

# Ranking and labeling in graphs: Analysis of links and node attributes

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# Course plan: Ranking (2 hours)

- ▶ Feature vectors
  - ▶ Basics of discriminative and max-margin ranking
- ▶ Nodes in a graph
  - ▶ HITS and Pagerank
  - ▶ Personalized Pagerank and variations
  - ▶ Maximum entropy flows
  - ▶ Learning edge conductance

# Course plan: Labeling (1.5 hours)

- ▶ Feature vectors
  - ▶ Discriminative loss minimization
  - ▶ Probabilistic and conditional models
  - ▶ Structured prediction problems
- ▶ Nodes in a graph
  - ▶ Directed Bayesian models, relaxation labeling
  - ▶ Undirected models, some easy graphs
  - ▶ Inference using LP and QP relaxations

# Ranking feature vectors

- ▶ Suppose  $x \in X$  are **instances** and  $\phi : X \rightarrow \mathbb{R}^d$  a **feature vector generator**
- ▶ E.g.,  $x$  may be a document and  $\phi$  maps  $x$  to the “vector space model” with one axis for each word
- ▶ The **score** of instance  $x$  is  $\beta' \phi(x)$  where  $\beta \in \mathbb{R}^d$  is a **weight** vector
- ▶ For simplicity of notation assume  $x$  is already a feature vector and drop  $\phi$
- ▶ We wish to learn  $\beta$  from training data  $\prec$ : “ $i \prec j$ ” means the score of  $x_i$  should be less than the score of  $x_j$ , i.e.,

$$\beta' x_i \leq \beta' x_j$$

## Soft constraints

- ▶ In practice, there may be no feasible  $\beta$  satisfying all preferences  $\prec$
- ▶ For constraint  $i \prec j$ , introduce slack variable  $s_{ij} \geq 0$

$$\beta' x_i \leq \beta' x_j + s_{ij}$$

- ▶ Charge a penalty for using  $s_{ij} > 0$

$$\min_{s_{ij} \geq 0; \beta} \sum_{i \prec j} s_{ij} \quad \text{subject to}$$

$$\beta' x_i \leq \beta' x_j + s_{ij} \quad \text{for all } i \prec j$$

# A max-margin formulation

- ▶ Achieve “confident” separation of loser and winner:

$$\beta' x_i + 1 \leq \beta' x_j + s_{ij}$$

- ▶ Problem: Can achieve this by scaling  $\beta$  arbitrarily; must be prevented by penalizing  $\|\beta\|$

$$\min_{s_{ij} \geq 0; \beta} \frac{1}{2} \beta' \beta + B \sum_{i \prec j} s_{ij} \quad \text{subject to}$$

$$\beta' x_i + 1 \leq \beta' x_j + s_{ij} \quad \text{for all } i \prec j$$

- ▶  $B$  is a magic parameter that balances violations against model strength

# Solving the optimization

- ▶  $\beta'x_i + 1 \leq \beta'x_j + s_{ij}$  and  $s_{ij} \geq 0$  together mean  $s_{ij} = \max\{0, \beta'x_i - \beta'x_j + 1\}$  (“hinge loss”)
- ▶ The optimization can be rewritten without using  $s_{ij}$

$$\min_{\beta} \frac{1}{2} \beta' \beta + B \sum_{i \prec j} \max\{0, \beta'x_i - \beta'x_j + 1\}$$

- ▶  $\max\{0, t\}$  can be approximated by a number of smooth functions
  - ▶  $e^t$  – growth at  $t > 0$  too severe
  - ▶  $\log(1 + e^t)$  – much better, asymptotes to  $y = 0$  as  $t \rightarrow -\infty$  and to  $y = t$  as  $t \rightarrow \infty$

# Approximating with smooth objective

- ▶ Simple unconstrained optimization, can be solved by Newton method

$$\min_{\beta \in \mathbb{R}^d} \frac{1}{2} \beta' \beta + B \sum_{i \prec j} \log(1 + \exp(\beta' x_i - \beta' x_j + 1))$$

- ▶ If  $\beta' x_i - \beta' x_j + 1 \ll 0$ , i.e.,  $\beta' x_i \ll \beta' x_j$ , then pay little penalty
- ▶ If  $\beta' x_i - \beta' x_j + 1 \gg 0$ , i.e.,  $\beta' x_i \gg \beta' x_j$ , then pay large penalty



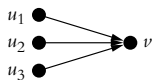
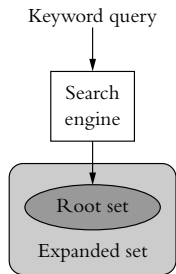
# Ranking nodes in graphs

- ▶ Instances no longer feature vectors sampled from some distribution
- ▶ Instances are (also) nodes in a graph
- ▶ Instance should score highly if high-scoring instances link to it
- ▶ Two instantiations of this intuition

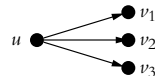
**Hyperlink-induced topic search (HITS):** Nodes have two roles: hubs (fans) and authorities (celebrities)

**Pagerank:** Nodes have only one role: endorse other nodes

# Quick HITS overview



$$a(v) = h(u_1) + h(u_2) + h(u_3)$$



$$h(u) = a(v_1) + a(v_2) + a(v_3)$$

$$\vec{a} \leftarrow (1, \dots, 1)^T, \vec{h} \leftarrow (1, \dots, 1)^T$$

**while**  $\vec{h}$  and  $\vec{a}$  change "significantly" **do**

$$\vec{h} \leftarrow E\vec{a}$$

$$\ell_h \leftarrow \|\vec{h}\|_1 = \sum_w h[w]$$

$$h \leftarrow h/\ell_h$$

$$\vec{a} \leftarrow E^T h_0 = E^T E \vec{a}_0$$

$$\ell_a \leftarrow \|\vec{a}\|_1 = \sum_w a[w]$$

$$\vec{a} \leftarrow \vec{a}/\ell_a$$

**end while**

- ▶ Authority flows along cocitation links, e.g.,  $v_1 \rightarrow u \rightarrow v_2$
- ▶ Note, hub (authority) scores are **copied**, not divided among authority (hub) nodes—important distinction from Pagerank and related approaches

## Detour: Translation models

- ▶ Long-standing goal of Information Retrieval: return documents with words *related to* query words, without damaging precision
- ▶ Retrieval using language models: score document  $d$  wrt a query  $q$  (each interpreted as a set or multiset of words) by estimating  $\Pr(q|d)$ ,
- ▶ If  $q_i$  ranges over query words and  $w$  ranges over all words in the corpus vocabulary, we can write

$$\Pr(q|d) = \prod_i \sum_w t(q_i|w) \Pr(w|d)$$

assuming conditional independence between query words

- ▶  $t(q_i|w)$  is the probability that a corpus  $w$  gets “translated” into query word  $q_i$  (e.g.,  $q_i = \textit{random}$  and  $w = \textit{probability}$ )

# Word-document random walks I

- ▶ Corpus as bipartite graph: word layer, document layer
- ▶ Document node  $d$  connects to word node  $w$  if  $w$  appears in  $d$
- ▶ Random walk with absorption:
  1. Start the walk at node  $v$  initialized to  $w$
  2. Repeat the following sub-steps: With probability  $1 - \alpha$  terminate the walk at  $v$ , and with the remaining probability  $\alpha$  execute these half-steps:
    - 2.1 From word node  $v$ , walk to a random document node  $d$  containing word  $v$
    - 2.2 From document node  $d$  walk to a random word node  $v' \in d$Now set  $v \leftarrow v'$  and loop.
- ▶ Let there be  $m$  words and  $n$  documents

## Word-document random walks II

- ▶ Starting with the  $m$ -node word layer, walking over to the  $n$ -node document layer can be expressed with a  $m \times n$  matrix  $A$ , where  $A_{wd} = \Pr(d|w)$
- ▶ Each row of  $A$  adds up to 1 by design
- ▶ Once we are at the document layer, the transition back to the word layer can be represented with a  $n \times m$  matrix  $B$ , where  $B_{dw} = \Pr(w|d)$
- ▶ Each row of  $B$  adds up to 1 by design
- ▶ In general  $B \neq A'$
- ▶ The overall transition from words back to words is then represented by the matrix product  $C = AB$ , where  $C$  is  $m \times m$
- ▶ Rows of  $C$  add up to one as well

