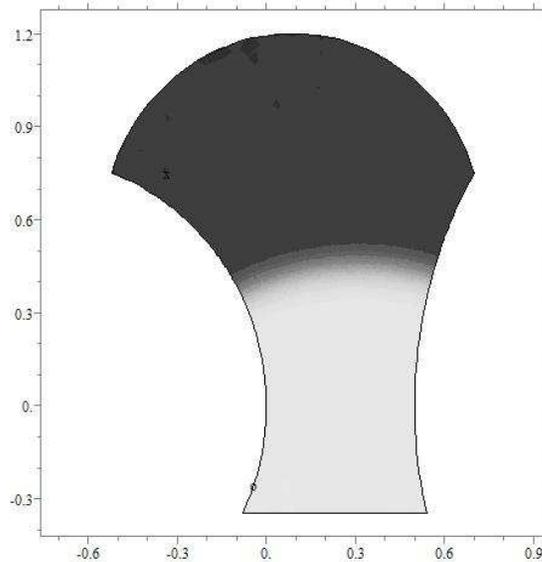


Curved interfaces in perturbed Allen-Cahn system

Theodore Kolokolnikov

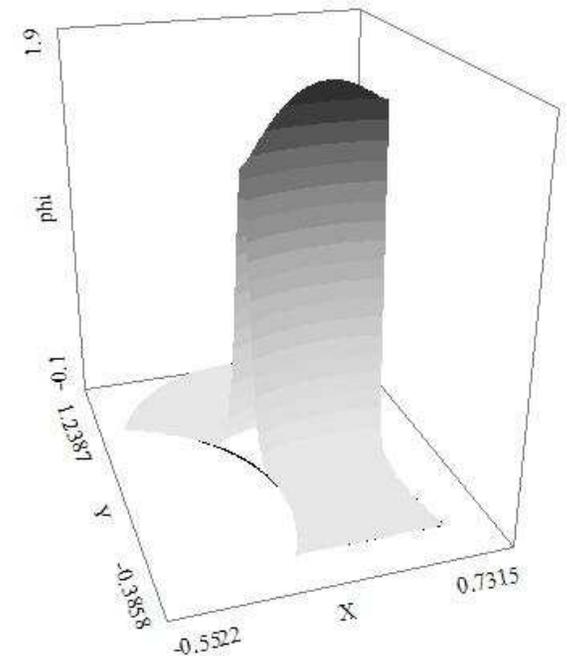


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Introduction

We consider the **perturbed** Allen-Cahn equation:

$$\begin{cases} u_t = \varepsilon^2 \Delta u + f(u) + \varepsilon g(u), & x \in \Omega \subset \mathbb{R}^2, \\ \partial_n u = 0, & x \in \partial\Omega. \end{cases} \quad (\text{PAC})$$

Here, Ω is a smooth two-dimensional domain and $f(u)$ is a smooth function having the following properties:

- f has three roots $u_- < u_0 < u_+$ with $f'(u_{\pm}) < 0$
- $\int_{u_-}^{u_+} f(u) du = 0$

and $g(u)$ is any smooth function with $\int_{u_-}^{u_+} g(u) du \neq 0$.

