



# Validity in Choice Logics

A Game-Theoretic Investigation

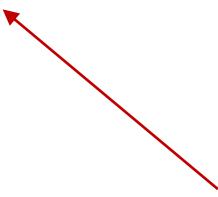


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**Choice logic = Truth + Preferences**

# Choice logic = Classical Logic + Preferences

$$(a \vee b \vee c) \wedge \neg(a \vee b)$$



$F \rightarrowtail G \dots F$  or  $G$ , but preferably  $F$

$$t \wedge (m \rightarrowtail a)$$

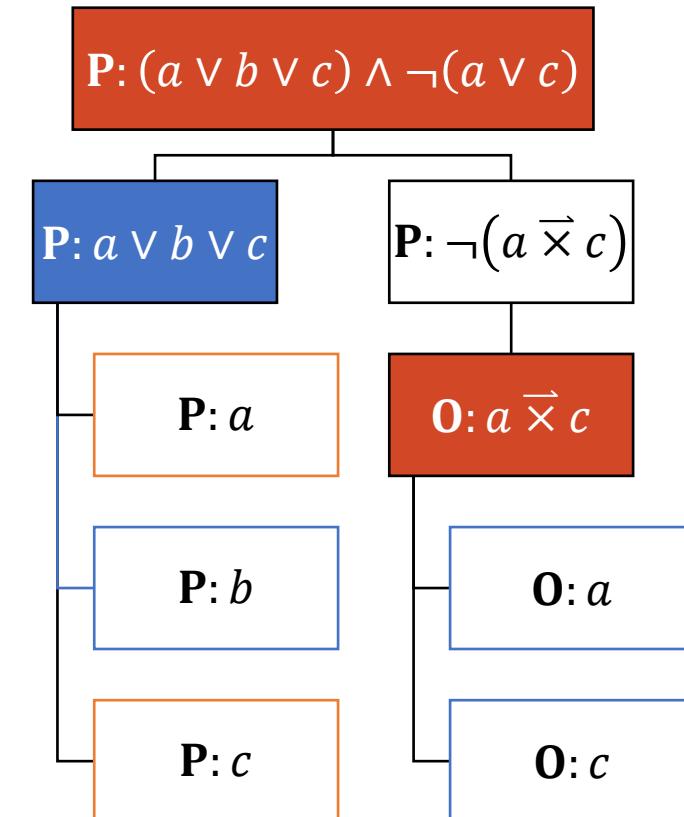
$$(a \rightarrowtail b \rightarrowtail c) \wedge \neg(a \rightarrowtail b)$$

# Hintikka's Semantic Game

- Game between two players, *I* and *You*
- Played over interpretation  $\mathcal{I} \subseteq \text{Var}$  and formula  $F$

$F_1 \vee F_2$	Proponent's choice: continue with $F_1$ or with $F_2$
$F_1 \wedge F_2$	Opponent's choice: continue with $F_1$ or with $F_2$
$\neg G$	game continues with $G$ and a role switch
$p$	Proponent wins if $p \in \mathcal{I}$ Opponent wins if $p \notin \mathcal{I}$

**Example:**  $\mathcal{I} = \{b\}$



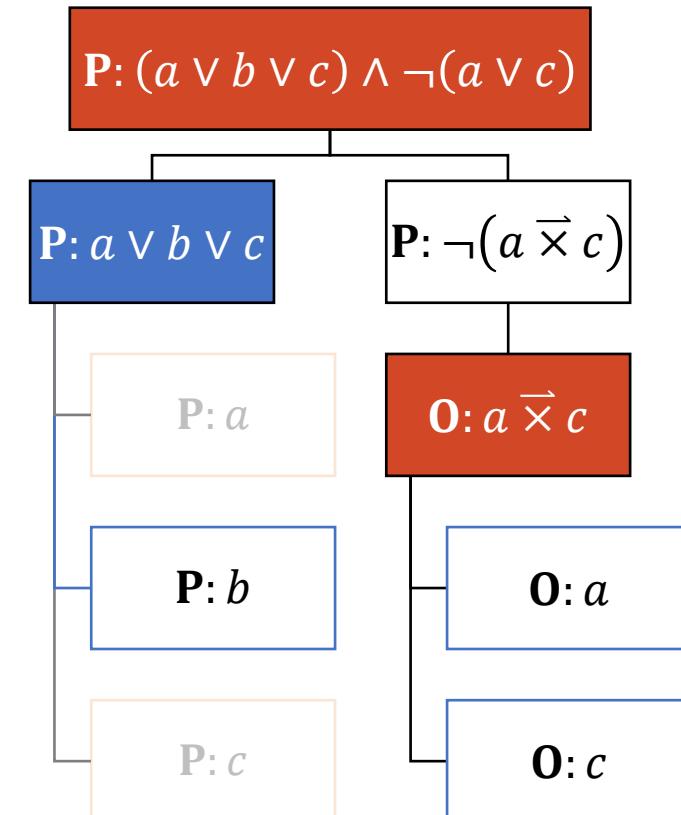
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**Theorem:** *I* have a ws in  $G_{\mathcal{I}}(\mathbf{P}:F)$  iff  $\mathcal{I} \models F$ .

**Example:**  $\mathcal{I} = \{b\}$



# Semantic Game for Choice Logics

- Game between two players, *I* and *You*
- Played over interpretation  $\mathcal{I} \subseteq \text{Var}$  and formula  $F$

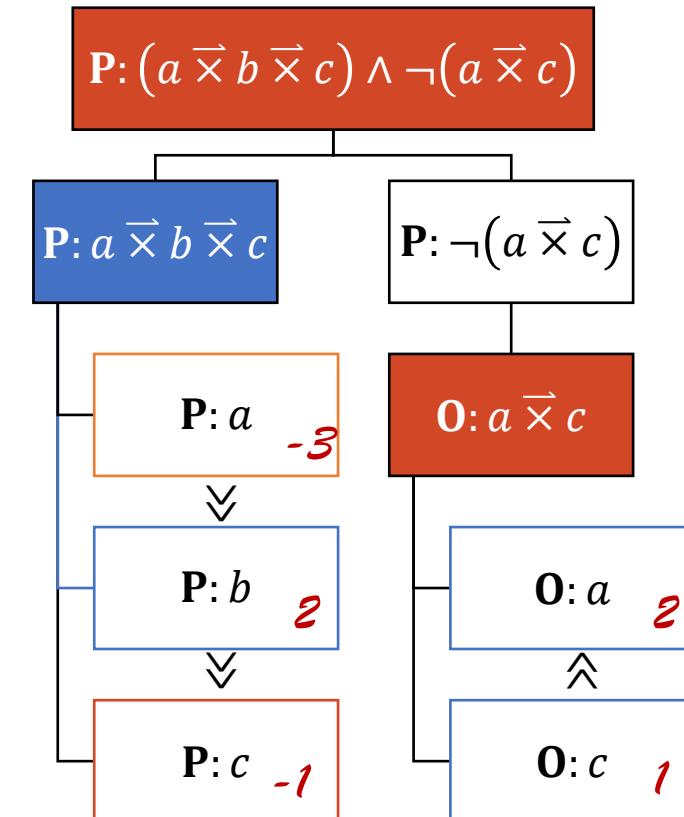
$F_1 \overrightarrow{\times} F_2$  Proponent's choice: continue with  $F_1$  or with  $F_2$   
But: this player prefers  $F_1$

