

Turing instability

Q: Can diffusion cause an instability?

- For the heat eq'n, $u_t = D u_{xx}$, we know that any initial conditions decay to a constant steady state, so diffusion has a smoothing effect.

- More generally, consider a pde

$$(1) \quad \begin{cases} u_t = D u_{xx} + f(u) & , \quad x \in (0, L) \\ u'(0) = 0 = u'(L) \end{cases}$$

Suppose u_0 is a stable steady state of ODE $u_t = f(u)$; i.e.

$$(2) \quad f(u_0) = 0; \quad f'(u_0) < 0$$

Can addition of diffusion $D u_{xx}$ destabilize u_0 ?

Linearize: $u(x, t) = u_0 + e^{\lambda t} \varphi(x)$; $\varphi \ll 1$;

$$\begin{cases} \lambda \varphi = D \varphi_{xx} + f'(u_0) \varphi \\ \varphi'(0) = 0, \varphi'(L) = 0 \end{cases}$$

$$\Rightarrow \varphi = \cos(mx) \quad \text{where} \quad mL = K\pi, \quad K = 1, 2, 3, \dots$$

$$\text{and} \quad \lambda = -m^2 D + f'(u_0) < 0 \quad \text{from (2)}$$

Conclusion: u_0 remains stable;

(2)

For a single PDE (2), diffusion cannot cause instability.

In 1952 paper, Turing asked: can diffusion destabilize a system of PDE's:

$$(3) \quad \begin{cases} u_t = D_1 u_{xx} + f(u, v) \\ v_t = D_2 v_{xx} + g(u, v) \end{cases}$$

Suppose (3) has a homogeneous steady state (u_0, v_0) satisfying $f(u_0, v_0) = 0$, $g(u_0, v_0) = 0$.

Moreover, suppose (u_0, v_0) is stable s.s. of the corresponding ODE system:

$$(4) \quad \begin{cases} u_t = f(u, v) \\ v_t = g(u, v) \end{cases}$$

Linearize (4): $u(t) = u_0 + e^{\lambda t} \eta$; $v(t) = v_0 + e^{\lambda t} \xi$

$$(5) \quad \Rightarrow \quad \lambda \begin{bmatrix} \eta \\ \xi \end{bmatrix} = \underbrace{\begin{bmatrix} f_u & f_v \\ g_u & g_v \end{bmatrix}}_{J|_{(u,v)=(u_0,v_0)}} \begin{bmatrix} \eta \\ \xi \end{bmatrix}$$

So (4) is stable provided that all eigenvalues of J have negative real part, or

$$\det J > 0; \quad \text{tr } J < 0.$$

$$\Leftrightarrow \begin{cases} f_u g_v - f_v g_u > 0 \\ f_u + g_v < 0 \end{cases} \quad (6)$$

(where the expressions are evaluated at $u=u_0, v=v_0$).

Now linearize (3):

$$(7) \quad \begin{cases} u = u_0 + \cos(mx) e^{\lambda t} \eta \\ v = v_0 + \cos(mx) e^{\lambda t} \xi \end{cases} \quad \text{with } \eta, \xi \ll 1$$

$$(8) \Rightarrow \lambda \begin{bmatrix} \eta \\ \xi \end{bmatrix} = \underbrace{\begin{bmatrix} -m^2 D_1 & 0 \\ 0 & -m^2 D_2 \end{bmatrix} + \begin{bmatrix} f_u & f_v \\ g_u & g_v \end{bmatrix}}_M \begin{bmatrix} \eta \\ \xi \end{bmatrix}$$

Now λ satisfies: $\lambda^2 - (\text{tr } M)\lambda + \det M = 0$.

• If $m=0 \Rightarrow \text{Re}(\lambda) < 0$ [since ODE is stable]

• If $m \rightarrow \infty \Rightarrow M \sim -m^2 \begin{bmatrix} D_1 & \\ & D_2 \end{bmatrix} \Rightarrow \text{Re } \lambda < 0$

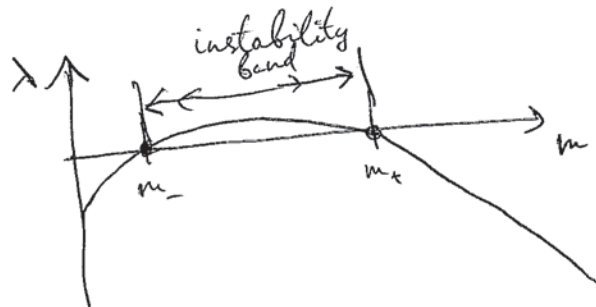
Is there a range of m for which $\text{Re } \lambda > 0$?