## Word-document random walks III

- ▶ Starting from word  $w$ , the probability that the process stops at word  $q$  after  $k$  steps is given by

$$(1 - \alpha)\alpha^k (C^k)_{wq}$$

where  $(C^k)_{wq}$  is the  $(w, q)$ -entry of the matrix  $C^k$

- ▶ Summing over all possible non-negative  $k$ , we get

$$\begin{aligned} t(q|w) &= (1 - \alpha)(\mathbb{I} + \alpha C + \dots + \alpha^k C^k + \dots)_{wq} \\ &= (1 - \alpha)(\mathbb{I} - \alpha C)_{wq}^{-1} \end{aligned}$$

▶ HW

- ▶ For  $0 < \alpha < 1$ , because rows of  $C$  add up to 1,  $(\mathbb{I} - \alpha C)^{-1}$  will always exist
- ▶ Parameter  $\alpha \in (0, 1)$  controls the amount of diffusion

## Word-document random walks IV

$w = \text{ebolavirus}$ , Web corpus: virus, ebola, hoax, viruses, outbreak, fever, disease, haemorrhagic, gabon, infected, aids, security, monkeys, hiv, zaire

$w = \text{starwars}$ , Web corpus: star, wars, rpg, trek, starwars, movie, episode, movies, war, character, tv, film, fan, reviews, jedi

$w = \text{starwars}$ , TREC corpus: star, wars, soviet, weapons, photo, army, armed, film, show, nations, strategic, tv, sunday, bush, series

- ▶ Starting at given  $w$ , top-scoring  $qs$  make eminent sense
- ▶ Depends on corpus, naturally

# HITS-SVD connection I

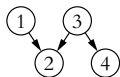
- ▶ Let  $A \in \{0, 1\}^{m \times n}$  be a boolean matrix where  $A_{ij}$  is 1 if and only if word  $i$  ( $1 \leq i \leq m$ ) occurs in document  $j$  ( $1 \leq j \leq n$ )
- ▶ This time let  $B = A'$
- ▶ Do not bother with walk absorption and the parameter  $\alpha$
- ▶ Start from a mix of all words instead of one word, i.e., initialize  $x = \mathbb{1}/m$
- ▶ After transition to documents the weight vector over documents is  $xA$
- ▶ After transition back to words the weight vector over words is  $xAA'$
- ▶  $x, xAA', x(AA')A, x(AA')(AA'), x(AA')^2A, \dots$



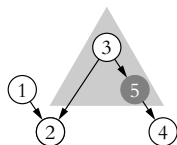
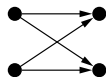
## HITS-SVD connection II

- ▶ Power iterations, converging to dominant eigenvector of  $C = AA'$ ;  $C$  is a symmetric  $m \times m$  matrix
- ▶  $C$  has  $m$  eigenvectors; stack them vertically to get  $U = u_{.1}, u_{.2}, \dots, u_{.m}$
- ▶  $C$  satisfies  $U' C = \Lambda U'$ , where  $\Lambda$  is a diagonal matrix with eigenvalues  $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_m \geq 0$
- ▶ Meanwhile suppose the SVD of  $A$  is  $A_{m \times n} = U_{m \times m} \Sigma_{m \times n} V'_{n \times n}$  where  $U' U = \mathbb{I}_{m \times m}$  and  $V' V = \mathbb{I}_{n \times n}$
- ▶  $\Sigma = \text{diag}(\sigma_1, \dots, \sigma_m)$  of singular values, with  $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > \sigma_{r+1} = \dots = \sigma_m = 0$ , for some  $0 < r \leq m$
- ▶  $C = AA' = U \Sigma V' V \Sigma U' = U \Sigma \mathbb{I} \Sigma U' = U \Sigma^2 U'$ ,  
 $\therefore CU = U \Sigma^2$ , or  $U' C = \Sigma^2 U'$

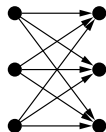
# Topology sensitivity and winner takes all



$$E = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} ; E^T E = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}$$



$$E = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix} ; E^T E = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$



(a)

(b)

- ▶ In (a, upper graph),  $a_2 \leftarrow 2a_2 + a_4$  and  $a_4 \leftarrow a_2 + a_4$  ▶ HW
- ▶ In (a, lower graph),  $a_2 \leftarrow 2a_2 + a_4$ ,  $a_4 \leftarrow a_4$ , and  $a_5 \leftarrow a_2 + a_5$  ▶ HW
- ▶ In (b), after  $k$  steps,  $a_{\text{small}} = 2^{2^i - 1}$  and  $a_{\text{large}} = 3^{2^i - 1}$  — ratio is  $a_{\text{large}}/a_{\text{small}} = (3/2)^{2^i - 1}$  ▶ HW

# HITS score stability I

- ▶  $E$  is the node adjacency matrix
- ▶ Authority vector  $a$  is dominant eigenvector of  $S = E'E$
- ▶ Perturb  $S$  to  $\tilde{S}$ , get  $\tilde{a}$  in place of  $a$
- ▶ Can  $S$  and  $\tilde{S}$  be close yet  $a$  and  $\tilde{a}$  far apart?
- ▶ Let  $\lambda_1 > \lambda_2$  be the two largest eigenvalues of  $S$
- ▶ Let  $\delta = \lambda_1 - \lambda_2 > 0$
- ▶  $S$  has a factorization

$$S = U \begin{bmatrix} \lambda_1 & 0 & \mathbf{0} \\ 0 & \lambda_2 & \mathbf{0} \\ 0 & 0 & \Lambda \end{bmatrix} U',$$

Each column of  $U$  an eigenvector of  $S$  having unit  $L_2$  norm;  $\Lambda$  is a diagonal matrix of remaining eigenvalues

## HITS score stability II

- ▶ Now we define

$$\tilde{S} = S + 2\delta U_{.2} U'_{.2} = U \begin{bmatrix} \lambda_1 & 0 & \mathbf{0} \\ 0 & \lambda_2 + 2\delta & \mathbf{0} \\ 0 & 0 & \Lambda \end{bmatrix} U'.$$

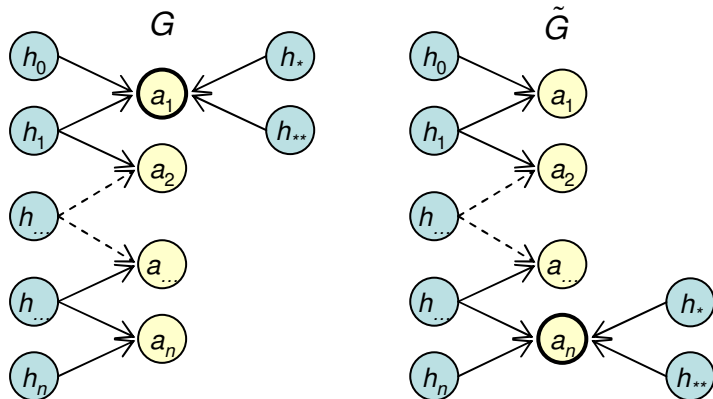
Because  $\|U_{.2}\|_2 = 1$ , the  $L_2$  norm of the perturbation,  $\|\tilde{S} - S\|_2$ , is  $2\delta$ .

