

Saturation in SIR model

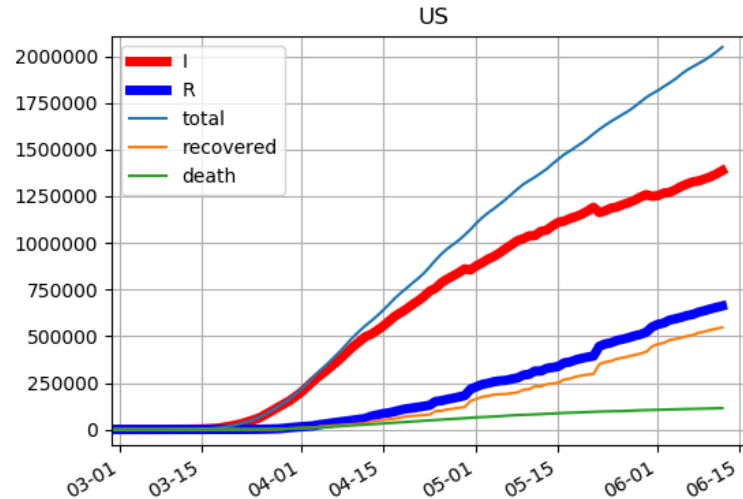
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- SIR model:

$$\frac{dS}{dt} = -\frac{\beta}{N}SI; \quad \frac{dI}{dt} = \frac{\beta}{N}SI - \gamma I; \quad \frac{dR}{dt} = \gamma I \quad (1)$$

- Here is US data:

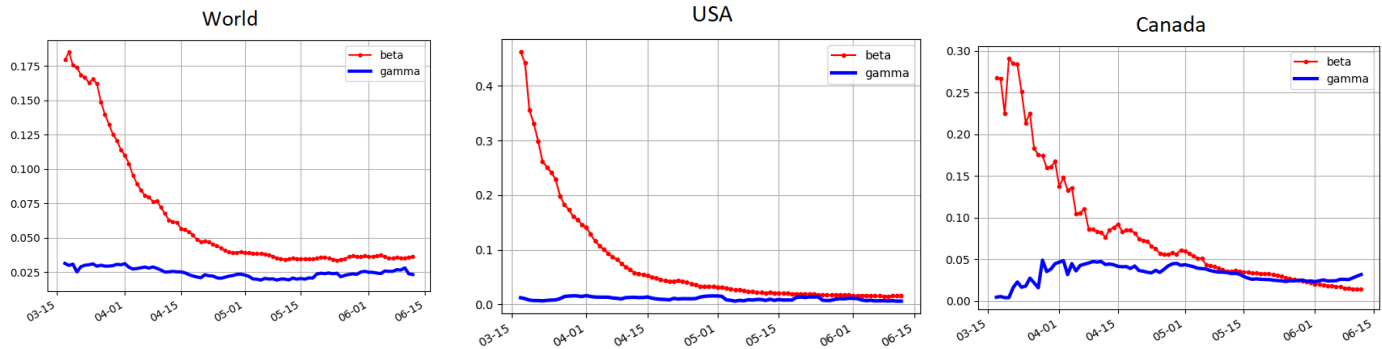


- Does SIR model fit coronavirus data?

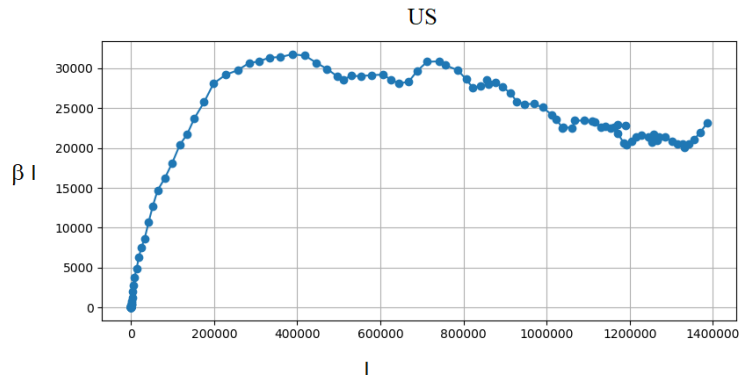
- Think of $\beta = \beta(t)$ and $\gamma = \gamma(t)$.