Suppose that such a range exists. Its endpoints

satisfy: • either $\det M = 0$ [one of $\lambda = 0$]
• or $\text{tr } M = 0$ [$\lambda = \pm i\omega$, $\text{Re } \lambda_{\pm} = 0$]

Exercise: only $\det M = 0$ is possible.

(4)



Then $m_{\pm}$ satisfy:

$$(f_u - m^2 D_1)(g_v - m^2 D_2) - f_v g_u = 0$$

$$\Leftrightarrow m^4 D_1 D_2 + m^2 (-D_1 g_v - D_2 f_u) + f_u g_v - f_v g_u = 0$$

This is a quadratic in m^2 ; thus instability

band exists iff

$$(9) \quad D_1 g_v + D_2 f_u \neq 0 \quad \text{and} \quad (D_1 g_v + D_2 f_u)^2 - 4 D_1 D_2 (f_u g_v - f_v g_u) \geq 0$$

Let $r = \frac{D_2}{D_1}$. Then (9) becomes:

$$(10) \quad p(r) = r^2 f_u^2 + r (4 f_v g_u - 2 f_u g_v) + g_v^2 \geq 0$$

and $g_v + r f_u \neq 0$

Note that $p(r) > 0$ if $r \gg 1$ or $r = 0$

Thus instability band will appear if

- $f_u > 0$ and $\frac{D_2}{D_1}$ is sufficiently large
- $g_v > 0$ and $\frac{D_1}{D_2}$ is sufficiently large.

Exercise: No instability if $f_u < 0$, $g_v < 0$ or if $D_1 = D_2$.

Example Consider GS model :

$$(11) \quad \begin{aligned} v_t &= D_1 v'' - v + A v^2 u \\ \tau u_t &= D_2 u'' - u + 1 - v^2 u \end{aligned}$$

S.S. given by : $v_0 u_0 A = 1$, $v_0^2 - A v_0 + 1 = 0$
or $v_0 = 0$, $u_0 = 1$

$$\Rightarrow \begin{cases} v_0 = 0, u_0 = 1 \\ v_0^\pm = \frac{A \pm \sqrt{A^2 - 4}}{2}, u_0^\pm = \frac{1}{A v_0^\pm}, A > 2 \end{cases}$$

Linearize : $\begin{aligned} v &= v_0 + \cos(mx) e^{\lambda t} \xi \\ u &= u_0 + \cos(mx) e^{\lambda t} \eta \end{aligned}$

$\Rightarrow \lambda$ is an eigenvalue of

$$M = \begin{bmatrix} -D_1 m^2 - 1 + 2u_0 v_0 & v_0^2 A \\ -\frac{1}{\tau} 2u_0 v_0 & -\frac{1}{\tau} (D_2 m^2 + 1 + v_0^2) \end{bmatrix}$$

For S.S. $v_0 = 0, u_0 = 1$, M is diagonal with $\lambda < 0$ $\forall m$.

For S.S. $v_0^\pm, u_0^\pm$ we have

$$M = \begin{bmatrix} -D_1 m^2 + 1 & v_0^2 A \\ -\frac{1}{\tau} \frac{2}{A} & -\frac{1}{\tau} (D_2 m^2 + 1 + v_0^2) \end{bmatrix}$$

Let $f(m) = \tau \det M = D_1 D_2 m^4 + m^2 (D_1 (1 + v_0^4) - D_2) + v_0^2 - 1$

so that $f(0) = v_0^2 - 1 \begin{cases} < 0 & \text{if } v_0 = v_0^- \\ > 0 & \text{if } v_0 = v_0^+ \end{cases}$

So v_0^- is unstable even when $m=0$;