- ▶ Given  $\tilde{S}$  instead of  $S$ , how will  $\lambda_1$  and  $\lambda_2$  change to  $\tilde{\lambda}_1$  and  $\tilde{\lambda}_2$ ?
- ▶ By construction  $\tilde{\lambda}_1 = \lambda_1$  while

$$\tilde{\lambda}_2 = \lambda_2 + 2\delta > \lambda_2 + \delta = \lambda_1 = \tilde{\lambda}_1$$

- ▶ Therefore,  $\tilde{\lambda}_1$  and  $\tilde{\lambda}_2$  have switched roles and  $\tilde{\lambda}_2$  is now the *largest* eigenvalue
- ▶ Old  $a = U_{.1}$ ; new  $\tilde{a} = U_{.2}$
- ▶  $\|a - \tilde{a}\|_2 = \|U_{.1} - U_{.2}\| = \sqrt{2}$

# HITS rank stability, adversarial



- ▶ Number of edges changed is  $O(1)$
- ▶  $\Omega(n^2)$  node pairs swapped in authority order ▶ HW

# HITS rank stability in practice

1	Genetic algorithms in search optimization	Goldberg	1	3	1	1	1
2	Adaptation in natural and artificial systems	Holland	2	5	3	3	2
3	Genetic programming: On the programming of...	Koza	3	12	6	6	3
4	Analysis of the behavior of a class of genetic...	De Jong	4	52	20	23	4
5	Uniform crossover in genetic algorithms	Syswerda	5	171	119	99	5
6	Artificial intelligence through simulated...	Fogel	6	135	56	40	8
7	A survey of evolution strategies	Back+	10	179	159	100	7
8	Optimization of control parameters for genetic...	Grefenstette	8	316	141	170	6
9	The GENITOR algorithm and selection pressure	Whitley	9	257	107	72	9
10	Genetic algorithms + Data Structures = ...	Michalewicz	13	170	80	69	18
11	Genetic programming II: Automatic discovery...	Koza	7	-	-	-	10
2060	Learning internal representations by error...	Rumelhart+	-	1	2	2	-
2061	Learning to predict by the method of temporal...	Sutton	-	9	4	5	-
2063	Some studies in machine learning using checkers	Samuel	-	-	10	10	-
2065	Neuronlike elements that can solve difficult...	Barto+Sutton	-	-	8	-	-
2066	Practical issues in TD learning	Tesauro	-	-	9	9	-
2071	Pattern classification and scene analysis	Duda+Hart	-	4	7	7	-
2075	Classification and regression trees	Breiman+	-	2	5	4	-
2117	UCI repository of machine learning databases	Murphy+Aha	-	7	-	8	-
2174	Irrelevant features and the subset selection...	John+	-	8	-	-	-
2184	The CN2 induction algorithm	Clark+Niblett	-	6	-	-	-
2222	Probabilistic reasoning in intelligent systems	Pearl	-	10	-	-	-

- ▶ Random erasure of 30% of the nodes
- ▶ Fairly serious instability
- ▶ Is **random** erasure the right model?

# Pagerank

*... we are involved in an "infinite regress": [an actor's status] is a function of the status of those who choose him; and their [status] is a function of those who choose them, and so ad infinitum.*

*Seeley, 1949*

- ▶ Random surfer roams around graph  $G = (V, E)$
- ▶ Probability of walking from node  $i$  to  $j$  is  $\Pr(j|i) = C(j, i)$
- ▶  $C$  is a  $|V| \times |V|$  nonnegative matrix; each column sums to 1 (what about dead-end nodes?)
- ▶ Steady-state probability of visiting node  $i$  is its **prestige**

# Ways to handle dead-end nodes

- Amputation:** Remove dead-ends, may cause other nodes to become dead-ends, keep removing
- ▶ How to assign scores to the removed nodes?
- Self-loop:** Each dead-end node  $i$  links to itself
- ▶ Still trapped at  $i$ ; need to escape/restart
- Sink node:** Dead-end nodes link to a sink node, which links to itself
- ▶ Reasonable, but probability of visiting sink node means nothing

Makes significant difference to node ranks (scilab demo)



# Steady state probabilities

Long after the walk gets under way, at any time step, the probability that the random surfer is at a given node

Need two conditions for well-defined steady-state probabilities of being in each state/node

- ▶  $E$  must be **irreducible**: should be able to reach any  $v$  starting from any  $u$
- ▶  $E$  must be **aperiodic**: There must exist some  $\ell_0$  such that for every  $\ell \geq \ell_0$ ,  $G$  contains a cycle of length  $\ell$

# Teleport

- ▶ Simple way to satisfy these conditions: all-to-all transitions

$$\tilde{C} = \alpha C + (1 - \alpha) \frac{1}{|V|} \mathbb{1}_{|V| \times |V|}$$

$\mathbb{1}_{|V| \times |V|}$  is a matrix filled with 1s;  $\tilde{C}$  also has columns summing to 1

- ▶ Random surfer **walks** with probability  $\alpha$ , **jumps** with probability  $1 - \alpha$
- ▶ What is the “right” value of  $\alpha$ ?
- ▶ Is  $\alpha$  a device to make  $E$  irreducible and aperiodic, or does it serve other purposes?

## Solving the recurrence

- ▶ Solve  $p = \alpha C p + (1 - \alpha) \mathbb{1}_{|V| \times 1}$  for steady-state visit probability  $p \in \mathbb{R}^{|V| \times 1}$ , with  $p_i \geq 0$ ,  $\|p\|_1 = \sum_i p_i = 1$
- ▶ Consider

$$\hat{C} = \begin{bmatrix} \alpha C_{|V| \times |V|} & \frac{\mathbb{1}_{|V| \times 1}}{|V|} \\ (1 - \alpha) \mathbb{1}_{1 \times |V|} & 0 \end{bmatrix}$$

- ▶ Dummy node  $d$  outside  $V$
- ▶ Transition from every node  $v \in V$  to  $d$
- ▶ And a transition from  $d$  back to every node  $v \in V$
- ▶ Recurrence can now be written as  $\hat{p} = \hat{C} \hat{p}$
- ▶ What is the relation between  $p$  and  $\hat{p}$ ? ▶ HW

# Pagerank score stability

- ▶  $V$  kept fixed
- ▶ Nodes in  $P \subset V$  get incident links changed in any way (additions and deletions)
- ▶ Thus  $G$  perturbed to  $\tilde{G}$
- ▶ Let the random surfer visit (random) node sequence  $X_0, X_1, \dots$  in  $G$ , and  $Y_0, Y_1, \dots$  in  $\tilde{G}$
- ▶ Coupling argument: instead of two random walks, we will design one joint walk on  $(X_i, Y_i)$  such that the marginals apply to  $G$  and  $\tilde{G}$

# Coupled random walks on $G$ and $\tilde{G}$

- ▶ Pick  $X_0 = Y_0 \sim \text{Multi}(r)$
- ▶ At any step  $t$ , with probability  $1 - \alpha$ , reset both chains to a common node using teleport  $r$ :  $X_t = Y_t \in_r V$
- ▶ With the remaining probability of  $\alpha$ 
  - ▶ If  $x_{t-1} = y_{t-1} = u$ , say, and  $u$  remained unperturbed from  $G$  to  $\tilde{G}$ , then pick one out-neighbor  $v$  of  $u$  uniformly at random from all out-neighbors of  $u$ , and set  $X_t = Y_t = v$ .
  - ▶ Otherwise, i.e., if  $x_{t-1} \neq y_{t-1}$  or  $x_{t-1}$  was perturbed from  $G$  to  $\tilde{G}$ , pick out-neighbors  $X_t$  and  $Y_t$  independently for the two walks.

# Analysis of coupled walks I

Let  $\delta_t = \Pr(X_t \neq Y_t)$ ; by design,  $\delta_0 = 0$ .

$$\begin{aligned}\delta_{t+1} &= \Pr(\text{reset at } t+1) \Pr(X_{t+1} \neq Y_{t+1} | \text{reset at } t+1) + \\ &\quad \Pr(\text{no reset at } t+1) \Pr(X_{t+1} \neq Y_{t+1} | \text{no reset at } t+1) \\ &= \Pr(\text{reset at } t+1) \mathbf{0} + \alpha \Pr(X_t \neq Y_t | \text{no reset at } t+1) \\ &= \alpha (\Pr(\underline{X_{t+1} \neq Y_{t+1}}, X_t \neq Y_t | \text{no reset at } t+1) + \\ &\quad \Pr(X_{t+1} \neq Y_{t+1}, X_t = Y_t | \text{no reset at } t+1))\end{aligned}$$

The event  $X_{t+1} \neq Y_{t+1}, X_t = Y_t$  can happen only if  $X_t \in P$ .  
Therefore we can continue the above derivation as follows:

## Analysis of coupled walks II

$$\begin{aligned}\delta_{t+1} &= \dots \\ &\leq \alpha(\Pr(X_t \neq Y_t | \text{no reset at } t+1) + \\ &\quad \Pr(X_{t+1} \neq Y_{t+1}, X_t = Y_t, \underline{X_t \in P} | \text{no reset at } t+1)) \\ &= \alpha(\Pr(X_t \neq Y_t) + \\ &\quad \Pr(X_{t+1} \neq Y_{t+1}, X_t = Y_t, \underline{X_t \in P} | \text{no reset at } t+1)) \\ &\leq \alpha(\Pr(X_t \neq Y_t) + \Pr(X_t \in P)) \\ &= \alpha(\delta_t + \sum_{u \in P} p_u),\end{aligned}$$

