right) \text{ if } r < R, \quad \rho = 0 \text{ otherwise,}$$

$$\text{with } \omega = \frac{a}{1-R^2} + \frac{cN}{R^2}$$

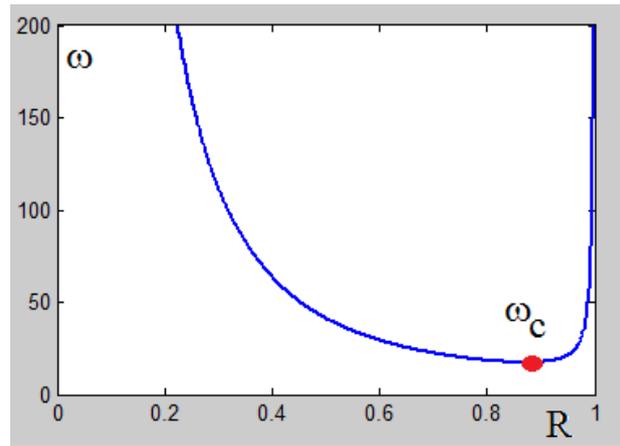




**Figure 2.** Top row: stable equilibrium of Eq. (2.4) with  $f(r)$  as in Eq. (2.2), with  $N$  as shown in the title and with  $c = 0.5/N$ ,  $\omega = 2.95139$ ,  $a = 1$ . The dashed circle is the asymptotic boundary whose radius  $R = 0.6$  is the smaller solution to Eq. (4.9). Bottom row: average of  $\rho(|x|)/\rho(0)$  as a function of  $r = |x|$ . Solid curve corresponds to the numerical computation. Dashed curve is the formula (4.10). Vertical line is the boundary  $r = R$ .

# Maximum $N$

$$\omega_c = \left( \sqrt{a} + \sqrt{cN} \right)^2; \quad R_c^2 = \frac{\sqrt{cN}}{\sqrt{a} + \sqrt{cN}}.$$



- No solutions if  $\omega < \omega_c$
- Two solutions  $R = R_{\pm}$  if  $\omega > \omega_c$ 
  - smaller is stable, larger has negative density (unphysical).
- Corollary: must have  $N < N_{\max}$  where

$$N_{\max} = \frac{(\sqrt{\omega} - \sqrt{a})^2}{c}.$$

(28)

# $N + 1$ problem

- $N$  vortices of equal strength and a single vortex of a much higher strength:

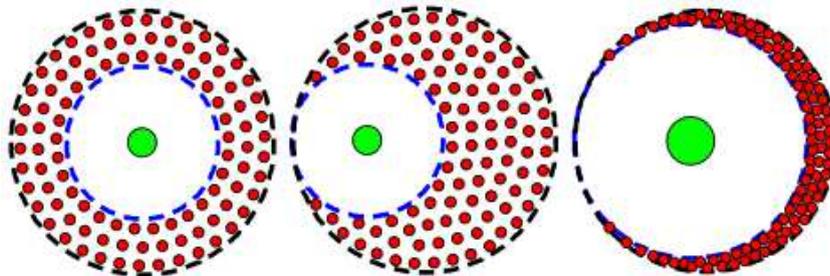
$$\frac{dx_j}{dt} = \frac{a}{N} \sum_{\substack{k=1 \dots N \\ k \neq j}} \frac{x_j - x_k}{|x_j - x_k|^2} + b \frac{x_j - \eta}{|x_j - \eta|^2} - x_j, \quad j = 1 \dots N, \quad (29)$$

$$\frac{d\eta}{dt} = \frac{a}{N} \sum_{k=1 \dots N} \frac{\eta - x_k}{|\eta - x_k|^2} - \eta \quad (30)$$

- Mean-field limit  $N \rightarrow \infty$ :

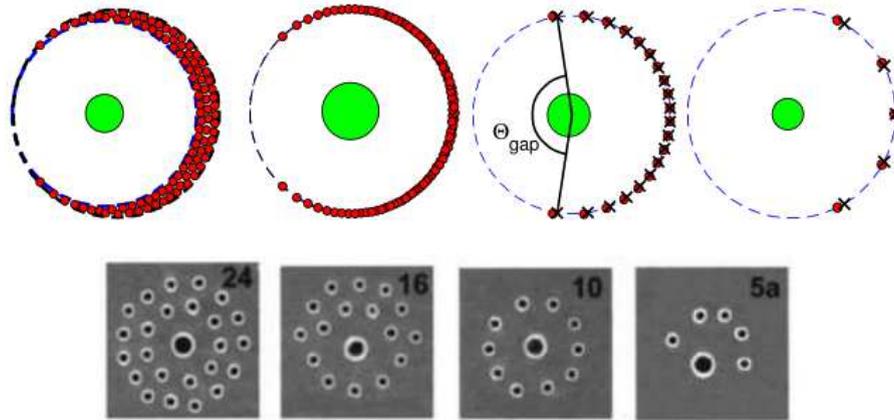
$$\begin{cases} \rho_t + \nabla \cdot (\rho \nabla v) = 0; \\ v(x) = a \int_{\mathbb{R}^2} \rho(y) \frac{x-y}{|x-y|^2} dy + b \frac{x-\eta}{|x-\eta|^2} - x \\ \frac{d\eta}{dt} = a \int_{\mathbb{R}^2} \rho(y) \frac{\eta-y}{|\eta-y|^2} dy - \eta \end{cases} \quad (31)$$