- Estimate $\beta(t)$ $\gamma(t)$ from equations and data: $\beta(t) \approx -\frac{NS'(t)}{SI}$; $\gamma(t) \sim \frac{R'}{I}$

- Here is an example of plot of $\beta(t)$, $\gamma(t)$ from data:



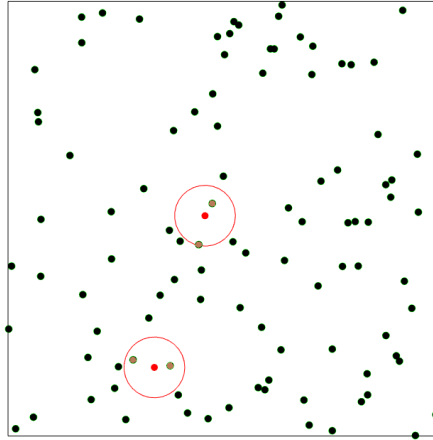
- Note that γ doesn't change much, but $\beta(t)$ decreases steadily throughout the infection.
- The decrease of $\beta(t)$ is consistent for multiple datasets.
- Alternatively, we can plot βI as a function of I :



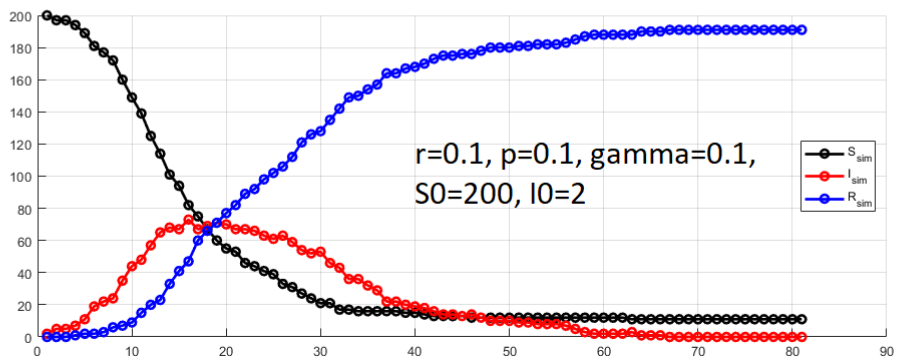
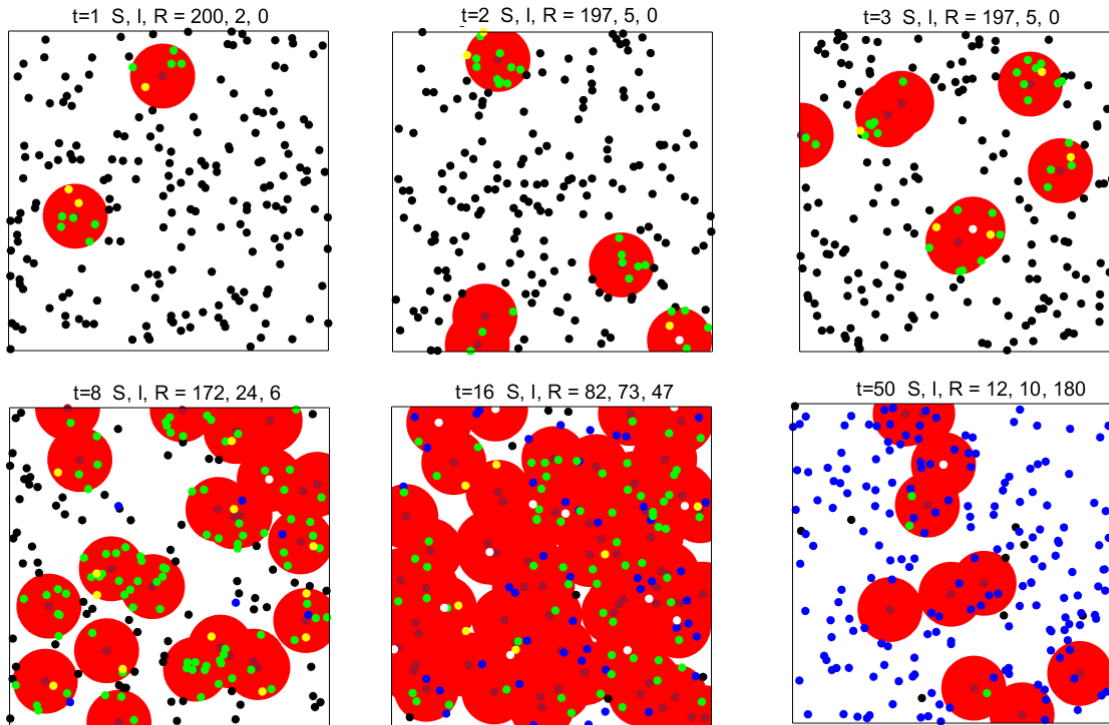
- Note how βI saturates as I increases. This suggests that some saturation may occur.