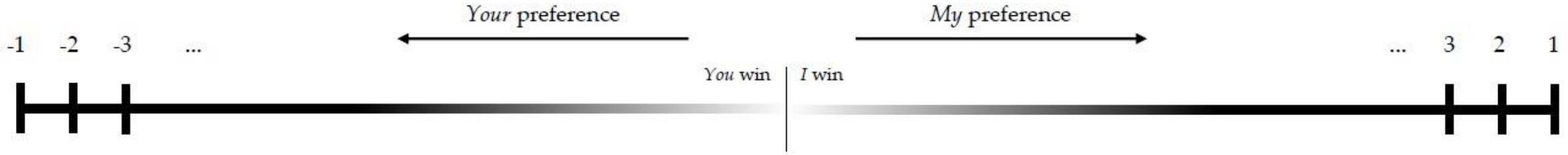
→ *Induces preference relation  $\ll$  on outcomes*

$\delta_{\mathcal{I}}(o)$  P receives payoff  $|\pi_{\ll}(o)|$  if they win  
P receives payoff  $-|\pi_{\ll}(o)|$  if they lose

→ *Payoffs in domain  $Z = \mathbb{Z}^+ \cup \mathbb{Z}^-$*

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- Game between two players,  $I$  and You
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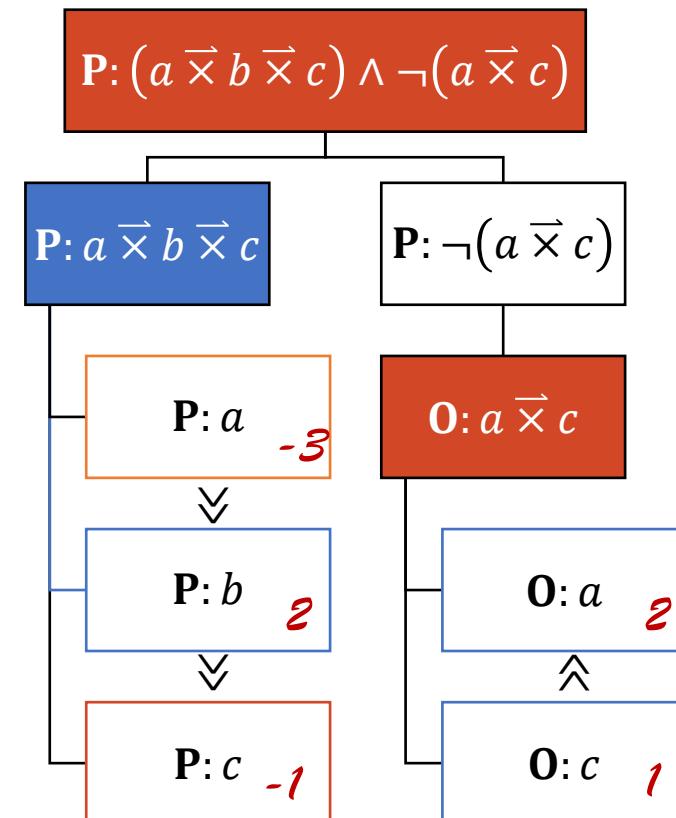
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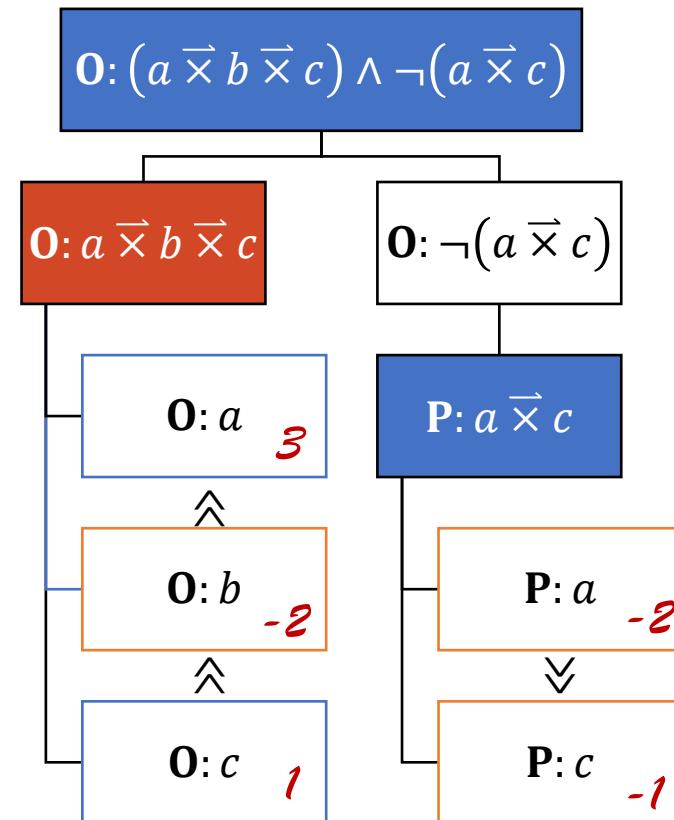
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**Example:**  $\mathcal{I} = \{b\}$

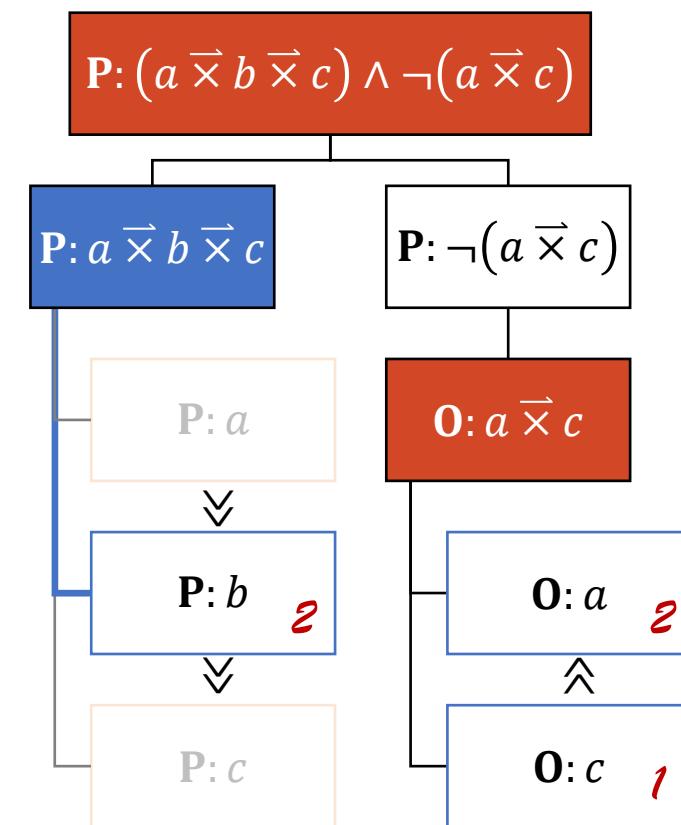


# Strategies, Value and Validity

**Example:**  $\mathcal{I} = \{b\}$



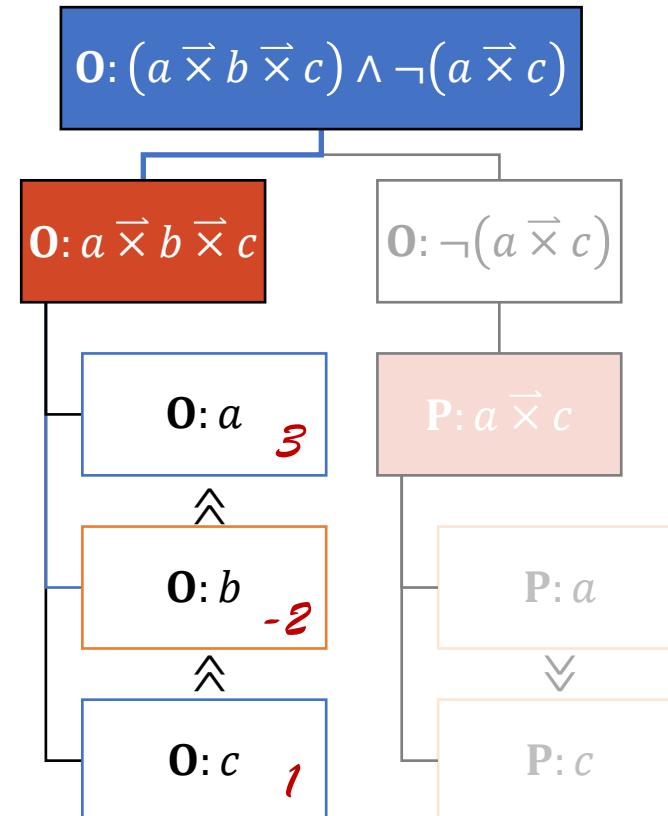
**Example:**  $\mathcal{I} = \{b\}$



→ 2-strategy!