(using  $\Pr(H, J|K) \leq \Pr(H|K)$ , and that events at time  $t$  are independent of a potential reset at time  $t+1$ )

Unrolling the recursion,

$$\delta_\infty = \lim_{t \rightarrow \infty} \delta_t \leq (\sum_{u \in P} p_u) / (1 - \alpha) \quad \text{▶ HW}$$

## Analysis of coupled walks III

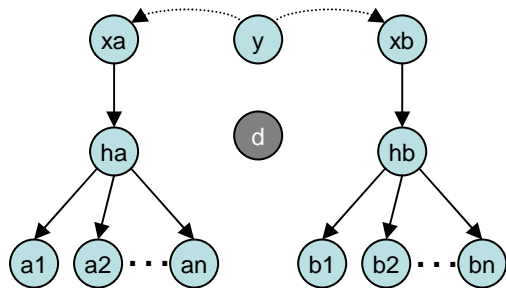
- ▶ Standard result: If the probability of a state disagreement between the two walks is bounded, then their Pagerank vectors must also have small  $L_1$  distance to each other. In particular,

$$\|p - \tilde{p}\|_1 \leq \frac{2 \sum_{u \in P} p_u}{1 - \alpha}$$

- ▶ Lower the value of  $\alpha$ , the more the random surfer teleports and more stable is the system
- ▶ Gives no direct guidance why  $\alpha$  should not be set to exactly zero! (WAW talk)



## Pagerank rank stability: adversarial



- ▶  $G$  formed by connecting  $y$  to  $x_a$ ,  $\tilde{G}$  by connecting  $y$  to  $x_b$
- ▶  $\Omega(n^2)$  node pairs flip PageRank order ▶ HW
- ▶ I.e.,  $L_1$  score stability does not guarantee rank stability
- ▶ Can “natural” social networks lead often to such tie-breaking?

# Pagerank rank stability: In practice

1	Genetic Algorithms in Search, Optimization and...	Goldberg	1	1	1	1	1
2	Learning internal representations by error...	Rumelhart+	2	2	2	2	2
3	Adaptation in Natural and Artificial Systems	Holland	3	5	6	4	5
4	Classification and Regression Trees	Breiman+	4	3	5	5	4
5	Probabilistic Reasoning in Intelligent Systems	Pearl	5	6	3	6	3
6	Genetic Programming: On the Programming of...	Koza	6	4	4	3	6
7	Learning to Predict by the Methods of Temporal...	Sutton	7	7	7	7	7
8	Pattern classification and scene analysis	Duda+Hart	8	8	8	8	9
9	Maximum likelihood from incomplete data via...	Dempster+	10	9	9	11	8
10	UCI repository of machine learning databases	Murphy+Aha	9	11	10	9	10
11	Parallel Distributed Processing	Rumelhart+	-	-	-	10	-
12	Introduction to the Theory of Neural Computation	Hertz+	-	10	-	-	-

- ▶ Quite stable, nowhere near adversarial
- ▶ Random 30% erasure hits many unpopular nodes,  
 $\sum_{u \in P} p_u$  small
- ▶ Is random erasure a good assumption?

## Other nonstandard path decay functions

- ▶ Standard Pagerank can be written as

$$p(\alpha) = (1 - \alpha) \sum_{t \geq 0} \alpha^t r P^t = (1 - \alpha) (\mathbb{I} - \alpha P)^{-1} \frac{\mathbb{1}}{|V|}$$

where  $P$  is the row-normalized node adjacency matrix

- ▶ For path  $\pi = (x_1, \dots, x_k)$ , let

$$\text{branching}(\pi) = \frac{1}{d_1 d_2 \cdots d_{k-1}}$$

- ▶ Equivalent Pagerank expression is

$$p_i(\alpha) = \sum_{\pi \in \text{path}(\cdot, i)} (1 - \alpha) \alpha^{|\pi|} \text{branching}(\pi) / |V|$$

- ▶ Can generalize to

$$p_i = \sum_{\pi \in \text{path}(\cdot, i)} \text{damping}(|\pi|) \text{branching}(\pi) / |V|$$

- ▶ Important application: fighting link spam

# Probabilistic HITS variants

In the analysis thus far, Pagerank's stability over HITS seems to come from two features:

- ▶ Pagerank *divides* among out-neighbors; hub score *copies* (which is why in HITS continual rescaling is needed)
- ▶ Pagerank uses teleport; HITS does not

Consider this authority-to-authority transition, starting at  $u$

- ▶ Walk back to an in-neighbor of  $u$ , say  $w$ , chosen uniformly at random from all in-neighbors of  $v$
- ▶ From  $w$  walk forward to an out-neighbor of  $w$ , chosen uniformly at random from all out-neighbors of  $w$

No teleport yet, but dividing rather than copying

# SALSA

- ▶ Combining the two half-steps, transition probability from authority  $v$  to authority  $w$  is

$$\Pr(w|v) = \frac{1}{\text{InDegree}(v)} \sum_{(u,v),(u,w) \in E} \frac{1}{\text{OutDegree}(u)}$$

- ▶ Suppose all pairs of authority nodes are connected to each other through alternating hub-authority paths
- ▶ Then  $\pi_v \propto \text{InDegree}(v)$  is a fixpoint of the authority-to-authority transition process ▶ HW
- ▶ Overkill? Prevents **any** cocitation-based reinforcement!

# HITS with teleport I

- ▶ Let the given graph be  $G = (V, E)$ . Remove any isolated nodes from  $G$  where no edge is incident.
- ▶ From  $G$  construct a bipartite graph  $G_2 = (L, R, E_2)$ , with  $L = R = V$  and for each  $(u, v) \in E$  connect the node corresponding to  $u$  in  $L$  to the node corresponding to  $v$  in  $R$ . By construction every node in  $L$  has some outlink and every node in  $R$  has some inlink.
- ▶ Write down the  $(2|V|) \times (2|V|)$  node adjacency matrix for  $G_2$ .
- ▶ Write down the row-normalized node-adjacency matrix, which we will call  $E_2^{\text{row}}$ . Each row corresponding node  $u \in L$  will add up to 1, and the rows for  $v \in R$  will be all zeros.

## HITS with teleport II

- ▶ Write down the column-normalized node-adjacency matrix, which we will call  $E_2^{\text{col}}$ . Each row corresponding to node  $v \in R$  will add up to 1, and the rows for  $u \in L$  will be all zeros.
- ▶ Initialize an authority vector  $a^{(0)}$  to be nonzero only for  $v \in R$ , with value  $1/|R|$ , and zero for all  $u \in L$ . Let  $\mathbb{1}_h$  represent the uniform teleport vector distributed only over nodes in  $L$ , and  $\mathbb{1}_a$  represent the uniform teleport vector

## HITS with teleport III

distributed only over nodes in  $R$ . Compute the following iteratively:

$$h^{(1)} = \alpha a^{(0)} E_2^{\text{col}} + (1 - \alpha) \mathbb{1}_h$$

$$a^{(1)} = \alpha h^{(1)} E_2^{\text{row}} + (1 - \alpha) \mathbb{1}_a$$

... ..