Agent-based SIR model

- Assume there is an “infection radius” r ; infection can only happen when susceptible comes within the distance r of infected individual

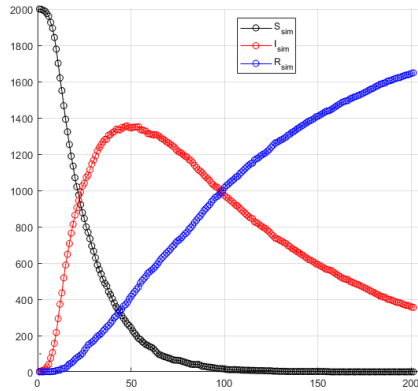


- An infection occurs with some probability p if a susceptible person comes within a radius r of the infected person
- Assume people are “well-mixed”: all are located at random within a unit box.
- Infected individuals are removed with some rate γ .

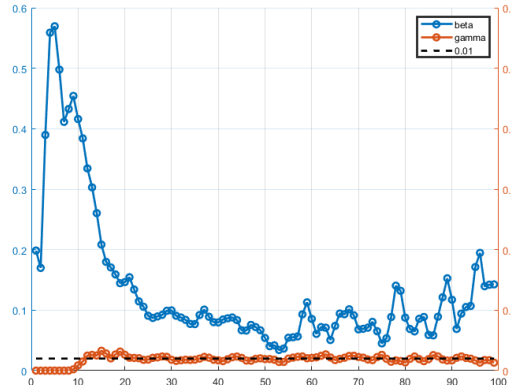


- Let's estimate $\beta \approx -\frac{S'(t)}{SI}$; $\gamma \sim \frac{R'}{I}$ we get this curve:

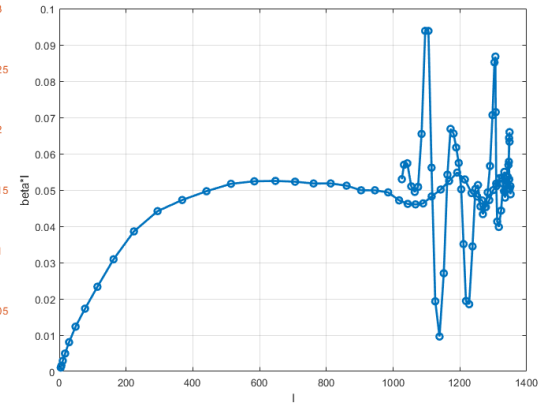
r=0.05, p=0.05, gamma=0.01



beta and gamma versus t



beta*I versus I

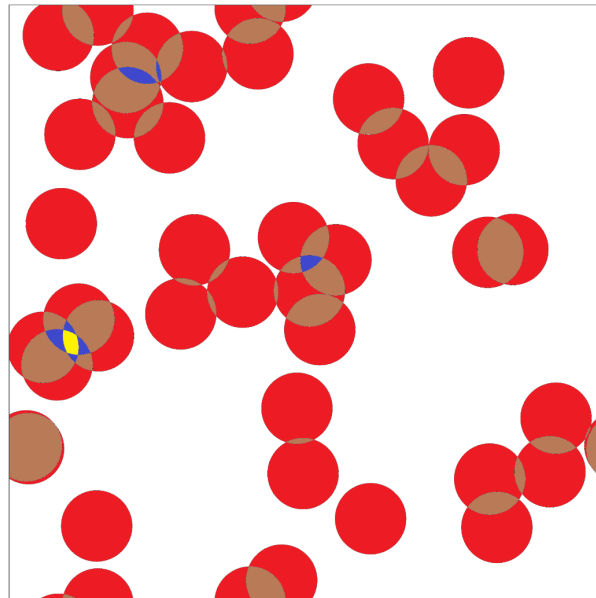


- Gamma is roughly constant ≈ 0.01 ; but β is clearly non-constant.
- There is a clear saturation of βI , when plotted versus I .
- This is similar to observed data for COVID in US, Canada, World and others.
- The reason is that when enough people are infected, they “cover” the whole area so introducing even more infecteds doesn't

Continuum limit of ABM

- Given I infected individuals, the probability of infection is: $p * E$, where E is the probability that you are inside one of I circles.
- E is the fraction of the area occupied by the union of I disks
- For small I and small r , we expect $E \approx aI$, where $a = \frac{\pi r^2}{A}$ is the area fraction for a single disk of radius r inside a domain of area A .
- But as I is increased, some circles intersect, so eventually E saturates to 1.
- **Key question: what is the expected area fraction of I disks?**

E : expected area fraction of union of I disks



red: 0.28854
brown: 0.06671
blue: 0.00348
yellow: 0.00086

- Add I areas, then subtract $\binom{I}{2}$ pairwise intersections, then add back $\binom{I}{3}$ triple intersections....