Some known results

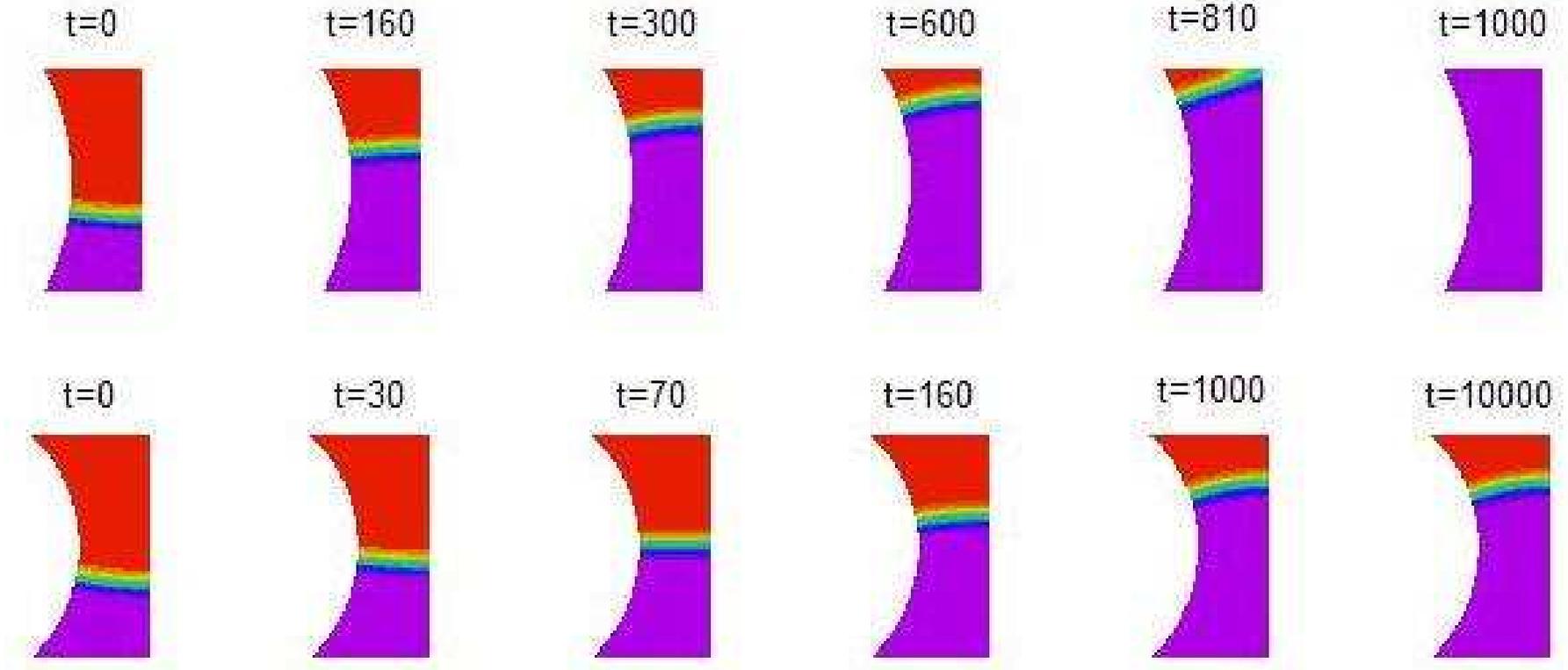
Standard form:

$$\begin{cases} u_t = \varepsilon^2 \Delta u - 2(u - \varepsilon a)(u^2 - 1), & x \in \Omega \subset \mathbb{R}^2 \\ \partial_n u = 0, & x \in \partial\Omega \end{cases} .$$

Standard A-C corresponds to $a = 0$:

- In 1-D, the steady state is given by $u = \pm \tanh(x/\varepsilon)$.
- In 2-D, the profile is 1-dimensional in some direction; the zero set $u = 0$ is a straight line, intersects boundary transversally.
- Such straight interface is stable (unstable) provided it is a local min (max) of the distance function. [Kowalczyk, 05]
- Time dependent solution evolves by mean curvature law until the interface merges with the boundary or becomes straight. [RSK, 89]

Effect of perturbation: numerics



Effect of perturbation: asymptotics

Let $U_0(z)$ be a solution to

$$U_0''(z) + f(U_0) = 0, \quad U \rightarrow u_{\pm} \text{ as } z \rightarrow \pm\infty.$$

and define

$$\hat{R} = -\frac{\int_{-\infty}^{\infty} U_0'^2(z) dz}{\int_{u_-}^{u_+} g(u) du} \quad (1)$$

Suppose that there exists a circle of radius \hat{R} which intersects $\partial\Omega$ orthogonally, and let p be its center. Then in the limit $\varepsilon \rightarrow 0$ we have

$$u(x) \sim U_0\left(\frac{\hat{R} - |p - x|}{\varepsilon}\right), \quad \varepsilon \rightarrow 0 \quad (2)$$

any solution to (PAC) of the form (2) must satisfy (1).