$$h^{(k)} = \alpha a^{(k-1)} E_2^{\text{col}} + (1 - \alpha) \mathbb{1}_h$$

$$a^{(k)} = \alpha h^{(k)} E_2^{\text{row}} + (1 - \alpha) \mathbb{1}_a$$

etc. until convergence



# HITS with teleport: Experience

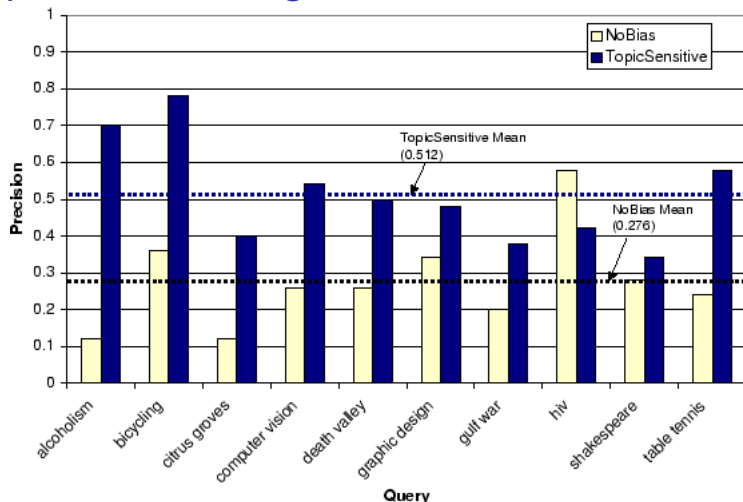
1	Learning internal representations by error...	Rumelhart+	1	3	3	2	1
2	Probabilistic Reasoning in Intelligent Systems	Pearl	4	1	1	1	2
3	Classification and Regression Trees	Breiman+	2	2	2	3	4
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5	Maximum likelihood from incomplete data via...	Dempster+	5	6	6	6	5
6	A robust layered control system for a mobile robot	Brook+	6	5	5	5	6
7	Numerical Recipes in C	Press+al	7	7	7	7	7
8	Learning to Predict by the Method of Temporal...	Sutton	8	8	8	8	8
9	STRIPS: A New Approach to ... Theorem Proving	Fikes+	9	10	10	10	15
10	Introduction To The Theory Of Neural Computation	Hertz+	11	11	9	9	9
11	Stochastic relaxation, gibbs distributions, ...	Geman+	10	9	-	-	-
12	Introduction to Algorithms	Cormen+	-	-	-	-	10

- ▶ Clearly much more rank-stable than HITS
- ▶ Is  $\alpha$  all there is to stability?
- ▶ How to set  $\alpha$  taking both content and links into account?  
(WAW talk)

# Personalized Pagerank

- ▶ Recall we were solving  $p = \alpha Cp + (1 - \alpha) \frac{\mathbb{1}_{|V| \times 1}}{|V|}$
- ▶ Can replace  $\frac{\mathbb{1}_{|V| \times 1}}{|V|}$  with arbitrary **teleport vector**  $r$ ,  $r_i \geq 0$ ,  $\sum_i r_i = 1$ , examples:
  - ▶  $r_i > 0$  for pages  $i$  that you have bookmarked, 0 for other pages
  - ▶  $r_i > 0$  for pages about topic “Java programming”, 0 for other pages
- ▶ Extreme case of  $r$ :  $r_i = 1$  for some specific node, 0 for all others —  $r$  called  $x_i$  in that case (“basis vector”)
- ▶  $p$  is a function of  $r$  (and  $C$ ) — write as  $p_r$

# Topic-sensitive Pagerank



- ▶ Details of how query is “projected” to topic space
- ▶ Clear improvement in precision

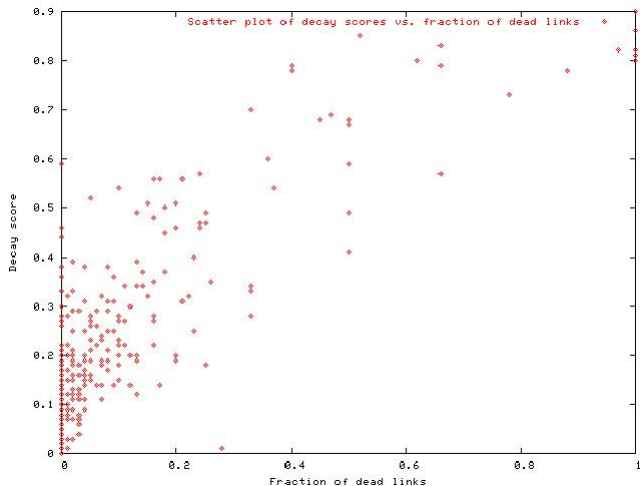
## Page staleness

“A page is stale if it is inaccessible, or if it links to many stale pages”—to find how stale a page  $u$  is,

- 1:  $v \leftarrow u$
- 2: **for** ever **do**
- 3:   **if** page  $v$  is inaccessible **then**
- 4:     return  $s(u) = 1$
- 5:   toss a coin with head probability  $\sigma$
- 6:   **if** head **then**
- 7:     **return**  $s(u) = 0$  {with probability  $\sigma$ }
- 8:   **else**
- 9:     choose  $w : (v, w) \in E$  with probability  $\propto C(w, v)$
- 10:     $v \leftarrow w$

$$s(u) = \begin{cases} 1, & u \in D \\ (1 - \sigma) \sum_v C(v, u) s(v), & \text{otherwise} \end{cases}$$

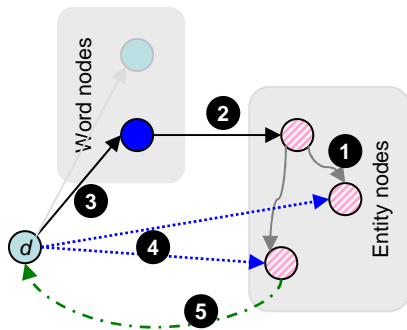
# Page staleness: Experience



Staleness of a page is generally larger than the fraction of dead links on the page would have you believe

# Biased walk for keyword search in graphs

- ▶ Teleport to query word nodes (3)
- ▶ Also teleport to entity nodes (4)
- ▶ Competition between relevance to query and query-independent prestige
- ▶ Each edge  $e$  has type  $t(e)$  and weight  $\beta(t(e))$



# Effect of tuning edge weights

transaction serializability, $\beta(d \rightarrow \text{word})/\beta(d \rightarrow \text{entity}) = 1$	#cites
Graph based algorithms for boolean function manipulation	506
Scheduling algorithms for multiprogramming in a hard real time environment	413
A method for obtaining digital signatures and public key cryptosystems	312
Rewrite systems	265
Tcl and the Tk toolkit	242
transaction serializability, $\beta(d \rightarrow \text{word})/\beta(d \rightarrow \text{entity}) = 10^6$	#cites
On serializability of multidatabase transactions through forced local conflicts	38
Autonomous transaction execution with epsilon serializability	6
The serializability of concurrent database updates	104
Serializability a correctness criterion for global concurrency control in interbase	41
Using tickets to enforce the serializability of multidatabase transactions	12

- ▶ For small  $\beta(d \rightarrow \text{word})$ , query is essentially ignored
- ▶ Larger  $\beta(d \rightarrow \text{word})$  gives better balance between query-independent prestige and query-dependent match
- ▶ Can learn  $\beta(t)$ s up to a scale factor from  $\prec$  (WAW talk)

# Personalization: Two key properties

- ▶ Cannot pre-compute  $p_r$  for all possible  $r$
- ▶ Can we assemble Pageranks for an arbitrary  $r$  from Pageranks computed using “basis vectors”?

**Linearity:** If  $p_{r_1}$  is a solution to  $p = \alpha Cp + (1 - \alpha)r_1$  and  $p_{r_2}$  is a solution to  $p = \alpha Cp + (1 - \alpha)r_2$ , then  $p = \lambda p_1 + (1 - \lambda)p_2$  is a solution to  $p = \alpha Cp + (1 - \alpha)(\lambda r_1 + (1 - \lambda)r_2)$ , where  $0 \leq \lambda \leq 1$

**Decomposition:** If  $p_{x_u}$  is the Pagerank vector for  $r = x_u$  and  $u$  has outlinks to neighbors  $v$ , then

$$p_{x_u} = \sum_{(u,v) \in E} \alpha C(v, u) p_{x_v} + (1 - \alpha)x_u$$

▶ HW



## Learning $r$ from $\prec$

- ▶ Recall  $p = \alpha Cp + (1 - \alpha)r$ , i.e.,  $(\mathbb{I} - \alpha C)p = (1 - \alpha)r$ , or  $p = (1 - \alpha)(\mathbb{I} - \alpha C)^{-1}r = Mr$ , say
- ▶  $\prec$  can be encoded as matrix  $\Pi \in \{-1, 0, 1\}^{|V| \times |V|}$  and written as  $\Pi p \geq \mathbf{0}^{|V| \times 1}$  (each row expresses one pair preference)
- ▶ “Parsimonious teleport” is uniform  $r_0 = \mathbb{1}_{|V| \times 1} / |V|$ ; that gives us standard Pagerank vector  $p_0 = Mr_0$
- ▶ Want to deviate from  $p_0$  as little as possible while satisfying  $\prec$

$$\min_{r \in \mathbb{R}^{|V|}} (Mr - p_0)'(Mr - p_0) \quad \text{subject to}$$

$$\Pi Mr \geq \mathbf{0}, \quad r \geq \mathbf{0}, \quad \mathbb{1}'r = 1$$

(quadratic objective with linear inequalities)