- $E = IE_1 - \binom{I}{2} E_2 + \binom{I}{3} E_3 + \dots - (-1)^I E_I$ where:

- $E_1 = a = \frac{\pi r^2}{A}$ is the area fraction of a single disk
- E_2 is the expected area fraction of intersection of two random disks of radius a
- etc

● CLAIM: $E_j = a^j$

- Proof: either by direct integration, or by scaling argument: $E_j = C (a)^j$ for small a . Also $E_j = 1$ when $a = 1$, so $C = 1$.

● So we have obtain: $E = - \sum_{j=1}^I \binom{I}{j} (-a)^j = 1 - (1 - a)^I$.

● **Conclusion:** $E = 1 - (1 - a)^I \sim (1 - \exp(-Ia))$, where $a = \frac{\pi r^2}{A}$ is the area fraction for a single disk of radius r inside a domain of area A .

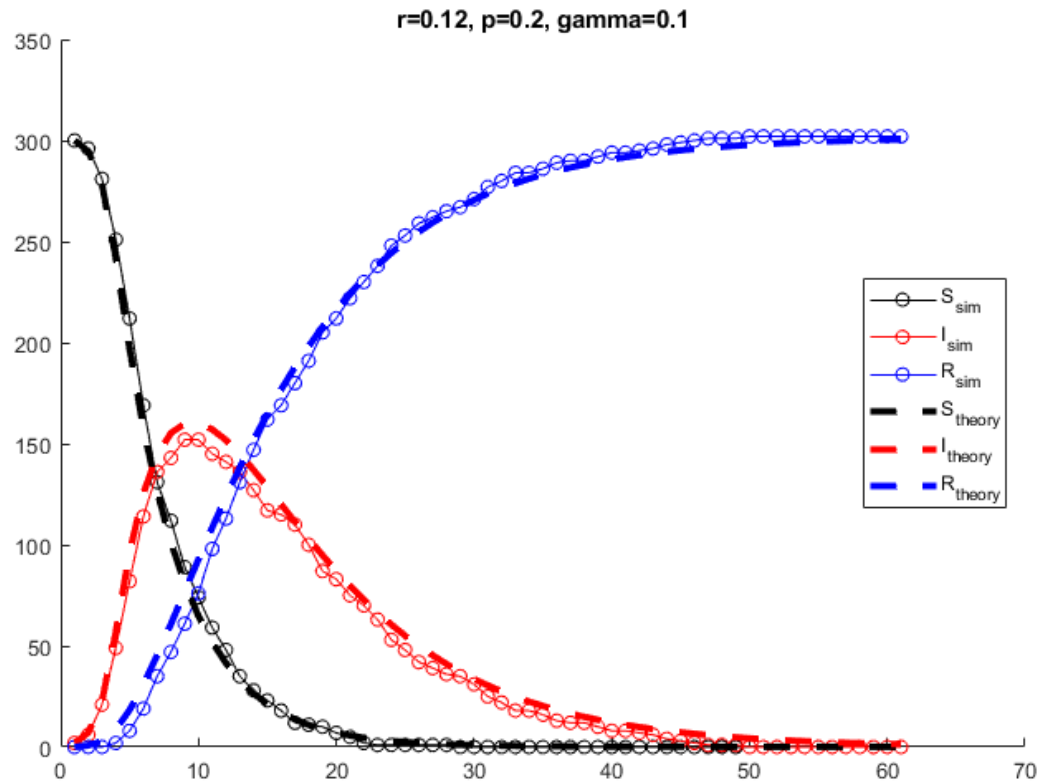
● SIR model becomes:

$$\boxed{\frac{dS}{dt} = -pS(1 - \exp(-Ia)); \quad \frac{dI}{dt} = pS(1 - \exp(-Ia)) - \gamma I; \quad \frac{dR}{dt} = \gamma I} \quad (2)$$

● Note that for small aI , we recover mass-action law: $pS(1 - \exp(-Ia)) \sim paSI$

Direct comparison: ABM vs ODE:

$$\frac{dS}{dt} = -pS(1 - \exp(-Ia)); \quad \frac{dI}{dt} = pS(1 - \exp(-Ia)) - \gamma I; \quad \frac{dR}{dt} = \gamma I \quad (3)$$