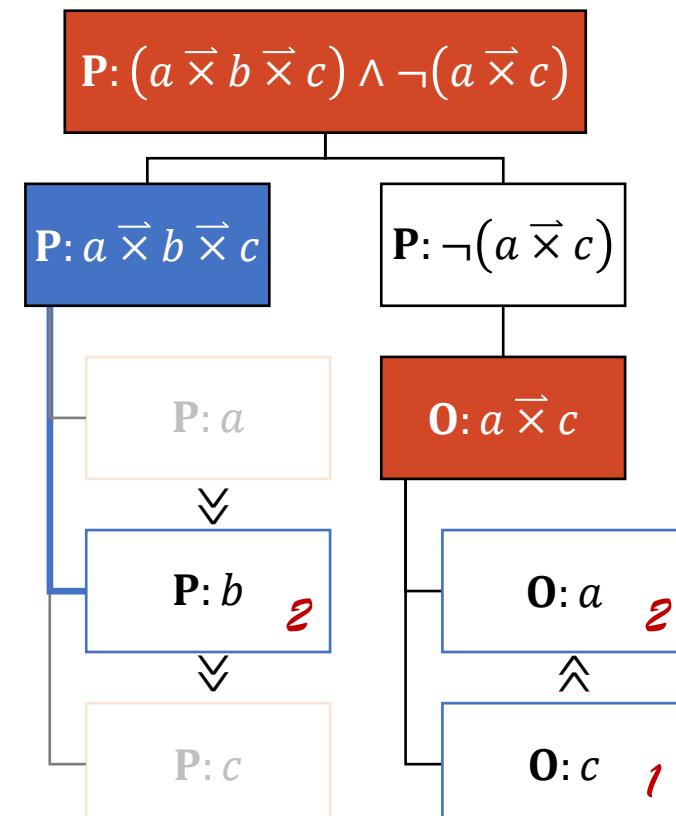
# Strategies, Value and Validity

**Example:**  $\mathcal{I} = \{b\}$



→ -2-strategy!

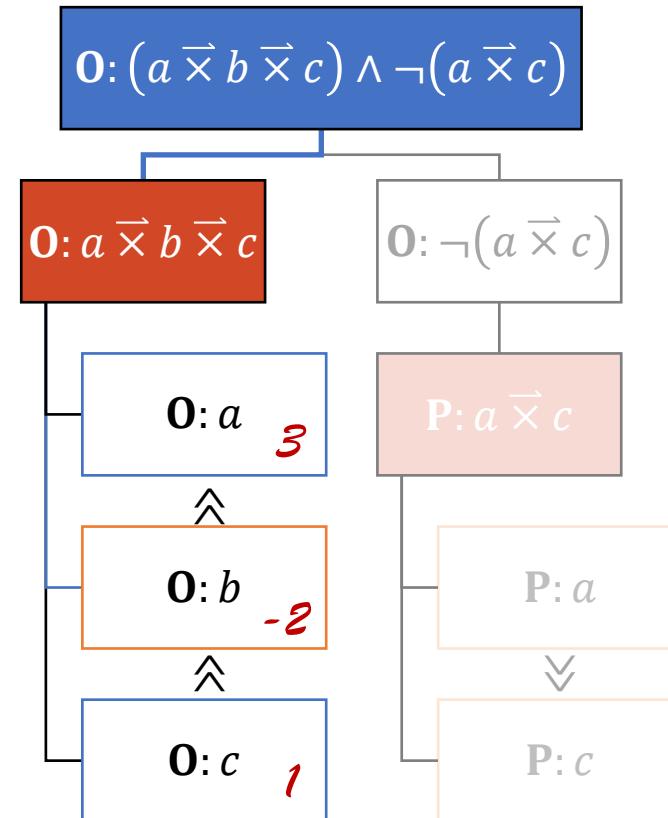
**Example:**  $\mathcal{I} = \{b\}$



→ 2-strategy!

# Strategies, Value and Validity

**Example:**  $\mathcal{J} = \{b\}$



→ -2-strategy!

**Definition:**

$v_{\mathcal{J}}(\mathbf{Q}: F)$  Value/degree of  $\mathbf{Q}: F$  = The maximal  $k$  such that I have a  $k$ -strategy in  $\mathbf{G}_{\mathcal{J}}(\mathbf{Q}: F)$