# Pagerank as network flow

- ▶ Extend from learning  $r$  to learning “flow” of Pagerank on each edge  $p_{uv} = p_u C(v, u) = p_u \Pr(v|u)$
- ▶ A valid flow satisfies

$$\sum_{(u,v) \in E'} p_{uv} = 1 \quad (\text{Total})$$

$$\forall v \in V' \quad \sum_{(u,v) \in E'} p_{uv} = \sum_{(v,w) \in E'} p_{vw} \quad (\text{Balance})$$

For all  $v \in V_o \subseteq V$  having at least one outlink

$$(1 - \alpha) \sum_{(v,w) \in E} p_{vw} = \alpha p_{vs} \quad (\text{Teleport})$$

- ▶ Pagerank satisfies these constraints, but so do many other flows

# Maximum entropy flow

- ▶ Any principle to prefer one flow over another? **Maximize entropy**  $\sum_{(u,v) \in E'} -p_{uv} \log p_{uv}$
- ▶ Or, stay close to a reference flow  $q$  by  $\min_p \text{KL}(p||q)$
- ▶ The flows  $p_{uv}$  look like ( $\beta$  and  $\tau$  unconstrained) ▶ HW

$$\forall v \in V \quad p_{dv} = (1/Z) q_{dv} \exp(\beta_v - \beta_d)$$

$$\forall v \in V_o \quad p_{vd} = (1/Z) q_{vd} \exp(\beta_d - \beta_v + \alpha \tau_v)$$

$$\forall v \in V \setminus V_o \quad p_{vd} = (1/Z) q_{vd} \exp(\beta_d - \beta_v)$$

$$\forall (u, v) \in E \quad p_{uv} = (1/Z) q_{uv} \exp(\beta_v - \beta_u - (1 - \alpha)\tau_u)$$

- ▶ Dual objective is  $\max_{\beta, \tau} -\log Z$ , with  $Z = \sum_{(u,v) \in E'} p_{uv}$
- ▶ Can now add constraints like (WAW talk)

$$\forall u \prec v : \sum_{(w,u) \in E'} p_{wu} - \sum_{(w,v) \in E'} p_{wv} \leq 0 \quad (\text{Preference})$$

## Labeling feature vectors and graph nodes

# Labeling feature vectors

**Training data:**  $(x_i, y_i)$ ,  $i = 1, \dots, n$ ,  $x_i \in \mathcal{X}$  (often  $\mathbb{R}^d$ )  
 $y_i \in \mathcal{Y} = \{-1, +1\}$

**Single test instance:** Given  $x$  not seen before, want to predict  $Y$

**Batch of test instances:** Given many  $x$ s in a batch, predict  $Y$  for each  $x$

**Transductive learning:** Given training and test batch together

**Predictor:** A parameterized function  $f : \mathcal{X} \rightarrow \mathcal{Y}$ ; parameters learnt from training data

**Loss:** For instance  $(x, y)$ , 1 if  $f(x) \neq y$ , 0 otherwise

**Training loss:**  $\sum_{i=1}^n \mathbb{I}[y_i \neq f(x_i)]$

# Supervised learning approaches

**Discriminative learning:** Directly minimize (regularized) training loss

**Joint probabilistic learning:** Build a model for  $\Pr(x, y)$ , use Bayes rule to get  $\Pr(Y = y|x)$

**Conditional probabilistic learning:** Directly build a model for  $\Pr(Y = y|x)$

## Linear parameterization of $f$

- ▶ Let  $f(x) = x\beta$ , where  $x \in \mathbb{R}^{1 \times d}$  and  $\beta \in \mathbb{R}^{d \times 1}$
- ▶ Training loss  $\sum_{i=1}^n \mathbb{I}[y_i \neq f(x_i)] = \sum_{i=1}^n \mathbb{I}[y_i x_i \beta < 0]$
- ▶ As in ranking, we may insist on more than  $y_i x_i \beta \geq 0$ ; say we want  $y_i x_i \beta \geq 1$
- ▶ Training loss is  $\sum_{i=1}^n \mathbb{I}[y_i x_i \beta < 1] = \sum_i \text{step}(1 - y_i x_i \beta)$

$$\text{step}(z) = \begin{cases} 0, & z \leq 0 \\ 1, & z > 0 \end{cases}$$

- ▶ Step function has two problems wrt optimization of  $\beta$ 
  - ▶ It is not differentiable everywhere
  - ▶ It is not convex
- ▶ Design surrogates for training loss so that we can search for  $\beta$

# Hinge loss

- ▶  $\max\{0, 1 - y_i x_i \beta\}$  is an upper bound on training loss

$$\min_{\beta, s} \frac{1}{2} \beta' \beta + \frac{B}{n} \sum_i s_i \quad \text{subject to}$$
$$\forall i \quad s_i \geq 1 - y_i x_i \beta, \quad s_i \geq 0$$

- ▶ Standard soft-margin primal SVM; dual is [▶ HW](#)

$$\min_{\alpha \in \mathbb{R}^n} \frac{1}{2} \alpha' X' Y' Y X \alpha - \mathbb{1}' \alpha$$

subject to  $\forall i : 0 \leq \alpha_i \leq B$  and  $y' \alpha = \mathbf{0}$

Here  $y = (y_1, \dots, y_n)'$  and  $Y = \text{diag}(y)$ .



## Soft hinge loss

- ▶ “Soft hinge loss”  $\ln(1 + \exp(1 - y_i x_i \beta))$  is a reasonable approximation for  $\max\{0, 1 - y_i x_i \beta\}$
- ▶ (Primal) optimization becomes

$$\min_{\beta} \frac{1}{2} \beta' \beta + \frac{B}{n} \sum_i \ln(1 + \exp(1 - y_i x_i \beta))$$

- ▶ Compare with logistic regression with a Gaussian prior:

$$\begin{aligned} & \max_{\beta} \sum_i \log \Pr(y_i | x_i) - \frac{\lambda}{2} \beta' \beta \\ & = \min_{\beta} \sum_i -\log \Pr(y_i | x_i) + \frac{\lambda}{2} \beta' \beta \\ & = \min_{\beta} \sum_i \ln(1 + \exp(-y x_i \beta)) + \frac{\lambda}{2} \beta' \beta \end{aligned}$$

# Classification for large $\mathcal{Y}$

Collective labeling of a large number of instances, whose labels cannot be assumed to be independent, e.g.,

- ▶ Assigning multiple topics from a topic tree/dag to a document
- ▶ Assigning parts of speech (pos) to a sequence of tokens in a sentence
- ▶ Matching tokens across an English and a Hindi sentence that say the same thing

A generic device: include  $x$  and  $y$  into a feature generator

$$\psi : \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}^d$$

- ▶ Given  $x$ , prediction is  $\arg \max_{y \in \mathcal{Y}} \beta' \psi(x, y)$
- ▶ In training set, want  $\beta' \psi(x_i, y_i)$  to beat  $\beta' \psi(x_i, y)$  for all  $y \neq y_i$

## Large $\mathcal{Y}$ example: Markov chain

- ▶ For simplicity assume all sequences of length exactly  $T$ ;  $x, y$  now sequences of length  $T$
- ▶ Labels  $\Sigma$  (noun, verb, preposition, etc.);  $\mathcal{Y} = \Sigma^T$ , huge
- ▶  $x_i^t$  ( $y_i^t$ ) is the  $t$ th token (label) of the  $i$ th instance
- ▶ Suppose there are  $W$  word-based features, e.g., hasCap, hasDigit etc.
- ▶  $\psi(x, y) \in \mathbb{R}^d$  where  $d = W|\Sigma| + |\Sigma||\Sigma|$

$$\psi(x, y) = \sum_{t=1}^T \psi(y^{t-1}, y^t, x, t),$$

$$\text{where } \psi(y, y', x, t) = \left( \underbrace{\hat{\psi}(x, y')}_{W|\Sigma|, \text{emission}}, \underbrace{\vec{\psi}(y, y')}_{|\Sigma||\Sigma|, \text{transition}} \right)$$