Estimating parameters from data

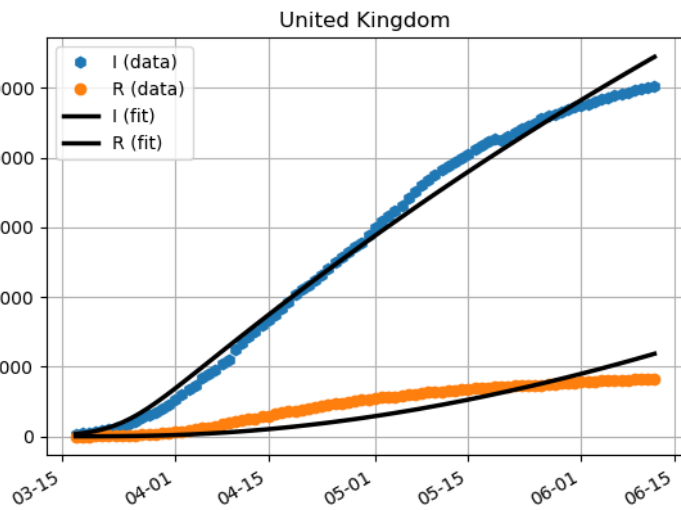
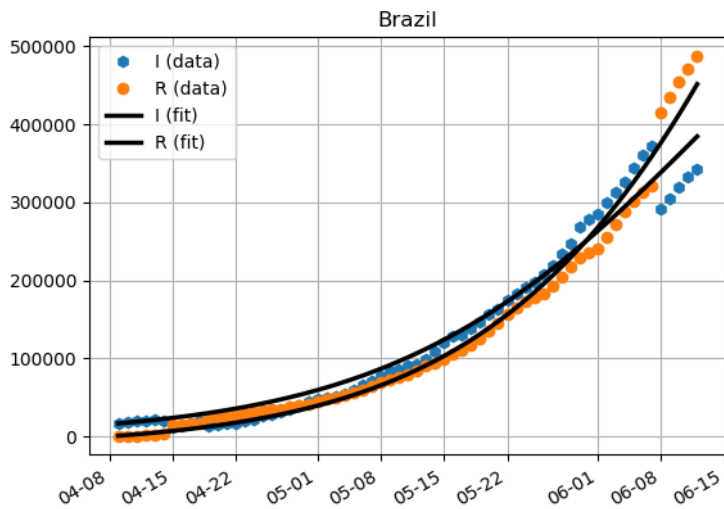
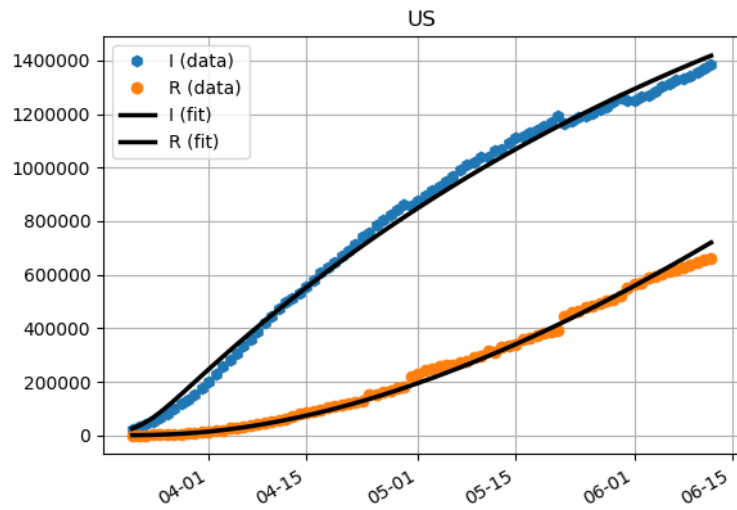
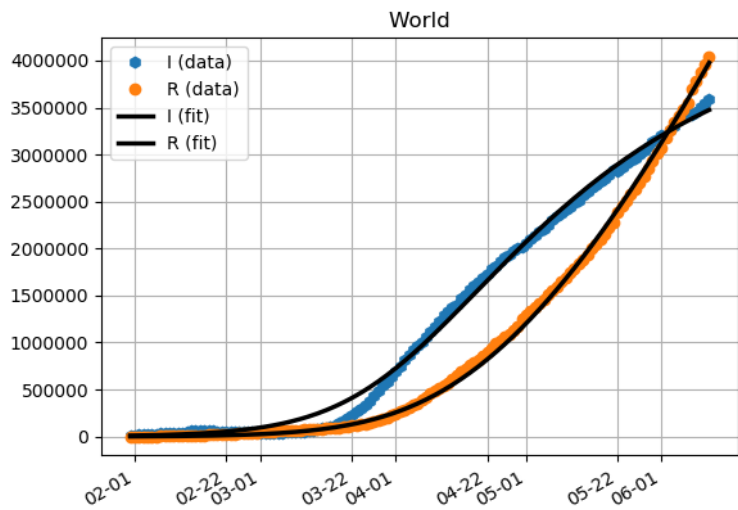
$$\frac{dS}{dt} = -\beta S \left(1 - \exp\left(-I \frac{\alpha}{N}\right)\right) \frac{1}{\alpha}; \quad \frac{dI}{dt} = \beta S \left(1 - \exp\left(-I \frac{\alpha}{N}\right)\right) \frac{1}{\alpha} - \gamma I; \quad \frac{dR}{dt} = \gamma I$$

