## Math/Stat 2300 Discrete Probabilistic Modeling

from text A First Course in Mathematical Modeling, Giordano, Fox, Horton, Weir, 2009.

## Markov Chains

A Markov chain is a process in which there are the same finite number of states or outcomes that can be occupied at any given time.

**Example**. Consider a rural town where the residents only purchase two brands of cereals: O's and W's.



The diagram gives the probability of what a resident will purchase next.

	O's	W's
O's	0.6	0.4
W's	0.3	0.7

**Example** (Voting Tendencies)

		Next State		
		Republicans	Democrats	Independents
	Republicans	0.75	0.05	0.20
Present	Democrats	0.20	0.60	0.20
State	Independents	0.40	0.20	0.40



## Model:

Let

$R_n$	=	percentage of voters to vote Republican in period $n$
$D_n$	=	percentage of voters to vote Democratic in period $n$
$I_n$	=	percentage of voters to vote Independent in period $\boldsymbol{n}$

$$R_{n+1} = 0.75R_n + 0.20D_n + 0.40I_n$$
  

$$D_{n+1} = 0.05R_n + 0.60D_n + 0.20I_n$$
  

$$I_{n+1} = 0.20R_n + 0.20D_n + 0.40I_n$$

A **Markov Chain** is a process consisting of a sequence of events with the following properties:

- An event has a finite number of outcomes, called states. The process is always in one of these states.
- At each stage or period of the process, a particular outcome can transition from its present state to any other state or itself.
- The probability of going from one state to another in a single stage represented by a transition matrix for which entries in each row are between 0 and 1; each row sums to one.

## Example.

Consider the pollution in two adjoining lakes in which the only flow is between the lakes. Let  $a_n$  and  $b_n$  be the total amounts of pollution in Lake A and B, respectively, after n years. The following graph gives the two state Markov Chain for lake pollution.



The transition matrix for this Markov chain is

The dynamical system model:

$$a_{n+1} = 0.35a_n + 0.1b_n$$
  
$$b_{n+1} = 0.65a_n + 0.9b_n$$