Derivation for cone-shaped domain

- Solution is radially symmetric:

$$\varepsilon^2 u_{rrr} + \frac{1}{r} u_r + f(u) + \varepsilon g(u) = 0$$

- Solvability condition determines radius

Main stability result

Consider an interface at an equilibrium whose radius is \hat{R} . Let ℓ be its length let κ_+, κ_- be the curvatures of the boundary at the points which intersect the interface. Consider the stability problem associated with (PAC),

$$\begin{cases} \lambda\phi = \varepsilon^2 \Delta\phi + f'(u)\phi + \varepsilon g'(u)\phi, & x \in \Omega \\ \partial_n \phi = 0, & x \in \partial\Omega. \end{cases} \quad (\text{EP})$$

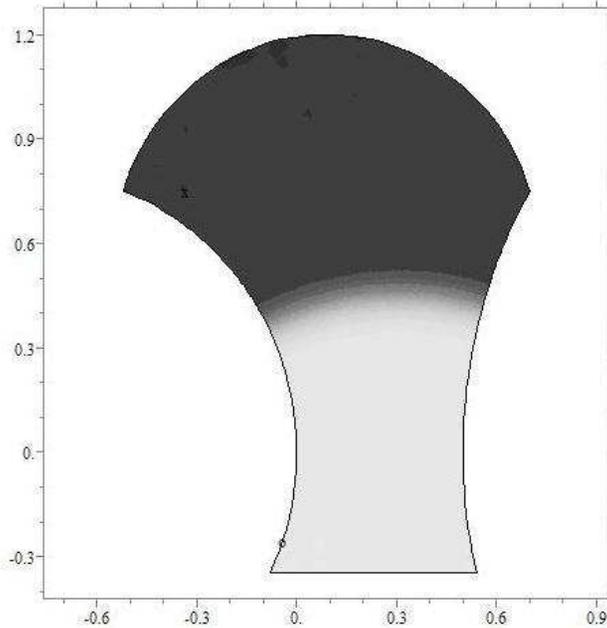
In the limit $\varepsilon \rightarrow 0$, we have $\lambda = \varepsilon^2 \lambda_0$ where λ_0 satisfies

$$\lambda_0 = \frac{1}{\hat{R}} - \mu^2 \quad \text{where} \quad \tan(\ell\mu) = -\frac{\mu(\kappa_+ + \kappa_-)}{\mu^2 - \kappa_+ \kappa_-} \quad (3)$$

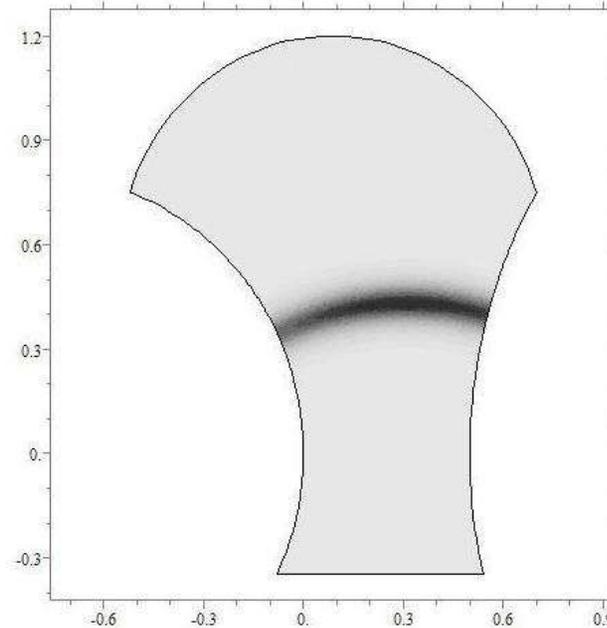
or

$$\arctan\left(\frac{-\kappa_+}{\mu}\right) + \arctan\left(\frac{-\kappa_-}{\mu}\right) = \ell\mu. \quad (4)$$