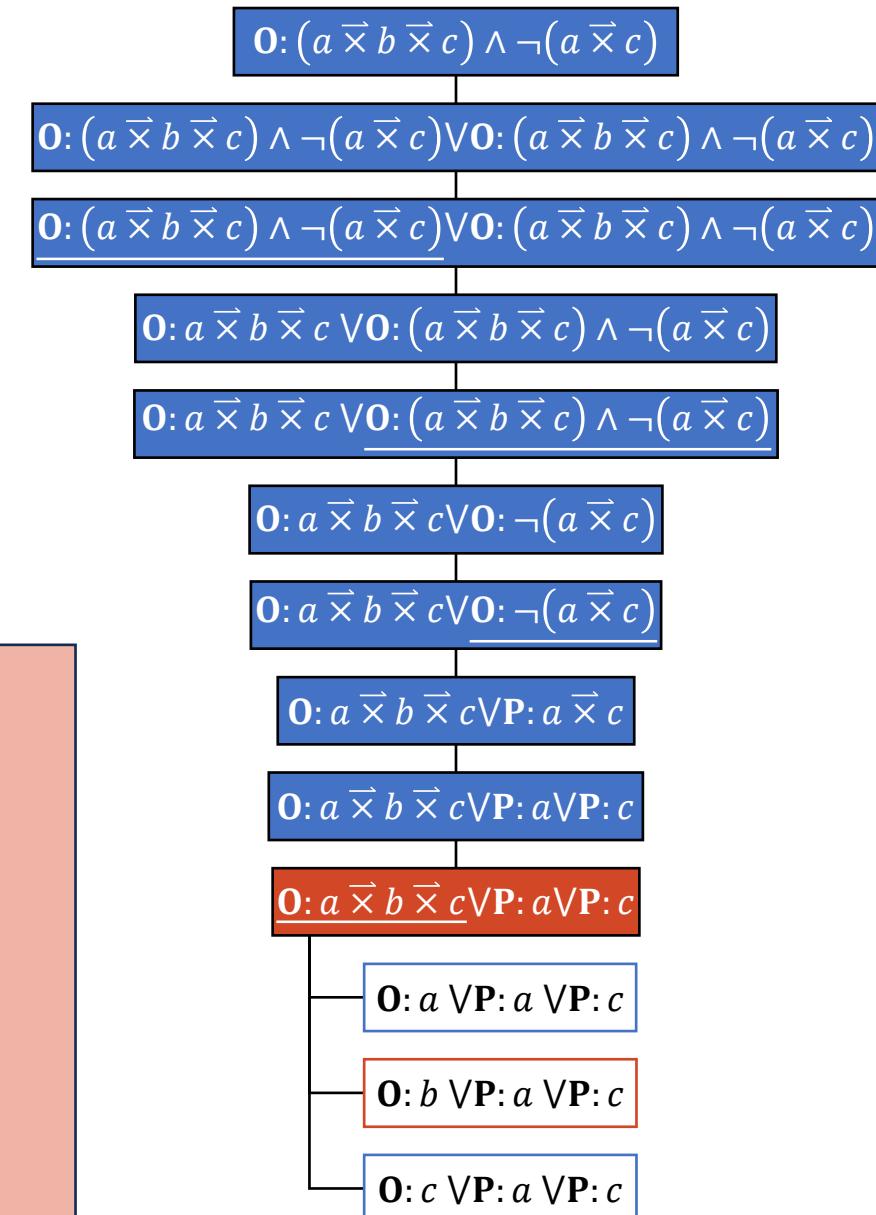
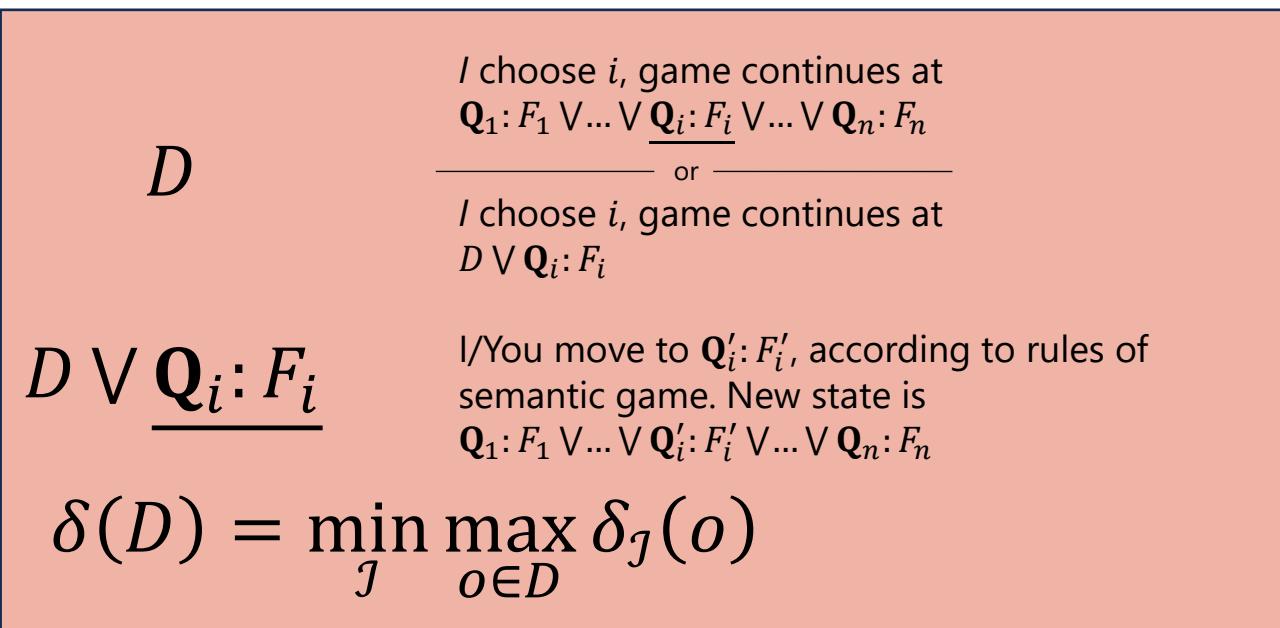
$v(F) = \min_{\mathcal{J}} v_{\mathcal{J}}(\mathbf{P}: F)$  Degree of validity of  $F$

# A Game for Validity

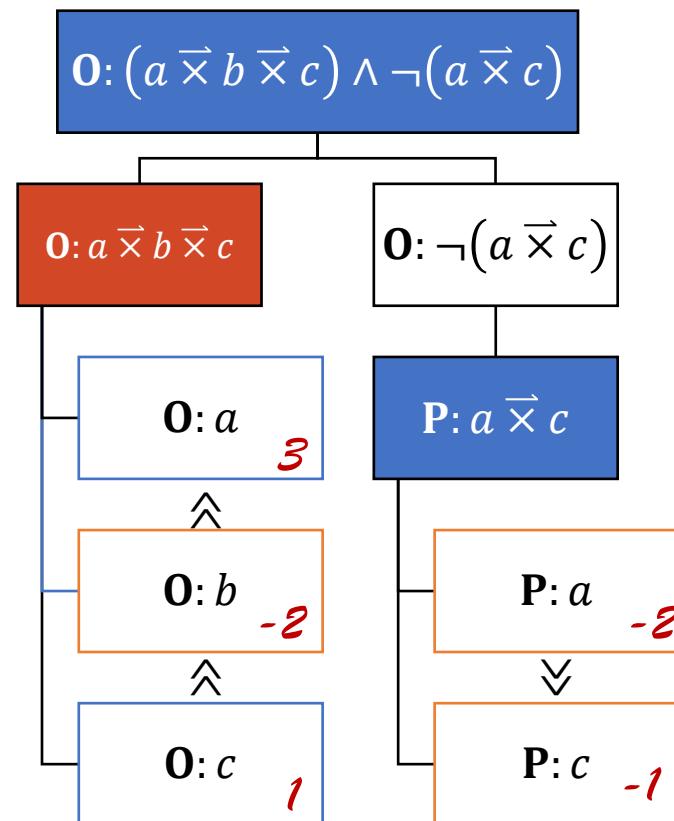
# Provability Game

Idea: play over all models simultaneously

But: I can create back-up copies  
 $\rightarrow$  Game played over disjunctive states  $D = Q_1 : F_1 \vee \dots \vee Q_n : F_n$



