

### Final exam preparation

- Go over all the homework, sample, and midterm questions.
- Attempt all the questions in this handout.
- There will be no calculators or any other aids allowed for the final exam.

### Final exam topics

1. Root finding (chap 1, chap 2.7.1): bisection method – fixed point iterations – Newton’s method – secant method – estimating error...
2. Interpolation (chap 3): Lagrange interpolation formula, Newton’s differences formula, error estimates, Chebychev polynomials...
3. Integration/differentiation (chap 5): finite differences; integration: basic formulas, Romberg, Legendre polynomials; Gaussian quadrature, adaptive quadrature, error estimates...
4. ODE’s (chap 6, chap 7.1): basic methods; local/global truncation error; variable step-size methods; multi-step methods; stability.
5. Data fitting (chap 4): overdetermined systems; least squares; nonlinear fitting, Gauss-Newton method.

### Additional sample questions

1. A bisection method The bisection method is applied to the function  $y = (x - 1)(x - 3)(x - 4)$ . The initial interval used for the method is  $[a, b] = [0, 5]$ .
  - (a) Compute the next two iterates. Which root will the method converge to, and why?
  - (b) How many iterations are needed until the root is found to within  $10^{-3}$  accuracy?
  - (c) Use Secant method to compute  $x_3$  if  $x_1 = 2$  and  $x_2 = 2.5$ .
2. Set up Newton’s method to determine the point  $x$  and the number  $m$  for which the line  $y = mx$  intersects the curve  $y = \cos(x)$  tangentially: that is  $y = mx$  is tangent to  $y = \cos(x)$  at the point of intersection  $x$ .
3. Find the polynomial  $P(x)$  which interpolates  $\sin x$  at  $x = 0, \pi/2, \pi$ . Then find a number  $E$  such that  $|P(\frac{\pi}{4}) - \sin(\pi/4)| \leq E$ .
4. A Chebychev polynomial  $T_n$  on  $[-1, 1]$  has the form  $T_n(x) = 2^{n-1}(x - x_1) \dots (x - x_n)$  where  $x_1 \dots x_n$  are its roots,  $x_i = \cos \frac{(2i-1)\pi}{2n}$ . Moreover it has the property that  $|T_n(x)| \leq 1$  for  $x \in [-1, 1]$ .
  - (a) Suppose that a function  $f(x) = \sin(2x)$  is interpolated on  $[-1, 1]$  at the roots of Chebychev polynomial  $x_1 \dots x_n$  by a polynomial  $P_{n-1}(x)$ . Give the bound for the error  $E = |P_{n-1}(x) - f(x)|$ , with  $x \in [-1, 1]$ .
  - (b) Suppose that a function  $f(x) = \sin(2x)$  is interpolated on the interval  $[0, 5]$ , at  $n$  points using Chebychev interpolation (that is, at the points which are the appropriately scaled and translated Chebychev roots) by a polynomial  $P_{n-1}(x)$ . Give the bound for the error  $E = |P_{n-1}(x) - f(x)|$ , with  $x \in [-1, 1]$ .
5. A free cubic spline  $s$  for a function  $f$  is defined on  $[1, 3]$  by

$$s(x) = \begin{cases} s_0(x) = 2(x - 1) - (x - 1)^3 & 1 \leq x < 2 \\ s_1(x) = a + b(x - 2) + c(x - 2)^2 + d(x - 2)^3 & 2 \leq x \leq 3 \end{cases}$$

Find  $a, b, c, d$ . Note that a free spline on  $[1, 3]$  satisfies  $s''(1) = 0 = s''(3)$ .

6. Someone has given you a subroutine for approximating the solution of an initial value problem. You don't know the order of the method, so you run the code on a problem with a known solution for two values of  $h$  and get the following errors:

$h$	$ error $
0.01	$1.2 \times 10^{-5}$
0.005	$1.51 \times 10^{-6}$

You conclude the order of the method is  $O(h^p)$  where  $p$  is what integer?

7.

- (a) Find the Lagrange polynomial interpolating  $y(x_0)$ ,  $y(x_0 + \frac{h}{3})$  and  $y(x_0 + h)$ . Include the error term.
- (b) Use the above Polynomial to find an approximation to  $y'(x_0)$  using the values at  $x = x_0, x_0 + \frac{h}{3}, x_0 + h$ . Also estimate the error term.

8. The centered differences formula for the second derivative of a function  $y(x)$  is

$$y_c''(x) = (y(x+h) + y(x-h) - 2y(x))/h^2.$$

- (a) Estimate the error  $|y_c''(x) - y''(x)|$  in terms of  $h$ .
  - (b) Use Richardson extrapolation to come up with an approximation to  $y''(x)$  which is accurate up to  $O(h^4)$ .
9. You have a numerical method  $N(h)$  which has  $O(h)$  error. Applying  $N(h)$  for three different values of  $h$  you get the following behaviour:

$h$	0.2	0.1	0.05
$N(h)$	1.6	1.4	1.3

Use Richardson extrapolation to get the best possible estimate you can for  $N(0)$ .