- **Main result:** Define  $R_1 = \sqrt{b}$ ,  $R_0 = \sqrt{a+b}$  and suppose that  $\eta$  is any point such that  $B_{R_1}(\eta) \subset B_{R_0}(0)$ . Then the equilibrium solution for (31) is constant inside  $B_{R_0}(0) \setminus B_{R_1}(\eta)$  and is zero outside.



- Unlike the  $N+0$  problem, the relative equilibrium for the  $N+1$  problem is non-unique: any choice of  $\eta$  yields a steady state as long as  $|\eta| < R_0 - R_1$ .

# Degenerate case: big central vortex



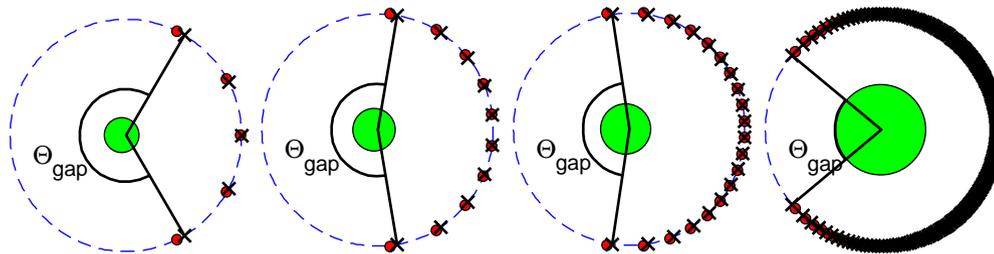
- Small vortices are constrained to a ring of radius  $R_0$ . with big vortex at the center.
- **Non-uniform** distribution of small particles!
- Question: Determine the size of the gap  $\Theta_{gap}$ .

- **Main Result:**

$$\Theta_{\text{gap}} \sim CN^{-1/3}.$$

where the constant  $C = 8.244$  satisfies

$$(8 - 6u + 2u^3) \ln(u - 1) = 3u(u^2 - 4); \quad C = 2 \left( \frac{6\pi(2 - u)}{u(u^2 - 1)} \right)^{1/3}$$



# Sketch of proof

- [Barry+Wayne, 2012]: Set  $x_j(t) \sim R_0 e^{i\theta_j(t)}$  then at leading order we get

$$\frac{d\theta_j}{dt} = \frac{1}{N} \sum_{k \neq j} \left( \frac{\sin(\theta_j - \theta_k)}{2 - 2 \cos(\theta_j - \theta_k)} - \sin(\theta_j - \theta_k) \right). \quad (32)$$

- In the mean-field limit  $N \rightarrow \infty$ , the density distribution  $\rho(\theta)$  for the angles  $\theta_j$  satisfies

$$\begin{cases} \rho_t + (\rho v_\theta)_\theta = 0, \\ v(\theta) = PV \int_{-\pi}^{\pi} \rho(\phi) \left( \frac{\sin(\theta - \phi)}{2 - 2 \cos(\theta - \phi)} - \sin(\theta - \phi) \right) d\phi, \end{cases} \quad (33)$$

where  $PV$  denotes the principal value integral, and  $\int_{-\pi}^{\pi} \rho = 1$ .

- [Barry, PhD Thesis]: Up to rotations, the steady state density  $\rho(\theta)$  for which  $v = 0$  must be of the form

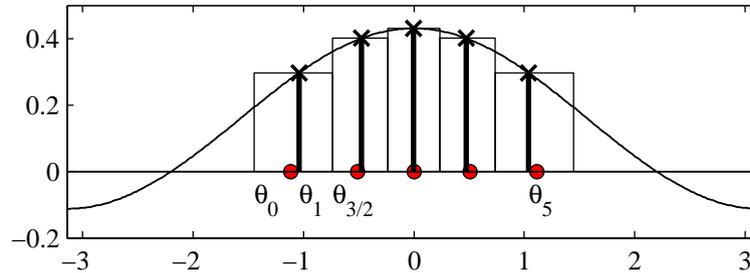
$$\rho(\theta) = \frac{1}{2\pi} (1 + \alpha \cos \theta). \quad (34)$$

This follows from (33) and (formal) expansion

$$\frac{\sin t}{2 - 2 \cos t} - \sin t = \sin(2t) + \sin(3t) + \sin(4t) + \dots$$