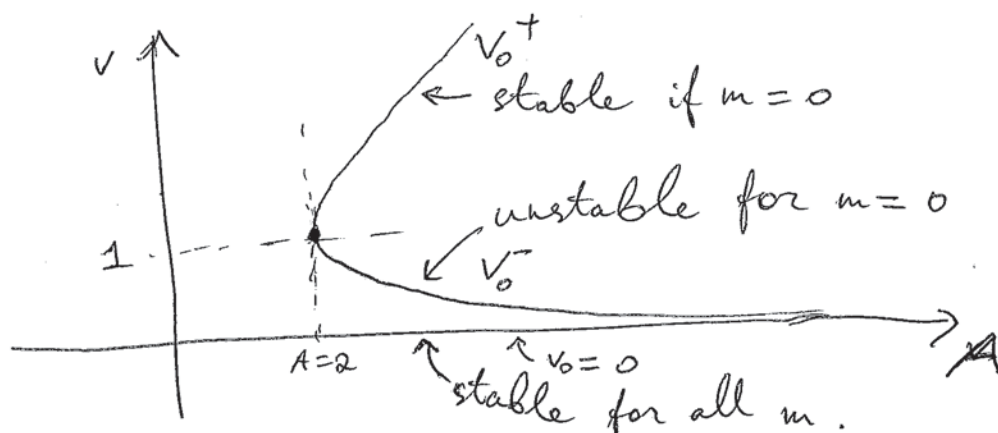
Suppose τ is s.t. $\text{trace } M|_{\substack{m=0 \\ v_0=v_0^+}} < 0$

i.e. $\tau < A v_0^+$

In particular, take $\tau < 2$.

Then v_0^+ is stable w.r.t. $m=0$

So for $m=0$ we have the bifurcation diagram:



Q: Can the v_0^+ become unstable for some m ?

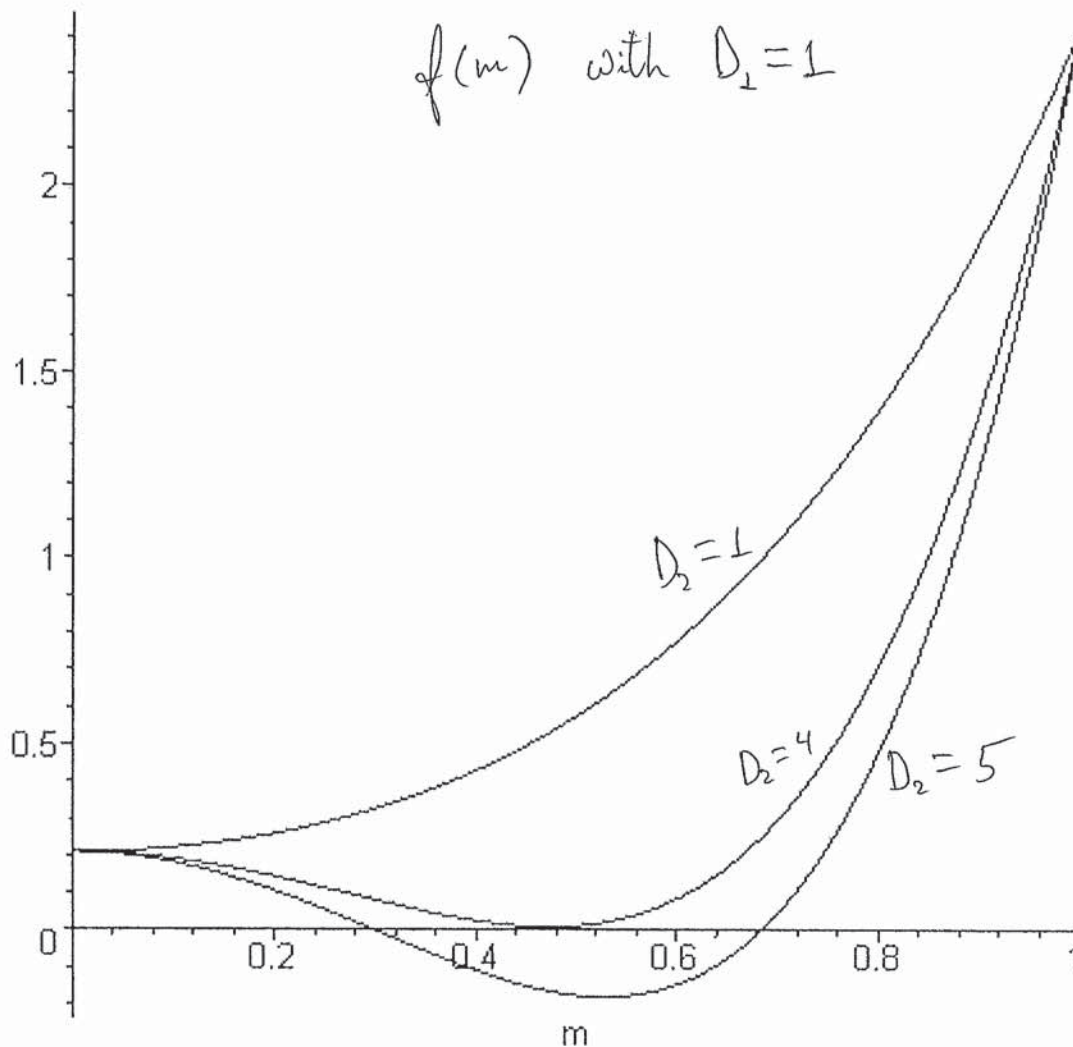
Answer: By assumption $\tau < 2$, $\text{tr } M < 0 \forall m$.