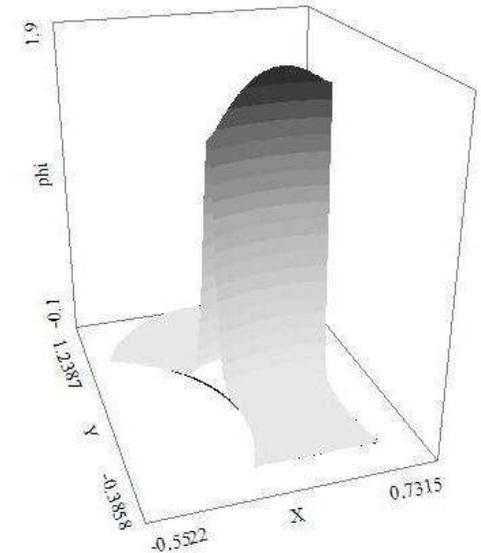
Example



(a)



(b)



(c)

- $u_t = \varepsilon^2 \Delta u - 2(u - \varepsilon a)(u - 1)(u + 1); \quad a = 0.55, \quad \varepsilon = 0.06;$
 $\kappa_- = -1.25, \quad \kappa_+ = -0.667, \quad l = 0.6486.$
- $\hat{R}_{\text{theory}} = 1/(2a) = 0.9091; \quad \hat{R}_{\text{numerical}} = 0.9066$
- $\lambda_{\text{theory}} = 0.00506. \quad \lambda_{\text{numerical}} = 0.00504.$

Instability on a cone domain

Radially symmetric case:

- Expand

$$\phi = \Phi_0(z) + \varepsilon \Phi_1 + \dots$$

$$r = \hat{R} + \varepsilon z$$

- Apply solvability condition
- End result:

$$\lambda_0 = \frac{1}{\hat{R}^2} > 0.$$

- Interface is unstable on a cone [or any convex domain]