- We use nonlinear least-squares fit to minimize the error in both I and R :

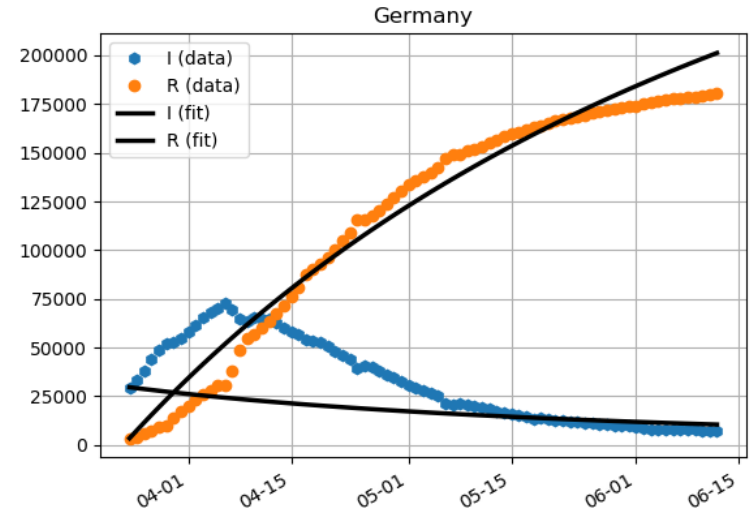
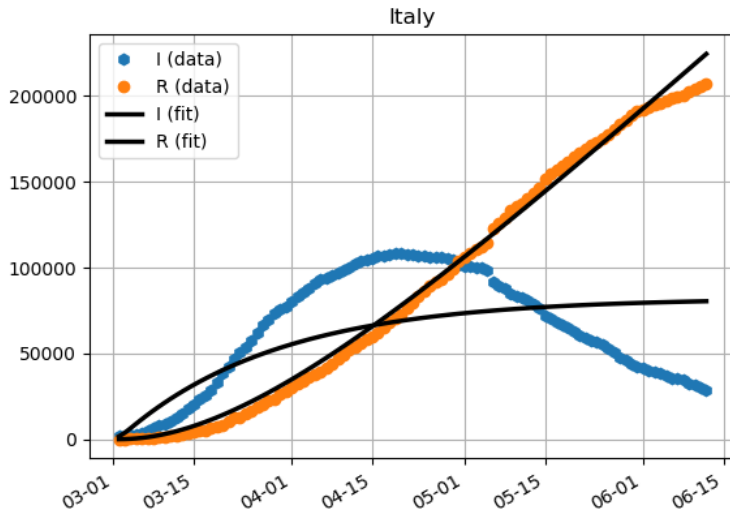
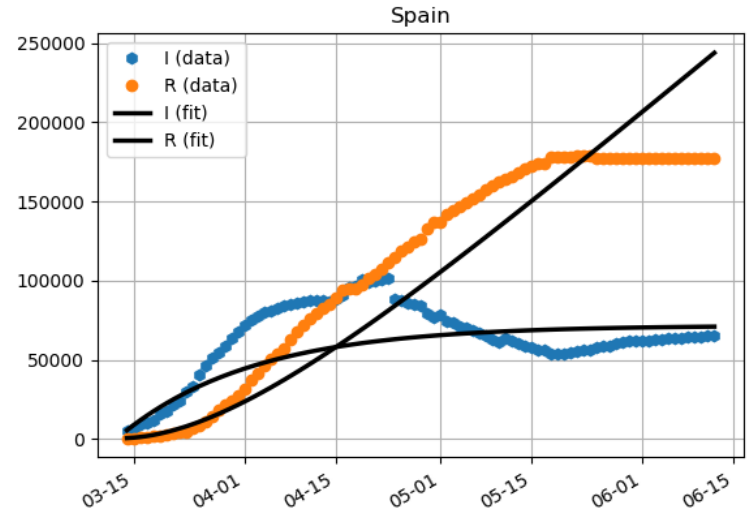
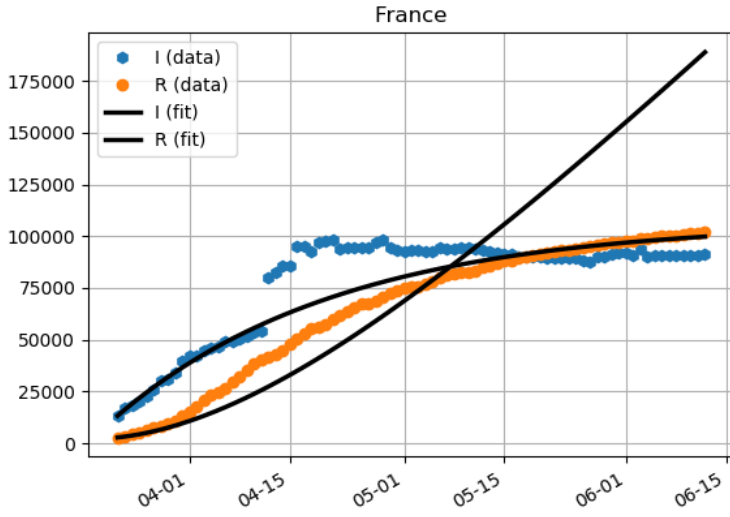
$$\min_{\alpha, \beta, \gamma} \sum_j (I(t_j) - I_j)^2 + (R(t_j) - R_j)^2$$