10. Given that  $f(x)$  is sufficiently smooth, find the bound for the error  $E = \left| \int_{-1}^1 f(x)dx - M \right|$  where  $M = f(1) + f(-1)$ .

11.

- (a) It is known that  $g(x) = \frac{1}{x^2+1} - 2x + \exp(\sin(x)) - \cos(\exp(x))$ . Find a constant  $M$  such that  $|g(x)| < M$  on the interval  $[-1, 2]$ .
- (b) Let  $T_n$  be the Trapezoid rule approximation to  $I = \int_{-1}^2 f(x)dx$ . Suppose that  $f''(x) = g(x)$  where  $g$  is as in part (a). How large should you choose  $n$  to guarantee that  $\left| \int_{-1}^2 f(x) - T_n \right| \leq 10^{-3}$ ? Remark: it is known that  $\left| \int_a^b f(x) - T_n \right| \leq \frac{M}{24}(b-a)h^2$  where  $M$  is a constant such that  $|f''(x)| \leq M$  for all  $x \in [a, b]$ .

12. Use two point Gaussian quadrature to approximate,

$$\int_0^1 \cos(x^2) dx$$

You may use the table below. You do not need to simplify your answer.

Points	Weighting Factors	Function Arguments
2	c1 = 1.000000000 c2 = 1.000000000	x1 = -0.577350269 x2 = 0.577350269
3	c1 = 0.555555556 c2 = 0.888888889 c3 = 0.555555556	x1 = -0.774596669 x2 = 0.000000000 x3 = 0.774596669
4	c1 = 0.347854845 c2 = 0.652145155 c3 = 0.652145155 c4 = 0.347854845	x1 = -0.861136312 x2 = -0.339981044 x3 = 0.339981044 x4 = 0.861136312

13. Consider the following initial value problem

$$y' = y - 2, \quad y(0) = 1. \quad (1)$$

- Take one time step of  $h = 0.1$  with the first order Euler's method to approximate  $y(0.1)$ .
- Repeat part (a) with backwards Euler's method.
- Describe the stability region of the Euler's method.
- Show that the backwards Euler's method is stable for all  $h > 0$ .

14. Given the following class of methods to integrate  $y' = f(y)$  :

$$y_{i+1} = y_i + h \left( \frac{1}{4}f(y_i) + af(y_i + hf(y_i)) \right). \quad (2)$$

- Determine the values of  $a, b$  which will minimize the local error. What will be the local and the global error?
- Apply this method to the ode  $y' = -y$ ,  $y(0) = 1$ . For which *real* values of  $h > 0$  it true that  $y_n \rightarrow 0$  as  $n \rightarrow \infty$ ?

15. Consider the following multi-step method:

$$y_{i+1} = y_i + ay_{i-1} + h (bf(y_i) + cf(y_{i-1})).$$

- Determine the values of  $a, b$  and  $c$  which will minimize the local error. What will be the local and the global error?
- Is the method you found in part (a) stable or unstable if  $h$  is sufficiently small?

16. Given a system

$$x^3 + y^3 = 1; \quad x^2 = \sin(y).$$

- Set up the multi-variable Newton method to determine the root of this system.
- Given an initial guess  $(x_0, y_0) = (0, 0)$ , determine the next iteration  $(x_1, y_1)$ .

17. Write out the linear system for  $a, b$  such that the quadratic  $y = ax + bx^2$  is the least squares approximation to the following data.

$x_i$	0	2	3	4
$y_i$	0	3	3	2

**Note:** You do not need to solve this system.

18. Assume we have the data set  $(x_1, y_1), \dots, (x_n, y_n)$ . We wish to determine the constants  $a$  and  $b$  which minimize the sum of the square of the error for the model  $y = \frac{ax}{x+b}$ .

- (a) Give the nonlinear least squares equations which must be satisfied for optimal values  $a$  and  $b$ .  
**Note:** Just give the equations which  $a$  and  $b$  must satisfy. You do not need to consider any iterative method for finding the values.
- (b) How can you transform the problem into a linear problem?
- (c) Write down the equations that you need to solve for  $a, b$ , which minimizes the error for the transformed data using linear least squares.
19. A rocket shoots straight up. After some rescaling, its height satisfies the ODE

$$y''(t) = -\frac{a}{(1+y)^2}.$$

Describe how you would use the Shooting method to determine the value of  $a$  so that  $y(t)$  satisfies the above equation with additional constraints  $y(0) = 0$ ,  $y(1) = 1$ ,  $y'(1) = 0$ .