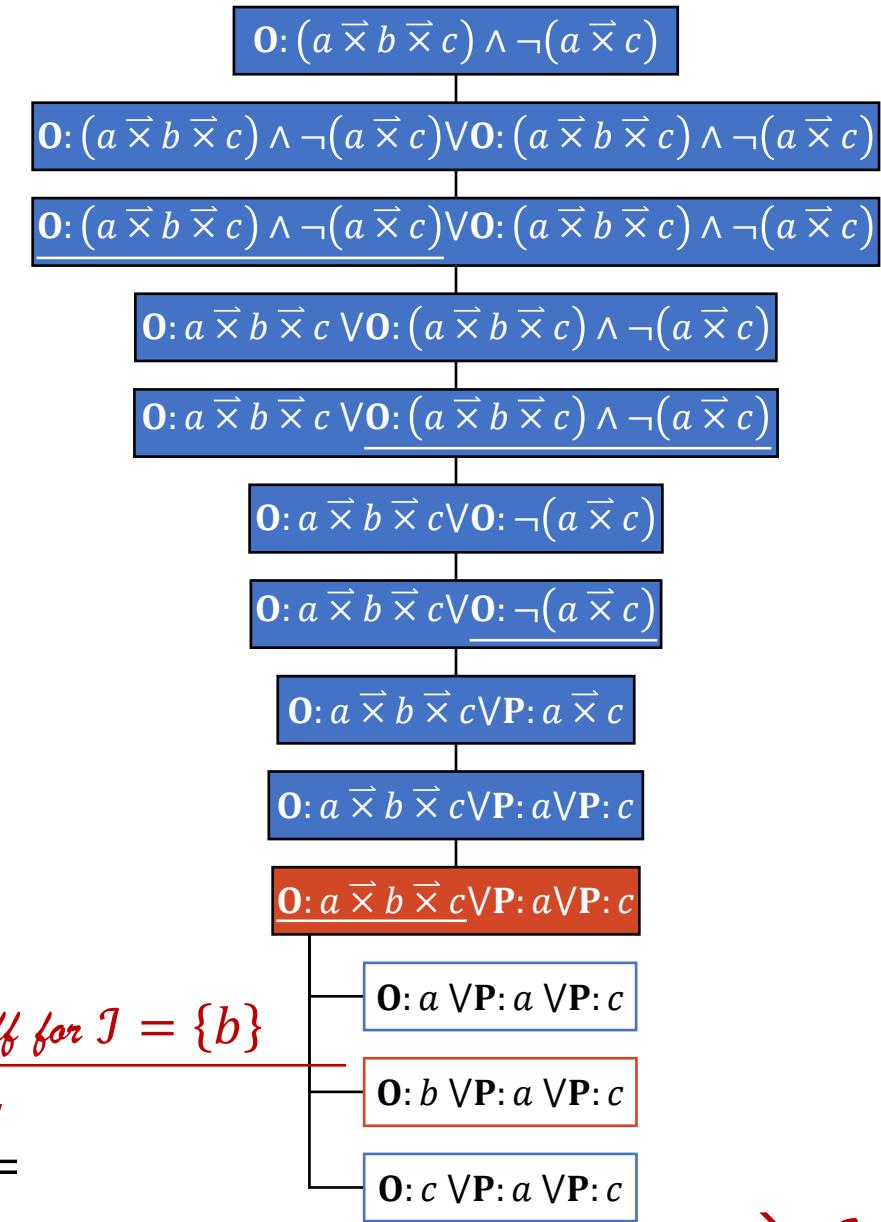
# Provability Game



*Minimal payoff for  $\mathcal{J} = \{b\}$*

$$\delta(\mathbf{O}: b \vee \mathbf{P}: a \vee \mathbf{P}: c) = \min_{\mathcal{J}} \max \{ \delta_{\mathcal{J}}(\mathbf{O}: b), \delta_{\mathcal{J}}(\mathbf{P}: a), \delta_{\mathcal{J}}(\mathbf{P}: c) \} =$$

$$\max \{ \delta_{\{b\}}(\mathbf{O}: b), \delta_{\{b\}}(\mathbf{P}: a), \delta_{\{b\}}(\mathbf{P}: c) \} = \max \{ -2, -2, -1 \} = -2.$$



$\rightarrow -2$ -strategy!

# Adequacy

**Theorem:** The value of the game  $\mathbf{DG}(\mathbf{P}: F)$  is  $v(F)$ , the degree of validity of  $F$ .

# Proof Theory

*My*  $k$ -strategy =  $k$ -proof

$\mathbf{O}: F_1 \vee \dots \vee \mathbf{O}: F_n \vee \mathbf{P}: G_1 \vee \dots \vee \mathbf{P}: G_m$

is written as

$F_1, \dots, F_n \Rightarrow G_1, \dots, G_m$

# Proof system GS for GCL

## Initial Sequents for GS

$\Gamma \Rightarrow \Delta$ , where  $\Gamma$  and  $\Delta$  consist of labeled variables

## Structural Rules

$$\frac{\Gamma, {}_l^k F, {}_l^k F \Rightarrow \Delta}{\Gamma, {}_l^k F \Rightarrow \Delta} (L_c)$$

## Propositional rules

$$\frac{\Gamma, {}_l^k F \Rightarrow \Delta \quad \Gamma, {}_l^k G \Rightarrow \Delta}{\Gamma, {}_l^k (F \vee G) \Rightarrow \Delta} (L_\vee)$$

$$\frac{\Gamma, {}_l^k F \Rightarrow \Delta}{\Gamma, {}_l^k (F \wedge G) \Rightarrow \Delta} (L_\wedge^1)$$

$$\frac{\Gamma, {}_l^k G \Rightarrow \Delta}{\Gamma, {}_l^k (F \wedge G) \Rightarrow \Delta} (L_\wedge^2)$$

$$\frac{\Gamma \Rightarrow {}_l^k F, \Delta}{\Gamma, {}_l^k \neg F \Rightarrow \Delta} (L_\neg)$$

## Choice rules

$$\frac{\Gamma, {}_{l+\text{opt}(G)}^k F \Rightarrow \Delta \quad \Gamma, {}^{k+\text{opt}(F)}_l G \Rightarrow \Delta}{\Gamma, {}_l^k (F \vec{\times} G) \Rightarrow \Delta} (L_{\vec{\times}}) \quad \frac{\Gamma \Rightarrow {}_l^{k+\text{opt}(G)} F, \Delta}{\Gamma \Rightarrow {}_l^k (F \vec{\times} G), \Delta} (R_{\vec{\times}}^1)$$

$$\frac{\Gamma \Rightarrow {}_{l+\text{opt}(G)}^k G, \Delta}{\Gamma \Rightarrow {}_l^k (F \vec{\times} G), \Delta} (R_{\vec{\times}}^2)$$

$$\frac{\Gamma \Rightarrow {}_l^k F, {}_l^k F, \Delta}{\Gamma \Rightarrow {}_l^k F, \Delta} (R_c)$$

$$\frac{\Gamma \Rightarrow {}_l^k F, \Delta}{\Gamma \Rightarrow {}_l^k (F \vee G), \Delta} (R_\vee^1)$$

$$\frac{\Gamma \Rightarrow {}_l^k G, \Delta}{\Gamma \Rightarrow {}_l^k (F \vee G), \Delta} (R_\vee^2)$$

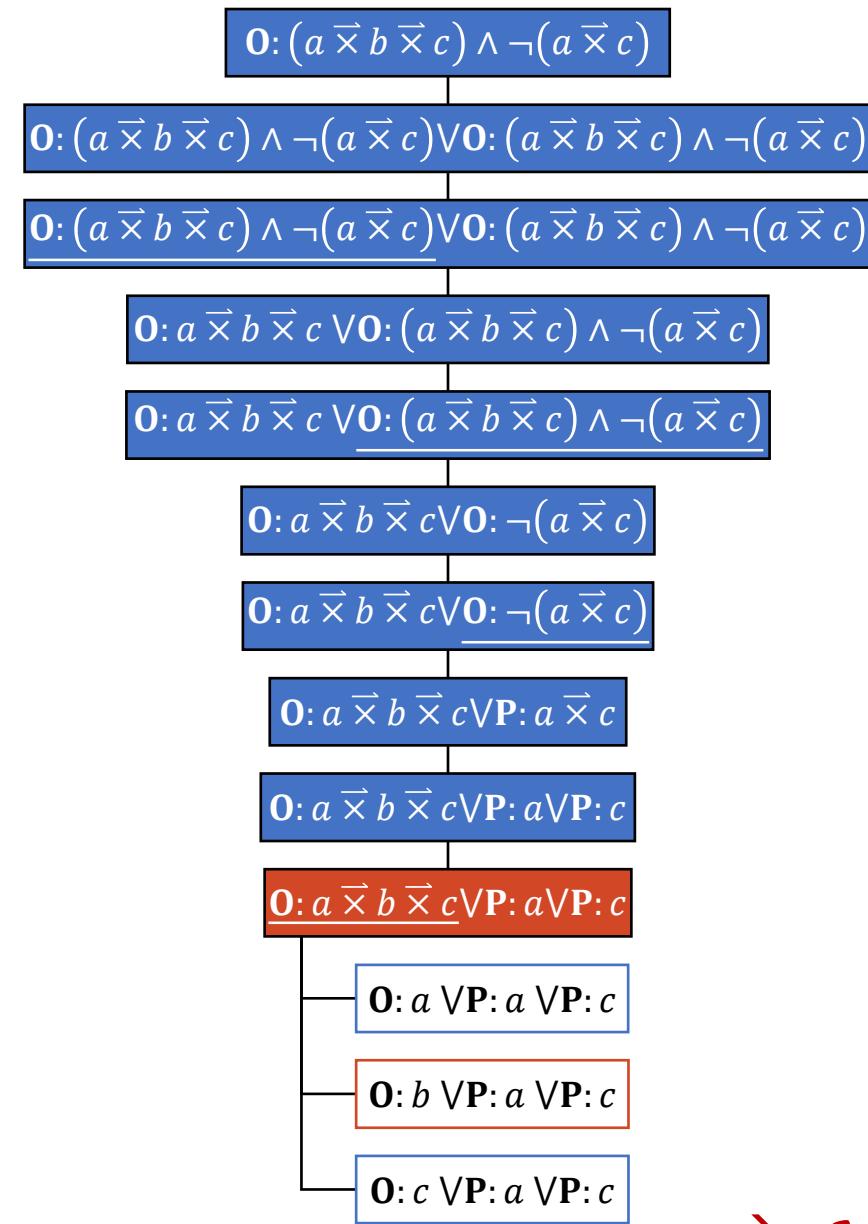
$$\frac{\Gamma \Rightarrow {}_l^k F, \Delta \quad \Gamma \Rightarrow {}_l^k G, \Delta}{\Gamma \Rightarrow {}_l^k (F \wedge G), \Delta} (R_\wedge)$$