where S_j, R_j is the data from CSSEGIS or COVID19Tracking websites.

- Recovered = recovered+death; infected = total-recovered
- Used python's `optimize` routine using reasonable initial conditions (it "just works").
- We optimize over all parameters including gamma; but we fit to both I and R .
- Used data up to June 13, 2020, and from the time of 100 recovered individuals.
- Here are results:

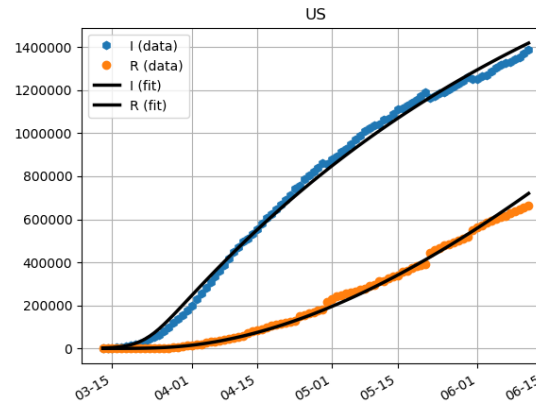
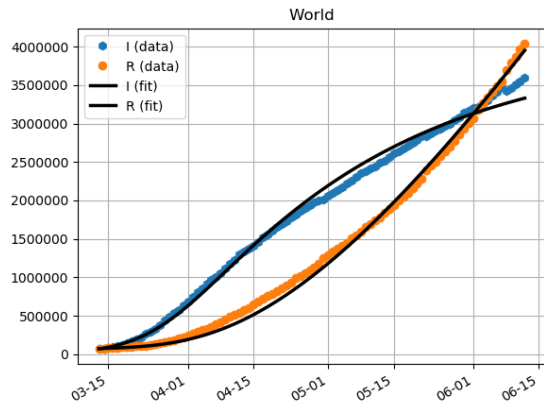


Sometimes it doesnt work:

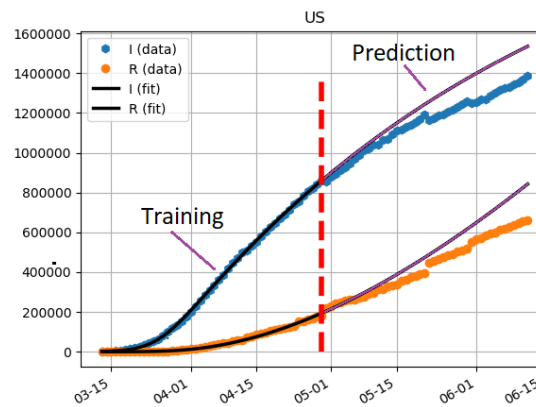
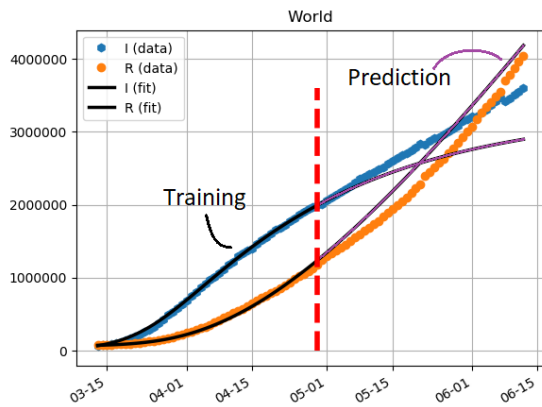