- ▶ Corresponding model weights  $\beta = (\hat{\beta}, \vec{\beta}) \in \mathbb{R}^d$

# Max-margin training for large $\mathcal{Y}$

- ▶ Given  $(x_i, y_i)$ ,  $i = 1, \dots, n$ , want to find  $\beta$  such that for each instance  $i$ ,

$$\beta' \psi(x_i, y_i) \geq \beta' \psi(x_i, y) + \text{margin} \quad \forall y \in \mathcal{Y} \setminus \{y_i\}$$

- ▶ Leads to the following optimization problem:

$$\min_{\beta, s \geq 0} \frac{1}{2} \beta' \beta + \frac{B}{n} \sum_i s_i \quad \text{subject to}$$

$$\forall i, \forall y \neq y_i \quad \beta' \delta \psi_i(y) \geq 1 - \frac{s_i}{\Delta(y_i, y)}$$

- ▶  $\Delta(y_i, y)$  is severity of mismatch
- ▶  $\delta \psi_i(y)$  is shorthand for  $\psi(x_i, y_i) - \psi(x_i, y)$
- ▶ Exponential number of constraints in primal and variables  $\alpha_{iy}$  in dual

# Cutting plane algorithm to optimize dual

- ▶ Primal:  $\min_x f(x)$  subject to  $g(x) \leq \mathbf{0}$
- ▶ Dual:  $\max_{x,z} z$  subject to  $u \geq \mathbf{0}$ ,  $z \leq f(x) + u'g(x) \quad \forall x$
- ▶ Approximate finite dual:  $\max z$  s.t.  $z \leq f(x_j) + u'g(x_j)$  for  $j = 1, \dots, k - 1$ ,  $u \geq \mathbf{0}$
- ▶ “Master program”: for  $k = 1, 2, \dots$ 
  - ▶ Let  $(z_k, u_k)$  be current solution
  - ▶ Solve  $\min_x f(x) + u_k'g(x)$  to get  $x_k$
  - ▶ If  $z_k \leq f(x_k) + u_k'g(x_k) + \epsilon$  terminate
  - ▶ Add constraint  $z \leq f(x_k) + u'g(x_k)$  to approximate dual
- ▶ Dual max objective is non-decreasing with  $k$
- ▶ Strictly increasing if  $\epsilon > 0$

# SVM training for structured prediction

- 1:  $S_i = \emptyset$  for  $i = 1, \dots, n$
- 2: **repeat**
- 3:   **for**  $i = 1, \dots, n$  **do**
- 4:     current  $\beta = \sum_j \sum_{y' \in S_j} \alpha_{jy'} \delta\psi_j(y')$  (Representer Theorem)
- 5:     we want  $\beta' \delta\psi_i(y) \geq 1 - s_i / \Delta(y_i, y)$  or  
       $s_i \geq \Delta(y_i, y)(1 - \beta' \delta\psi_i(y)) = H(y)$ , say
- 6:      $\hat{y}_i = \arg \max_{y \in \mathcal{Y}} H(y)$  {to look for violations}
- 7:      $\hat{s}_i = \max\{0, \max_{y \in S_i} H(y)\}$
- 8:     **if**  $H(\hat{y}_i) > \hat{s}_i + \epsilon$  **then**
- 9:       add  $\hat{y}$  to  $S_i$  {admit  $\alpha_{i\hat{y}}$  into dual}
- 10:      $\alpha_S \leftarrow$  dual optimum for  $S = \cup S_i$
- 11: **until** no  $S_i$  changes

## Structured SVM: Analysis sketch

- ▶ Let  $\bar{\Delta} = \max_{i,y} \Delta(y_i, y)$ ,  $\bar{R} = \max_{i,y} \|\delta\psi_i(y)\|_2$
- ▶ After every inclusion, dual objective increases by

$$\min \left\{ \frac{B\epsilon}{2n}, \frac{\epsilon^2}{8\bar{\Delta}^2\bar{R}^2} \right\}$$

- ▶ Dual objective upper bounded by min of primal which is at most  $B\bar{\Delta}$
- ▶ Number of inclusion rounds is at most

$$\max \left\{ \frac{2n\bar{\Delta}}{\epsilon}, \frac{8B\bar{\Delta}^3\bar{R}^2}{\epsilon^2} \right\}$$

- ▶ Need inference subroutine:  $\max_y \Delta(y_i, y)(1 - \beta' \delta\psi_i(y))$
- ▶ Can do this for Markov chains in poly time ▶ HW

# Directed probabilistic view of Markov network

Concrete setting:

- ▶ Hypertext graph  $G(V, E)$
- ▶ Each node  $u$  is associated with observable text  $x(u)$ ; text of node set  $A$  denoted  $x(A)$
- ▶ Each node has unknown (topic) label  $y_u$ ; labels of node set  $A$  denoted  $y(A)$

Our goal is

$$\arg \max_{y(V)} \Pr(y(V) | E, x(V)) = \arg \max_{y(V)} \frac{\Pr(y(V)) \Pr(E, x(V) | y(V))}{\Pr(E, x(V))}$$

where  $\Pr(E, x(V)) = \sum_{y(V)} \Pr(y(V)) \Pr(E, x(V) | y(V))$

is a scaling factor (which we do not need to know for labeling).



## Using the Markov assumption

- ▶  $V^K \subset V$  has known labels  $y(V^K)$
- ▶ Fix node  $v$  with neighbors  $N(v)$
- ▶ Known labels for  $N^K(v)$ , unknown labels for  $N^U(v)$

$$\begin{aligned} & \Pr(Y(v) = y | E, x(V), y(V^K)) \\ &= \sum_{y(N^U(v)) \in \Omega_v} \Pr(y, y(N^U(v)) | E, x(V), y(V^K)) \\ &= \sum_{y(N^U(v)) \in \Omega_v} \Pr(y(N^U(v)) | E, x(V), y(V^K)) \\ & \qquad \qquad \qquad \Pr(y | y(N^U(v)), E, x(V), y(V^K)) \end{aligned}$$

- ▶  $\Omega_v =$  label configurations of  $N^U(v)$  (can be large)
- ▶ “Solve for” all  $\Pr(Y(v) = y | \dots)$  simultaneously

# Relaxation labeling

- ▶ To ease computation, approximate as in naive Bayes

$$\begin{aligned} \Pr(y(N^U(v)) \mid E, x(V), y(V^K)) \\ \approx \prod_{w \in N^U(v)} \Pr(y(w) \mid E, x(V), y(V^K)) \end{aligned}$$

- ▶ Estimated class probabilities in the  $r$ th round is  $\Pr_{(r)}(y(v) \mid E, x(V), y(V^K))$ .
- ▶ May use a text classifier for  $r = 0$

## Relaxation steps

- ▶ Update as follows

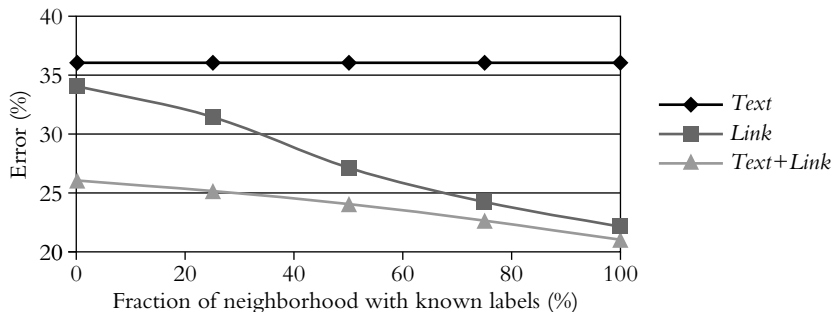
$$\frac{\Pr_{(r+1)}(y(v) \mid E, x(V), y(V^K))}{\approx \sum_{y(N^U(v)) \in \Omega_v} \left[ \frac{\prod_{w \in N^U(v)} \Pr_{(r)}(y(w) \mid E, x(V), y(V^K))}{\Pr(y(v) \mid y(N^U(v)), E, x(V), y(V^K))} \right]}$$