$$\frac{\Gamma, {}_l^k F \Rightarrow \Delta}{\Gamma \Rightarrow {}_l^k \neg F, \Delta} (R_\neg)$$

# Example

$$\begin{array}{c}
 \frac{\frac{1}{3}a \Rightarrow \frac{2}{1}a, \frac{1}{2}c \quad \frac{2}{2}b \Rightarrow \frac{2}{1}a, \frac{1}{2}c}{\frac{2}{1}(a \vec{\times} b) \Rightarrow \frac{2}{1}a, \frac{1}{2}c} \stackrel{(L_{\vec{\times}})}{} \quad \frac{3}{1}c \Rightarrow \frac{2}{1}a, \frac{1}{2}c \stackrel{(L_{\vec{\times}})}{} \\
 \frac{\frac{1}{1}((a \vec{\times} b) \vec{\times} c) \Rightarrow \frac{2}{1}a, \frac{1}{2}c}{\frac{1}{1}((a \vec{\times} b) \vec{\times} c) \Rightarrow \frac{2}{1}a, \frac{1}{1}(a \vec{\times} c)} \stackrel{(R_{\vec{\times}}^2)}{} \\
 \frac{\frac{1}{1}((a \vec{\times} b) \vec{\times} c) \Rightarrow \frac{1}{1}(a \vec{\times} c), \frac{1}{1}(a \vec{\times} c)}{\frac{1}{1}((a \vec{\times} b) \vec{\times} c) \Rightarrow \frac{1}{1}(a \vec{\times} c)} \stackrel{(R_{\vec{\times}}^1)}{} \\
 \frac{\frac{1}{1}((a \vec{\times} b) \vec{\times} c) \Rightarrow \frac{1}{1}(a \vec{\times} c)}{\frac{1}{1}((a \vec{\times} b) \vec{\times} c), \frac{1}{1}(\neg(a \vec{\times} c)) \Rightarrow} \stackrel{(R_C)}{} \\
 \frac{\frac{1}{1}((a \vec{\times} b) \vec{\times} c), \frac{1}{1}(((a \vec{\times} b) \vec{\times} c) \wedge \neg(a \vec{\times} c)) \Rightarrow}{\frac{1}{1}(((a \vec{\times} b) \vec{\times} c) \wedge \neg(a \vec{\times} c)), \frac{1}{1}(((a \vec{\times} b) \vec{\times} c) \wedge \neg(a \vec{\times} c)) \Rightarrow} \stackrel{(L_{\wedge})}{=} \\
 \frac{\frac{1}{1}(((a \vec{\times} b) \vec{\times} c) \wedge \neg(a \vec{\times} c)) \Rightarrow}{\frac{1}{1}(((a \vec{\times} b) \vec{\times} c) \wedge \neg(a \vec{\times} c)) \Rightarrow} \stackrel{(L_C)}{=}
 \end{array}$$

→ -2-proof!



→ -2-strategy!

# Proof system GS\* for GCL

## Initial Sequents

$\Gamma \Rightarrow \Delta$ , where  $\Gamma$  and  $\Delta$  consist of labeled variables

## Propositional rules

$$\frac{\Gamma, {}_l^k F \Rightarrow \Delta \quad \Gamma, {}_l^k G \Rightarrow \Delta}{\Gamma, {}_l^k(F \vee G) \Rightarrow \Delta} (L_{\vee})$$

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$$\frac{\Gamma, {}_l^k F \Rightarrow \Delta}{\Gamma \Rightarrow {}_l^k \neg F, \Delta} (R_{\neg})$$