So mode m is unstable iff $f(m) < 0$

An instability band appears as D_2 is increased

For example, take $D_1=1$ and $v_0=1.1$.

Then $f(m)$ is as shown for $D_2=1, 4, 5$:



An instability band appears around $D_2 \sim 4$.

For example, when $D_2=5$, the modes $m \in [0.3, 0.68]$ are unstable.

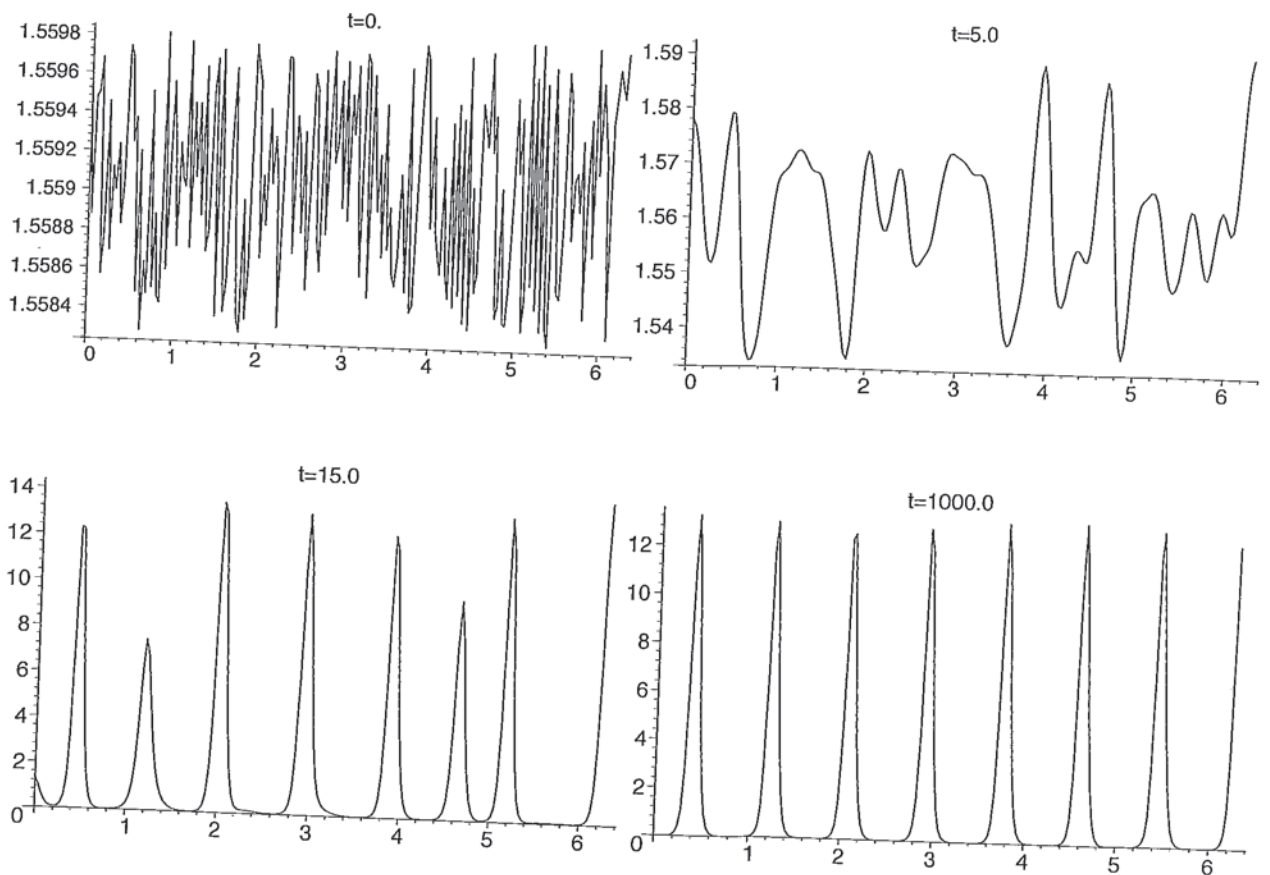
The endpoints of instability band are roots of $f(m)$.