- ▶ More approximations

$$\begin{aligned} \Pr(y(v) \mid y(N^U(v)), E, x(V), y(V^K)) \\ \approx \Pr(y(v) \mid y(N^U(v)), E, x(V), y(N^K(v))) \\ \approx \Pr(y(v) \mid y(N(v)), x(v)) \end{aligned}$$

- ▶ Add terms for deterministic annealing? ▶ HW

## Relaxation labeling: Sample results



- ▶ Randomly sample node, grow neighborhood, randomly erase fraction of known labels, reconstruct, evaluate
- ▶ Text+link better than link better than text-only
- ▶ Link better than text even when **all** labels wiped out! (associative prior: pages link to similar pages)

# Undirected view of Markov network

- ▶ Each node  $u$  represents random variable  $X_u$
- ▶ Undirected edges express potential dependencies
- ▶ Each clique  $c \subset V$  has associated **potential function**  $\phi_c$ 
  - ▶ Input to  $\phi$  is an assignment of values to  $X_c$ , say  $x_c$
  - ▶  $\phi$  outputs a real number
- ▶  $\Pr(x) \propto \prod_{c \in \mathcal{C}} \phi_c(x_c)$  ( $\mathcal{C}$  is set of all cliques) —  
Hammersley-Clifford theorem
- ▶  $\Pr(x) = (1/Z) \prod_{c \in \mathcal{C}} \phi_c(x_c)$  where  $Z = \sum_x \prod_{c \in \mathcal{C}} \phi_c(x_c)$   
is the **partition function**

## Conditional Markov networks

- ▶ Each node  $v$  has observable  $x_v$  and unobserved label  $y_v$

$$\Pr(y|x) = \frac{1}{Z(x)} \prod_{c \in \mathcal{C}} \phi(x, y_c)$$

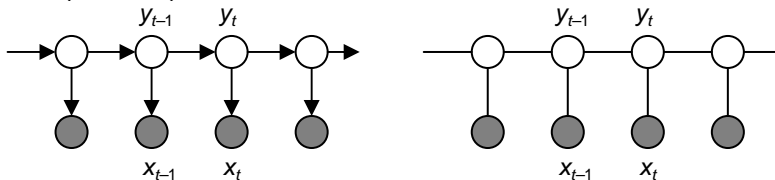
# Potential functions and feature generators I

▶  $\Pr(y|x) = \frac{1}{Z(x)} \prod_{c \in C} \phi_c(x, y_c) =$   
 $\frac{1}{Z(x)} \exp \left( \sum_{c \in C} \psi_c(x, y_c) \right)$

- ▶ Write (log) potential function  $\psi$  as

$$\psi_c(x, y_c) = \sum_k \beta_k f_k(x, y_c; c) = \beta' F(x, y_c; c)$$

- ▶  $F$  is a feature (vector) generator
- ▶  $c$  is a clique identifier; e.g., in case of a linear chain,  $c = (t - 1, t)$



## Potential functions and feature generators II

- ▶  $k$  is a feature identifier
- ▶ One feature may consider only  $t$ ,  $y_t$  and  $x_t$ , and emit a number reflecting the compatibility between state  $y_t$  and observed word output  $x_t$ , or topic  $y_t$  and observed document  $x_t$
- ▶ Another feature may consider only  $t$ ,  $y_{t-1}$  and  $y_t$ , and emit a number reflecting the belief that a  $y_{t-1} \rightarrow y_t$  can occur
- ▶ Have a weight  $\beta_k$  for each  $k$
- ▶ Given fixed  $\beta$ , **inference** finds the most likely  $y \in \mathcal{Y}$  (will see LP and QP relaxations soon)
- ▶ During **training** we fit  $\beta$
- ▶ Training often uses inference as a subroutine

# Training log-linear models

- ▶ Our goal is to find  $\max_{\beta} L(\beta)$  where

$$\begin{aligned}L(\beta) &= \sum_{i=1}^n \log \Pr(y_i | x_i) \\&= \sum_{i=1}^n \left[ \sum_c \beta' F(x_i, y_{i,c}; c) - \log Z(x_i) \right] \\ \frac{\partial L}{\partial \beta} &= \sum_{i=1}^n \left[ \sum_c F(x_i, y_{i,c}; c) - \frac{\partial}{\partial \beta} \log Z(x_i) \right] \\&= \sum_{i=1}^n \left[ \sum_c (F(x_i, y_{i,c}; c) - E_{Y|x_i} F(x_i, Y_c; c)) \right]\end{aligned}$$

- ▶ At optimum  $F(x_i, y_{i,c}; c) = E_{Y|x_i} F(x_i, Y_c; c)$
- ▶ Once we have a procedure for **the difficult part**, we can easily use gradient-based methods to optimize for  $\beta$
- ▶ For Markov chains, can use Viterbi decoding ▶ HW



# Inference for Markov networks: LP relaxation I

- ▶ Labeling to minimize energy

$$\min_{y(V)} \left[ \sum_{u \in V} c(u, y(u)) + \sum_{(u,v) \in E} w(u, v) \Gamma(y(u), y(v)) \right]$$

- ▶  $c$  models local information at  $u$
- ▶  $\Gamma$  models compatibility of neighboring labels
- ▶ For two labels, sometimes easy via mincut

# Inference for Markov networks: LP relaxation II

- ▶ Integer program formulation for  $\Gamma(y, y') = \llbracket y \neq y' \rrbracket$

$$\begin{aligned} \min \quad & \sum_{e \in E} w_e z_e + \sum_{u \in V, y \in \mathcal{Y}} c(u, y) x_{uy} \\ \text{subject to} \quad & \sum_{y \in \mathcal{Y}} x_{uy} = 1 && \forall u \in V \\ & z_e = \frac{1}{2} \sum_y z_{ey} && \forall e \in E \quad \text{▶ HW} \\ & z_{ey} \geq x_{uy} - x_{vy} && \forall e = (u, v), \forall y \\ & z_{ey} \geq x_{vy} - x_{uy} && \forall e = (u, v), \forall y \\ & x_{uy} \in \{0, 1\} && \forall u \in V, y \in \mathcal{Y} \end{aligned}$$

- ▶ Can round to a factor of 2

# Inference for Markov networks: QP relaxation I

- ▶  $\theta_{s;j}$  compatibility of node  $s$  with label  $j$
- ▶  $\theta_{s;j;t,k}$  compatibility of edge  $(s, t)$  with labels  $(j, k)$

$$\max \sum_{s,j} \theta_{s;j} \mathbb{I}[y(s) = j] + \sum_{s,j;t,k} \theta_{s;j;t,k} \mathbb{I}[y(s) = j] \mathbb{I}[y(t) = k]$$

$$\text{subject to } \sum_j \mathbb{I}[y(s) = j] = 1$$

## Inference for Markov networks: QP relaxation II

- ▶ Relaxation of  $\llbracket y(s) = j \rrbracket$  to  $\mu(s, j)$ :

$$\begin{aligned} \max \quad & \sum_{s,j} \theta_{s,j} \mu(s, j) + \sum_{s,j;t,k} \theta_{s,j;t,k} \mu(s, j) \mu(t, k) \\ \text{subject to} \quad & \sum_j \mu(s, j) = 1 \quad \forall s \\ & 0 \leq \mu(s, j) \leq 1 \quad \forall s, j \end{aligned}$$

- ▶ No integrality gap (proof via probabilistic method)
- ▶ Limitation: efficient QP solvers work only if  $\Theta = \{\theta_{s,j;t,k}\}$  is negative definite
- ▶ If we try to make  $\Theta$  negative definite, gap develops between QP optimum and label assignment

## Concluding remarks

- ▶ Graphs and probability: at the intersection of statistics and classic AI knowledge representation
- ▶ Two computation paradigms: pushing weights along edges (Pagerank etc.) and computing local distributions or belief measures (graphical models)
- ▶ Lots of difficult problems!
  - ▶ Modeling
  - ▶ Optimization
  - ▶ Performance on real computers on large data
- ▶ Real applications both a challenge and an opportunity