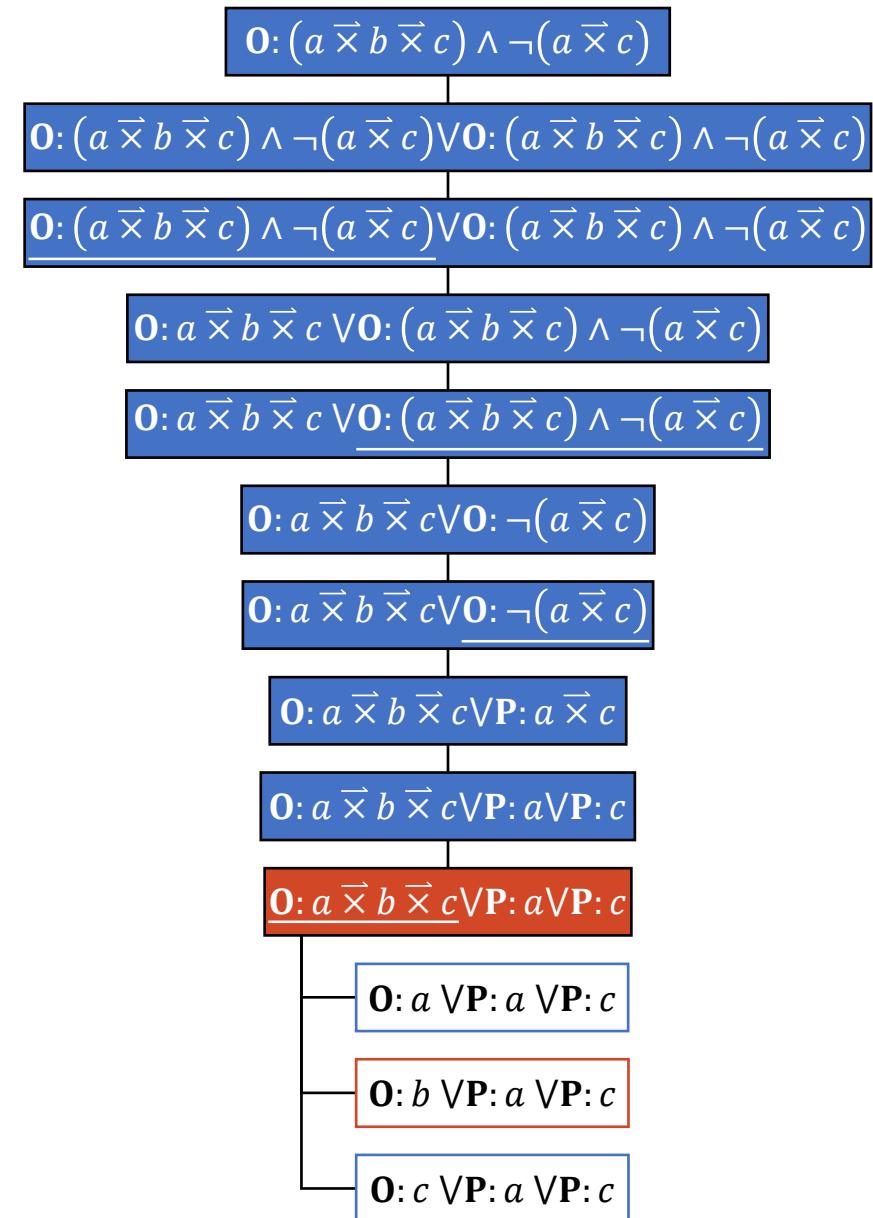
## Choice rules

$$\frac{\Gamma, {}_{l+\text{opt}(G)}^k F \Rightarrow \Delta \quad \Gamma, {}^{k+\text{opt}(F)}_l G \Rightarrow \Delta}{\Gamma, {}_l^k(F \vec{\times} G) \Rightarrow \Delta} (L_{\vec{\times}})$$

$$\frac{\Gamma \Rightarrow {}^{k+\text{opt}(G)}_l F, {}_{l+\text{opt}(F)}^k G, \Delta}{\Gamma \Rightarrow {}_l^k(F \vec{\times} G), \Delta} (R_{\vec{\times}})$$

# Example

$$\begin{array}{c}
 \frac{\frac{1}{3}a \Rightarrow \frac{2}{1}a, \frac{1}{2}d \quad \frac{2}{2}b \Rightarrow \frac{2}{1}a, \frac{1}{2}d}{\frac{2}{1}(a \vec{\times} b) \Rightarrow \frac{2}{1}a, \frac{1}{2}d} \stackrel{(L_{\vec{\times}})}{} \quad \frac{3}{1}c \Rightarrow \frac{2}{1}a, \frac{1}{2}d \\
 \frac{\frac{1}{1}((a \vec{\times} b) \vec{\times} c) \Rightarrow \frac{2}{1}a, \frac{1}{2}d}{\frac{1}{1}((a \vec{\times} b) \vec{\times} c) \Rightarrow \frac{1}{1}(a \vec{\times} d)} \stackrel{(R_{\vec{\times}})}{} \\
 \frac{\frac{1}{1}((a \vec{\times} b) \vec{\times} c), \frac{1}{1}\neg(a \vec{\times} d) \Rightarrow}{\frac{1}{1}(((a \vec{\times} b) \vec{\times} c) \wedge \neg(a \vec{\times} d)) \Rightarrow} \stackrel{(L_{\wedge})}{}
 \end{array}$$



# Conclusion

## Conclusion

- Game semantics for choice logic
- Negation behaves better
- Same complexity
- Provability game for graded validity
- Sequent-style proof system

## Future work

- Preferred model entailment
- Why classical logic?
- Incomparability of outcomes

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# Fun Facts

# Negation in Choice Logics

	QCL	PQCL	GCL*
degree of $\neg F$ depends only on the degree of $F$	✓		✓
$F \vee \neg F$ valid	✓	✓	✓
$F \wedge \neg F$ unsat	✓		✓
$F$ has same degree as $\neg\neg F$		✓	✓
De Morgan's laws	✓	✓	✓
degree semantics	✓	✓	→ SOON

\*in GCL, degree=value

# Negation in QCL and PQCL

**Example:**  $\neg(a \rightarrow b)$  is equivalent to  $\neg(a \vee b)$  in QCL and to  $\neg a \rightarrow \neg b$  in PQCL.

	QCL/PQCL $a \rightarrow b$	$\neg(a \rightarrow b)$ QCL	$\neg(a \rightarrow b)$ PQCL
$\mathcal{I} = \emptyset$	-1	1	1
$\mathcal{I} = \{a\}$	2	-1	1
$\mathcal{I} = \{b\}$	1	-1	2
$\mathcal{I} = \{a, b\}$	1	-1	-1

# Degree semantics QCL

$$\text{opt}(a) = 1$$

$$\text{opt}(\neg F) = 1$$

$$\text{opt}(F \wedge G) = \max\{\text{opt}(F), \text{opt}(G)\}$$

$$\text{opt}(F \vee G) = \max\{\text{opt}(F), \text{opt}(G)\}$$

$$\text{opt}(F \overrightarrow{\times} G) = \text{opt}(F) + \text{opt}(G)$$

$$\deg_J(a) = \begin{cases} 1 & \text{if } a \in J, \\ -1 & \text{if } a \notin J. \end{cases}$$

$$\deg_J(\neg F) = \begin{cases} 1 & \text{if } \deg_J(\neg F) = -1, \\ -1 & \text{if } \deg_J(\neg F) \in \mathbb{Z}^+. \end{cases}$$

$$\deg_J(F \wedge G) = \min_{\leq} \{\deg_J(F), \deg_J(G)\}$$

$$\deg_J(F \vee G) = \max_{\leq} \{\deg_J(F), \deg_J(G)\}$$

$$\deg_J(F \overrightarrow{\times} G) = \begin{cases} \deg_J(F) & \text{if } \deg_J(F) \in \mathbb{Z}^+, \\ \text{opt}(F) + \deg_J(G) & \text{if } \deg_J(F) = -1 \text{ and } \deg_J(G) \in \mathbb{Z}^+, \\ -1 & \text{else.} \end{cases}$$

# Degree semantics GCL

$$\text{opt}^{\mathcal{G}}(a) = 1$$

$$\text{opt}^{\mathcal{G}}(\neg F) = \text{opt}^{\mathcal{G}}(F)$$

$$\text{opt}^{\mathcal{G}}(F \wedge G) = \max\{\text{opt}^{\mathcal{G}}(F), \text{opt}^{\mathcal{G}}(G)\}$$

$$\text{opt}^{\mathcal{G}}(F \vee G) = \max\{\text{opt}^{\mathcal{G}}(F), \text{opt}^{\mathcal{G}}(G)\}$$

$$\text{opt}^{\mathcal{G}}(F \vec{\times} G) = \text{opt}^{\mathcal{G}}(F) + \text{opt}^{\mathcal{G}}(G)$$

$$\deg_{\mathcal{I}}^{\mathcal{G}}(a) = \begin{cases} 1 & \text{if } a \in \mathcal{I}, \\ -1 & \text{if } a \notin \mathcal{I}. \end{cases}$$

$$\deg_{\mathcal{I}}^{\mathcal{G}}(\neg F) = -\deg_{\mathcal{I}}^{\mathcal{G}}(F)$$

$$\deg_{\mathcal{I}}^{\mathcal{G}}(F \wedge G) = \min_{\leq} \{\deg_{\mathcal{I}}^{\mathcal{G}}(F), \deg_{\mathcal{I}}^{\mathcal{G}}(G)\}$$

$$\deg_{\mathcal{I}}^{\mathcal{G}}(F \vee G) = \max_{\leq} \{\deg_{\mathcal{I}}^{\mathcal{G}}(F), \deg_{\mathcal{I}}^{\mathcal{G}}(G)\}$$

$$\deg_{\mathcal{I}}^{\mathcal{G}}(F \vec{\times} G) = \begin{cases} \deg_{\mathcal{I}}^{\mathcal{G}}(F) & \text{if } \deg_{\mathcal{I}}^{\mathcal{G}}(F) \in \mathbb{Z}^+, \\ \text{opt}^{\mathcal{G}}(F) + \deg_{\mathcal{I}}^{\mathcal{G}}(G) & \text{if } \deg_{\mathcal{I}}^{\mathcal{G}}(F) \in \mathbb{Z}^-, \deg_{\mathcal{I}}^{\mathcal{G}}(G) \in \mathbb{Z}^+, \\ \deg_{\mathcal{I}}^{\mathcal{G}}(F) - \text{opt}^{\mathcal{G}}(G) & \text{else.} \end{cases}$$