The instability band exists iff $\frac{D_2}{D_1} > \tau$

Where τ is given by:

$$(1 + V_0^{+2} - \tau)^2 = 4\tau(V_0^{+2} - 1)$$

In particular, $\tau=2$ if $A=2$, $V_0^+=1$ and τ increases with A .



Grey-Scott model:
 Example of Turing instability, with $A=2.3$,
 $D_1=1$, $D_2=1000$. Note that the final steady
 state consists of spikes.

Weakly nonlinear Turing analysis

We found that $\exists D_2^*$ s.t. the homogeneous steady state is unstable when $D_2 > D_2^*$; the instability is of the form

$$u = u_0 + \eta \cos(mx) e^{\lambda t}, \quad \eta \ll 1$$

Question:

- Can we find η as a function of D_2 ?
- What happens to a Turing pattern as $t \rightarrow \infty$?

Such questions can be answered when D_2 is near

Example: Consider the Ginzburg-Landau equation

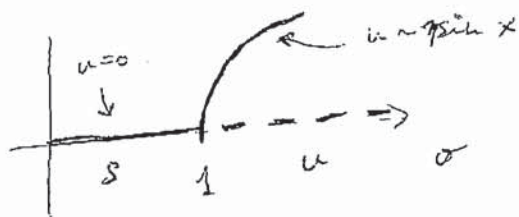
$$\begin{cases} u_t = u_{xx} + \sigma u - u^3, & x \in (0, \pi) \\ u(0) = 0 = u(\pi) \end{cases}$$

It has a steady state $u=0$. To study its stability, we linearize:

$$u = 0 + \eta e^{\lambda t} \sin(mx), \quad \eta \ll 1$$

Then $\lambda = -m^2 + \sigma \quad m=1, 2, \dots$

Note that $\lambda < 0 \quad \forall m=1, 2, \dots$ provided that $\sigma < 1$. As σ crosses 1, the ground state $u=0$ becomes unstable, and $u \sim \eta \sin(x), \quad \eta \ll 1$.



Now suppose σ is near 1;

we want to find $\eta = \eta(\sigma)$. Suppose $\eta = \varepsilon A$ and $\varepsilon \ll$

Rescale: $u = \varepsilon U$
and let: $\sigma = 1 + \varepsilon^2$

$$\Rightarrow \begin{cases} U_t = U_{xx} + U + \varepsilon^2(U - U^3) \\ U(0, t) = 0 = U(\pi, t) \end{cases}$$

Rescale time:

$$\Rightarrow U_{xx} + U = \varepsilon^2(U^3 - U + U_s) \quad s = \varepsilon^2 t$$

Expand: $U = U_0(x, s) + \varepsilon^2 U_1(x, s) + \dots$

We get
$$\begin{cases} U_{0,xx} + U_0 = 0 & (*) \\ U_{1,xx} + U_1 = U_0^3 - U_0 + U_{0,s} & (**) \end{cases}$$

with B.C. $U_0(0, s) = 0 = U_0(\pi, s)$

Thus, $U_0(x, s) = A(s) \sin(x)$

where $A(s)$ is to be found.