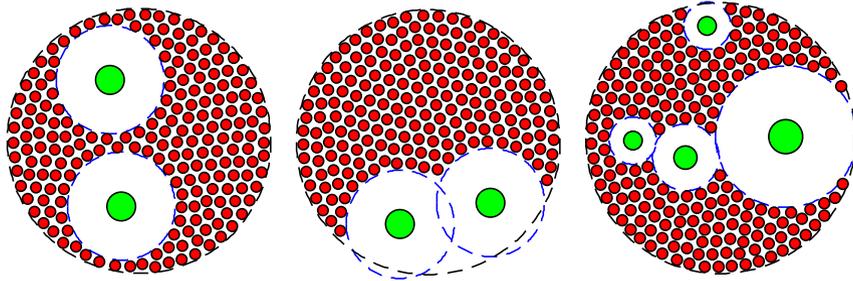
- $\alpha$  is free parameter in the continuum limit.
- For discrete  $N$ , particle positions satisfy

$$\int_{\theta_{j-1}}^{\theta_j} \frac{1}{2\pi} (1 + \alpha \cos \theta) d\theta = \frac{1}{N}$$



To estimate  $\Phi_{gap}$ , choose  $\theta_1$  so that  $v(\theta_1) \sim 0$ . See our paper for hairy details.

# $N + K$ problem



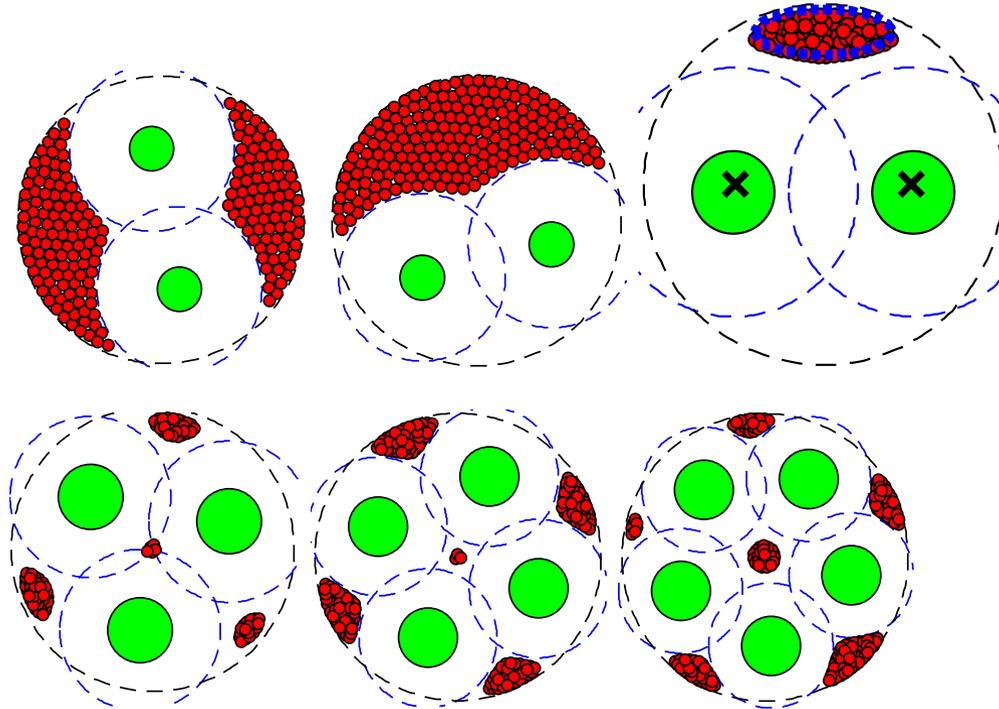
$$v(x) = a \int_{\mathbb{R}^2} \rho(y) \frac{x - y}{|x - y|^2} dy + \sum_{k=1 \dots K} b_k \frac{x - \eta_k}{|x - \eta_k|^2} - x,$$

$$\frac{d\eta_j}{dt} = a \int_{\mathbb{R}^2} \rho(y) \frac{\eta_k - y}{|\eta_k - y|^2} dy + \sum_{\substack{k=1 \dots K \\ k \neq j}} b_k \frac{\eta_j - \eta_k}{|\eta_j - \eta_k|^2} - \eta_j,$$

$$j = 1 \dots K.$$

**Main result:** Let  $R_k = \sqrt{b_k}$ ,  $k = 1 \dots K$  and  $R_0 = \sqrt{a + b_1 + \dots + b_K}$ . Suppose  $\eta_1 \dots \eta_K$  are such  $B_{R_1}(\eta_1) \dots B_{R_K}(\eta_K)$  are all disjoint and are contained inside  $B_{R_0}(0)$ . The equilibrium density is constant inside  $B_{R_0}(0) \setminus \bigcup_{k=1}^K B_{R_k}(\eta_k)$  and is zero outside.

# $N + K$ problem, with very large $K$ vortices



- The **blue ellipse** is described by the reduced system

$$\frac{d\xi_j}{dt} = \frac{1}{N} \sum_{\substack{k=1 \dots N \\ k \neq j}} \frac{1}{\xi_j - \xi_k} + \frac{1}{2} \bar{\xi}_k - \xi_k \quad (35)$$

- From [K, Huang, Fetecau, 20011], its axis ratio is 3.