**Theorem:** For every  $F$ ,

$$v_{\mathcal{I}}(\mathbf{P}: F) = \deg_{\mathcal{I}}^{\mathcal{G}}(F)$$

$$v_{\mathcal{I}}(\mathbf{O}: F) = -\deg_{\mathcal{I}}^{\mathcal{G}}(F)$$

# Preferred models

**Theorem:** Let  $\mathcal{I}$  be a preferred model of  $F$  and let  $k$  be the value of  $\mathbf{DG}(\mathbf{O}:F)$ . Then  $k = -\deg_{\mathcal{I}}^{\mathcal{G}}(F)$  and a preferred model of  $F$  can be extracted from *Your k-strategy* or *My optimal strategy* in  $\mathbf{DG}(\mathbf{O}:F)$ ,

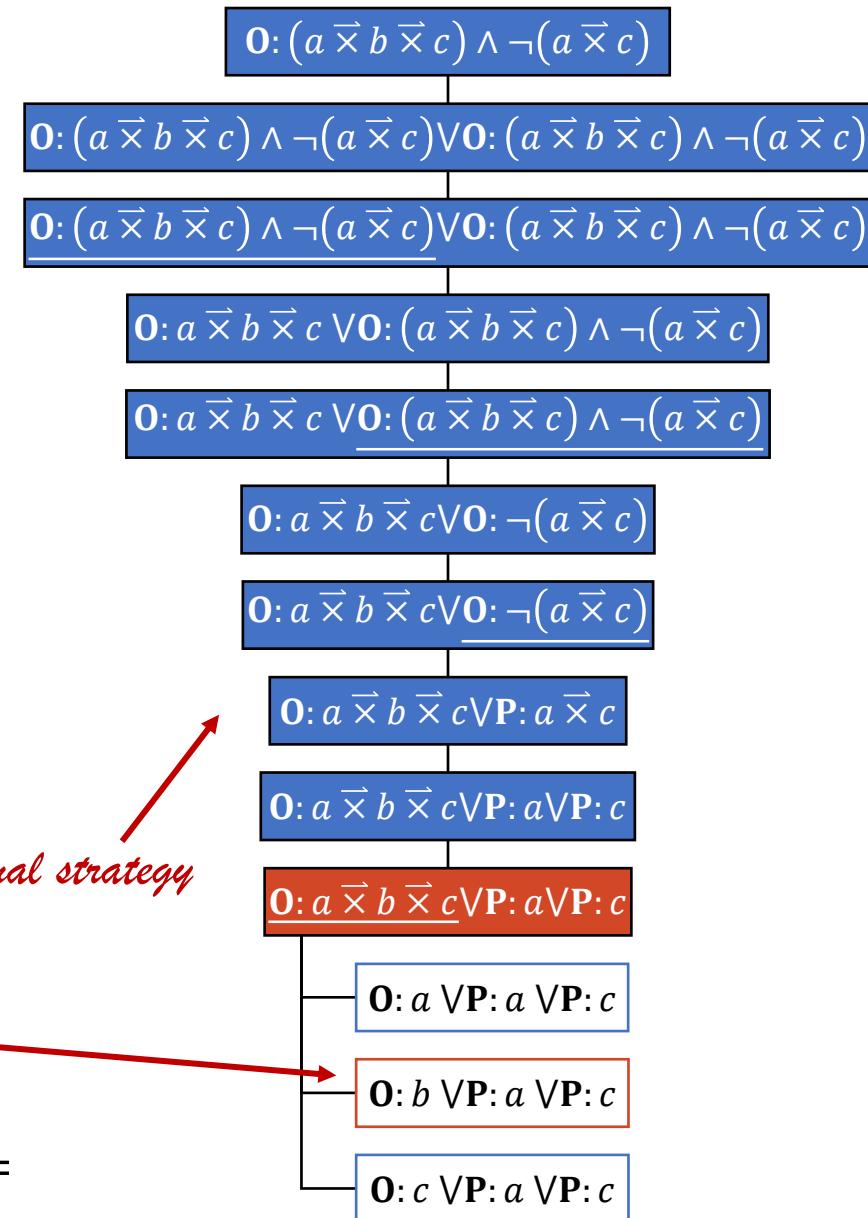
# Example

$\{b\}$  is a preferred model of  $(a \vec{x} b \vec{x} c) \wedge \neg(a \vec{x} c)$  with value 2.

*Minimum here*

$$\delta(\mathbf{O}: b \vee \mathbf{P}: a \vee \mathbf{P}: c) = \min_J \max\{\delta_J(\mathbf{O}: b), \delta_J(\mathbf{P}: a), \delta_J(\mathbf{P}: c)\} =$$

$$\max\{\delta_{\{b\}}(\mathbf{O}: b), \delta_{\{b\}}(\mathbf{P}: a), \delta_{\{b\}}(\mathbf{P}: c)\} = \max\{-2, -2, -1\} = -2.$$



# cut

The following degree-version of cut does not hold:

$$\frac{\nu(D \vee P : F) \sqsupseteq k \quad \nu(D \vee O : F) \sqsupseteq k}{\nu(D) \sqsupseteq k}$$

**Example:**  $\nu(O : T \vee O : T \vec{x} \perp) \sqsupseteq -2$  and  $\nu(O : T \vee P : T \vec{x} \perp) \sqsupseteq -2$ ,  
but  $\nu(O : T) = -1$ .

# cut

There is no function  $f$  such that:

$$\frac{v(D \vee P : F) = k \quad v(D \vee O : F) = l}{v(D) = f(k, l)}$$

**Example:**

$$v(O : T \vee O : T \xrightarrow{\times} \perp) = v(V O : T \xrightarrow{\times} \perp \vee O : T \xrightarrow{\times} \perp) = -2 \text{ and}$$
$$v(O : T \vee P : T \xrightarrow{\times} \perp) = v(V O : T \xrightarrow{\times} \perp \vee P : T \xrightarrow{\times} \perp) = 2, \text{ but}$$

$$v(O : T) = -1 \neq -2 = v(O : T \xrightarrow{\times} \perp)$$

# Complexity results

- DEGCHECKNG: given a disjunctive state  $D$  and  $k \in \mathbb{Z}$ , is  $\nu(D) \sqsupseteq k$ ?  
- coNP-complete
- DEGCHECKNGINIT: given an elementary disjunctive state  $D$  and  $k \in \mathbb{Z}$ , is  $\nu(D) \sqsupseteq k$ ? - in P
- PMCHECKING: given a formula  $F$  and an interpretation  $\mathcal{I}$ , is  $\mathcal{I}$  a preferred model of  $F$ ? - coNP-complete for QCL and GCL
- PMCONTAINMENT: given a GCL-formula  $F$  and a variable  $a$ , is there a preferred model  $\mathcal{I}$  of  $F$  such that  $a \in \mathcal{I}$ ? -  $\Theta_2^P$ -complete for QCL and GCL