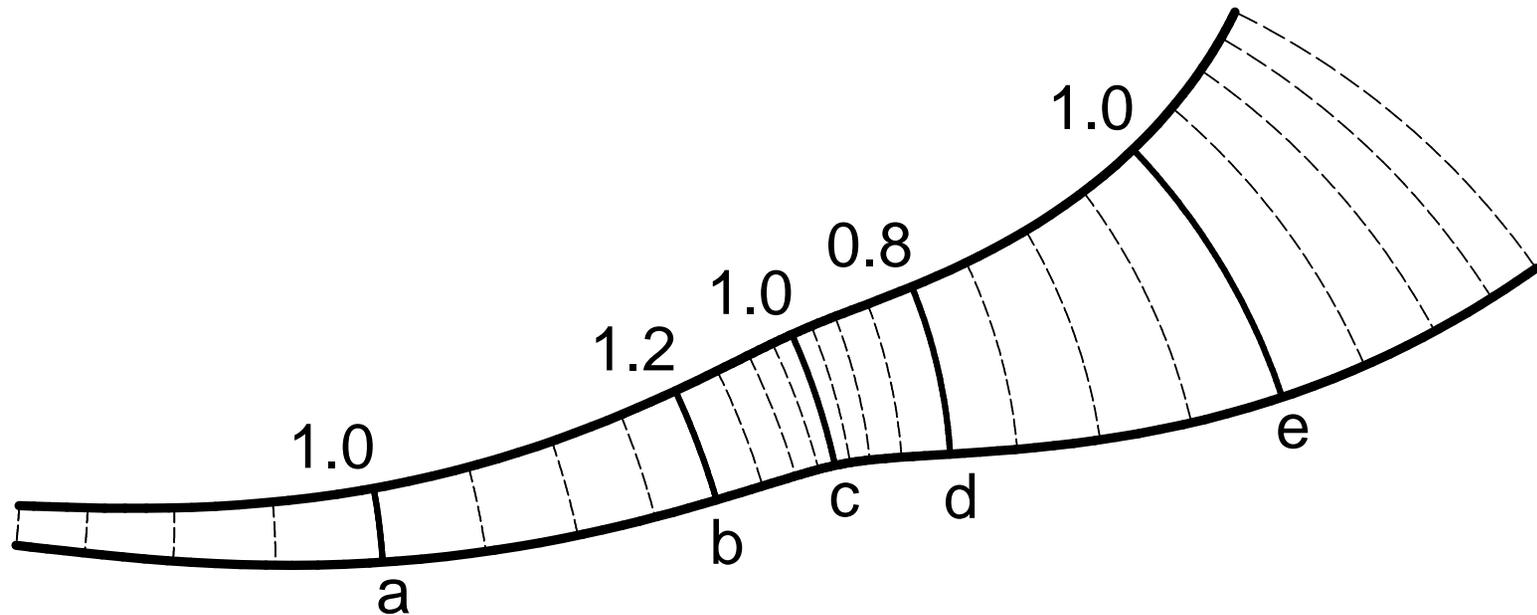
Geometric eigenvalue problem

... Equivalently, $\lambda = \varepsilon^2 \lambda_0$ where λ_0 satisfies

$$\begin{cases} w'' + (\lambda_0 - \hat{R}^{-2})w = 0 \\ w'(-\ell/2) + \kappa_- w(-\ell/2) = 0 \\ w'(\ell/2) + \kappa_+ w(\ell/2) = 0. \end{cases} \quad (\text{GEP})$$

- The standard AC model corresponds straight interface, $\hat{R}^{-1} = 0$. In this case (GEP) is the same as the formula derived by Kowalczyk (2005).
- In the case $\hat{R}^{-1} = 0$, stability threshold $\lambda_0 = 0$ occurs when $l + \kappa_+^{-1} + \kappa_-^{-1} = 0$. Geometrically, the circles tangent to the boundaries are concentric.
- QUESTION: What is the threshold in general case ($\hat{R}^{-1} \neq 0$)?