Now:
$$\int_0^\pi (U_{1,xx} + U_1) U_0 = \int_0^\pi U_0 (U_0^3 - U_0 + U_{0,s}) = 0$$

So multiply (**) by U_0 & integrate to get:

$$\int_0^\pi U_0 (U_0^3 - U_0 + U_{0,s}) = 0 \quad (***)$$

Note: $\int_0^\pi \sin^2(t) dt = \frac{\pi}{2}$

$\int_0^\pi \sin^4(t) dt = \frac{3}{8}\pi$

so that $(*)$ becomes:

$$\frac{3}{8}\pi A^4 - \frac{\pi}{2} A^2 + \frac{\pi}{2} A A_S = 0$$

or $A_S = A - \frac{3}{4} A^3$ ★

• This eqn describes the slow evolution of the amplitude; remember that

$$\begin{cases} u(x,t) = \varepsilon A(\varepsilon^2 t) \sin(x) \\ \sigma = 1 + \varepsilon^2 \end{cases}$$

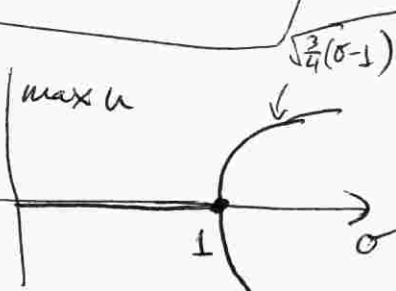
• Note that $A \rightarrow \pm \sqrt{\frac{3}{4}}$ as $\varepsilon \rightarrow \infty$

• Conclusion: for s.s. indep. of t , we get:

$$u \sim \varepsilon \sqrt{\frac{3}{4}} \sin x, \quad \sigma = 1 + \varepsilon^2$$

$$\max u \sim \varepsilon \sqrt{\frac{3}{4}}$$

$$\max u \sim \sqrt{\frac{3}{4}(\sigma-1)}, \quad \sigma > 1$$



References

- 1) A. Turing, "The chemical basis of Morphogenesis", Phil. Trans. Royal Soc. B, 237 (1952)
- 2) J. Reynolds, "Complex patterns in a simple system", Science 261 (1993), p. 183-192.
(about Gray-scott model).
- 3) Holmes, M.H., "Introduction to Perturbation methods"
(see Chap. 6 for more on Ginzburg-Landau eqn)

Some Questions:

- 1) For GS model (11), show that there is no Turing instability if $\frac{D_2}{D_1} < 2$.
- 2) Consider the Brusselator model:

$$\begin{aligned}u_t &= D u_{xx} - u + \alpha + u^2 v \\ \varepsilon v_t &= D v_{xx} + (1 - \beta) u - u^2 v\end{aligned}$$

with $D, \varepsilon, \alpha, \beta > 0$.

- a) Find the steady states and classify their stability when $D = 0$.
 - b) Perform the Turing stability analysis of the steady states found in (a).
- 3) Consider the model of organic farming:

$$\begin{cases} u_t = u_{xx} + g(x)u - u^2, & x \in [0, \infty] \\ u'(0) = 0, \quad u'(\infty) = 0, \quad u \geq 0 \quad \forall x \geq 0. \end{cases}$$

with $g(x) = \begin{cases} 1, & x < l \\ -1, & x > l \end{cases}$.

Recall that if $l < \frac{\pi}{4}$ then the only sol'n is $u = 0$, but if $l > \frac{\pi}{4}$ then there is a non-zero solution. If $l = \frac{\pi}{4} + \varepsilon$ and $\varepsilon \ll 1$ then $u \sim A \phi_0(x)$ where ϕ_0 solves

$$\begin{cases} -\phi_0'' + g(x) \phi_0 = 0 & \text{with } l = \frac{\pi}{4} \\ \phi_0'(0) = 0, \quad \phi_0'(\infty) = 0. \end{cases}$$

Determine A as a function of ε , $\varepsilon \ll 1$.