Geometric criterion for stability

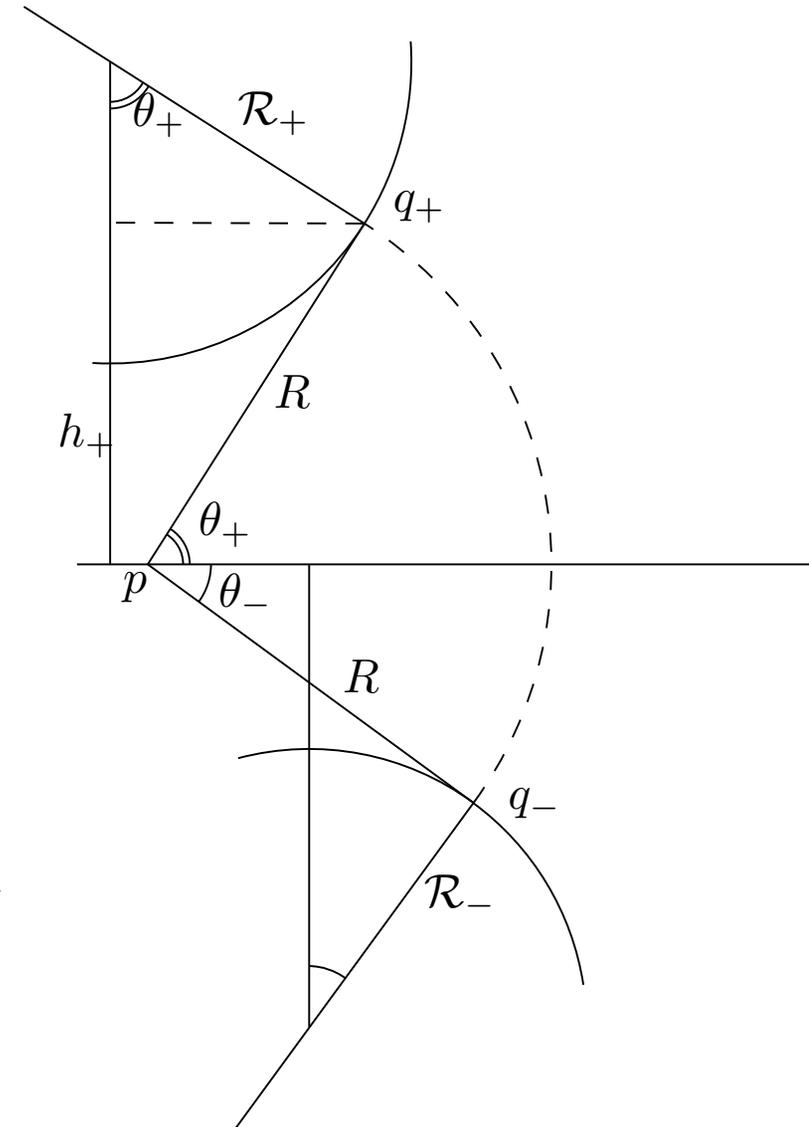


Stability $\iff R'(s) < 0$ whenever $R = \hat{R}$

Example: If $\hat{R} = 1$ then curve c represents the location of a stable interface, whereas curves a and e correspond to unstable interfaces.

Derivation of Geometric Criterion

- $R = \frac{\mathcal{R}_+(1 - \cos \theta_+) + h_+}{\sin \theta_+}$.
- $R' = 0 \iff \arctan\left(\frac{R}{\mathcal{R}_\pm}\right) = \theta_\pm$
- $\theta_+ = \ell_+/R$, $\theta_- = \ell_-/R$ and $\ell = \ell_+ + \ell_-$
- $R' = 0 \iff \lambda_0 = 0$
- For a cone domain, $\lambda_0 = 1/\hat{R}^2 > 0$.
- By continuity, $\lambda_0 > 0$ whenever $R' > 0$.



Open question: Stability of tractrix

- In general, we have

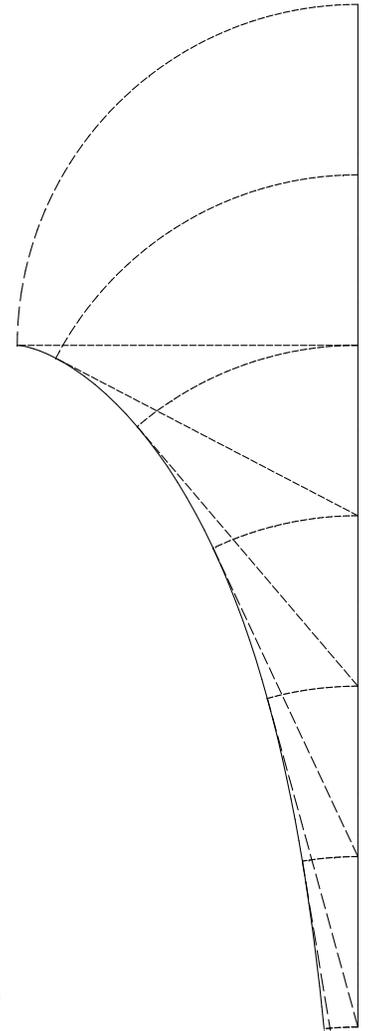
$$R \frac{d\theta}{ds} = p'_1 \sin \theta - p'_2 \cos \theta.$$

where p, θ, R are functions of s , and the boundary of the domain is given by $p + R(\cos \theta, \sin \theta)$.

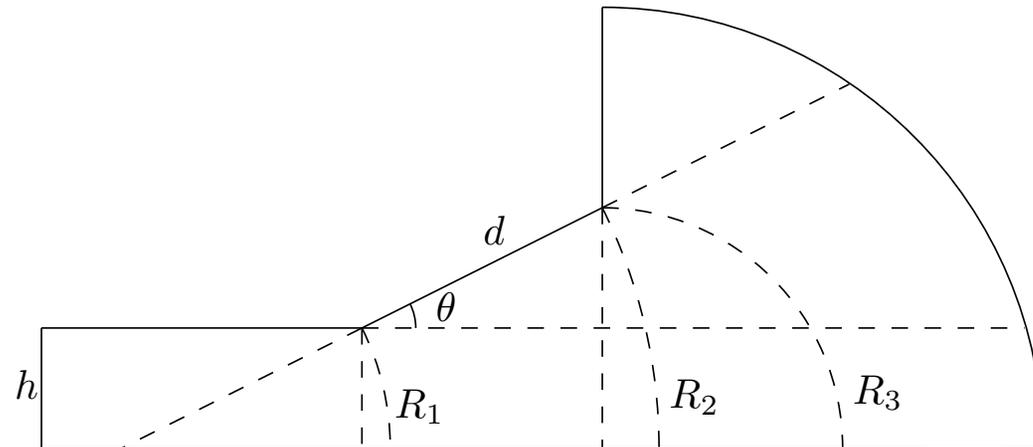
- If R is constant then every circle that intersects the boundary orthogonally has the same radius. The resulting curve is a *tractrix* given by

$$x = \hat{R}(-t + \tanh(t)), \quad y = \hat{R} \operatorname{sech}(t).$$

- $\lambda_0 = 0, \lambda = O(\varepsilon^3)$? **Open question:** Determine stability.



Open question: Corner junctions

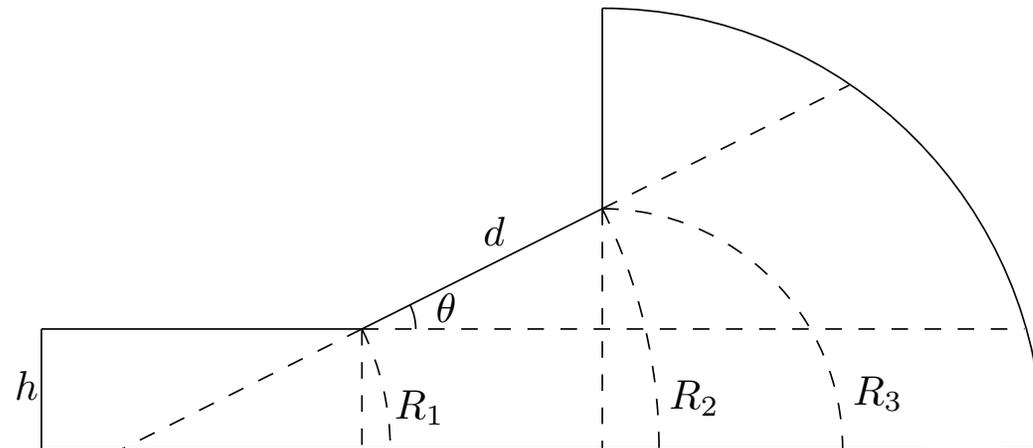


$$R_1 = h / \sin \theta, \quad R_2 = R_1 + d, \quad R_3 = h + d \sin \theta$$

If we “smooth out” the corners and start with an interface at the left...

- If $\hat{R} > R_1$ then interface stops at left corner
- If $R_1 > \hat{R} > R_3$ then interface stops at right corner
- If $\hat{R} < \min(R_1, R_3)$ then interface propagates and dies.

Open question: Corner junctions



Example: $h = 0.2$, $d = 0.5$, $\theta = \pi/6$; then

$$R_1 = 0.6, R_2 = 0.9, R_3 = 0.45$$

- Take $\hat{R} = 0.65$; interface stops at first corner
- Take $\hat{R} = 0.5$; interface stops at second corner
- Take $\hat{R} = 0.4$; interface goes through
- **Open question:** compute λ_0 for corner interface...