Predictive value

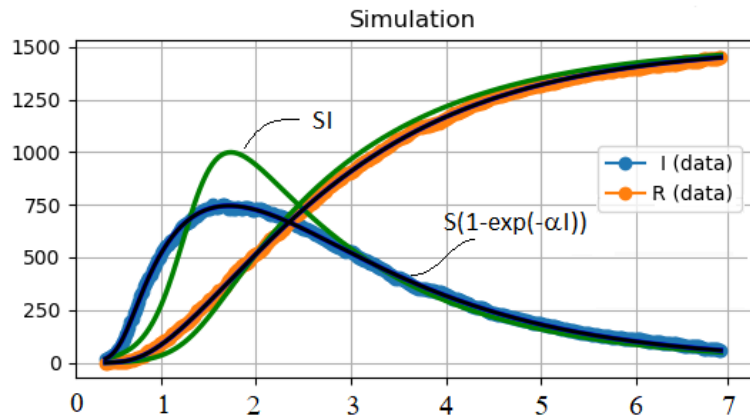
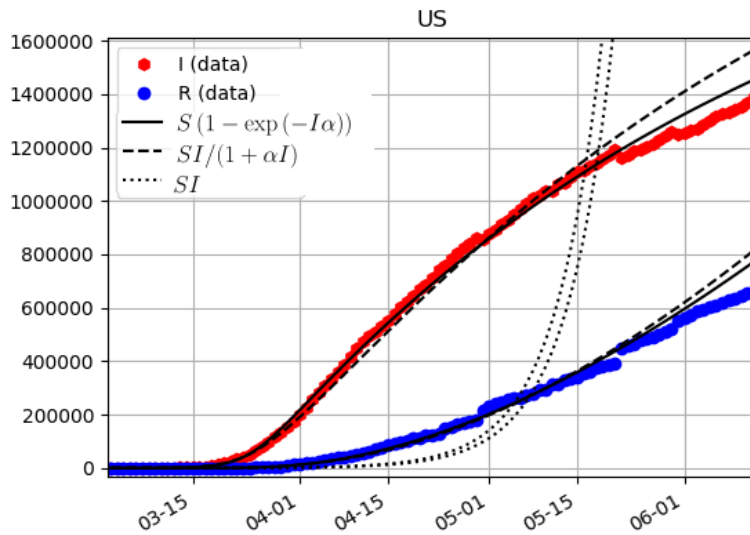
Training on all of data



Training on half of data, predicting other half



Comparison: saturation vs. without



Effect of population density on R_0

- SIR with saturation

$$\frac{dS}{dt} = -pS(1 - \exp(-Ia)); \quad \frac{dI}{dt} = pS(1 - \exp(-Ia)) - \gamma I; \quad \frac{dR}{dt} = \gamma I \quad (4)$$

- For small aI , we linearize $1 - \exp(-Ia) \sim aI$ so the model becomes

$$\frac{dS}{dt} = -paSI; \quad \frac{dI}{dt} = paSI - \gamma I; \quad \frac{dR}{dt} = \gamma I \quad (5)$$

- Here, $a = \pi r^2/A$, where A is total area and r infection radius.
- In terms of population density, $A = N/\rho$ so we have:

$$a = \pi r^2 \frac{\rho}{N}$$

- Compared to the usual SIR model, $pa = \beta/N$ and

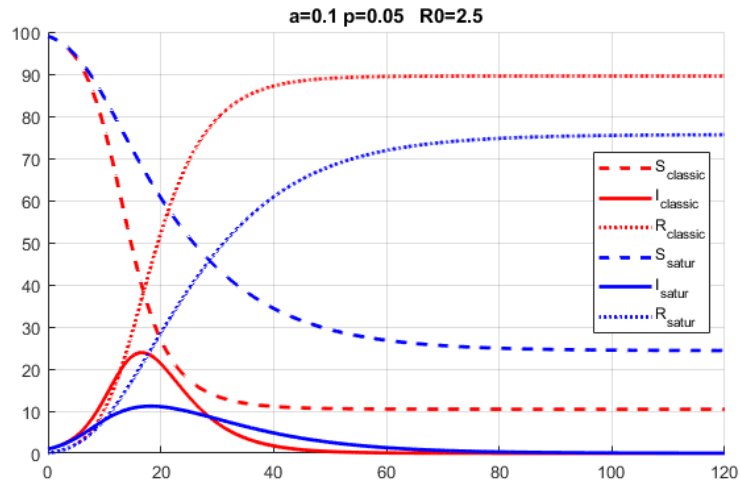
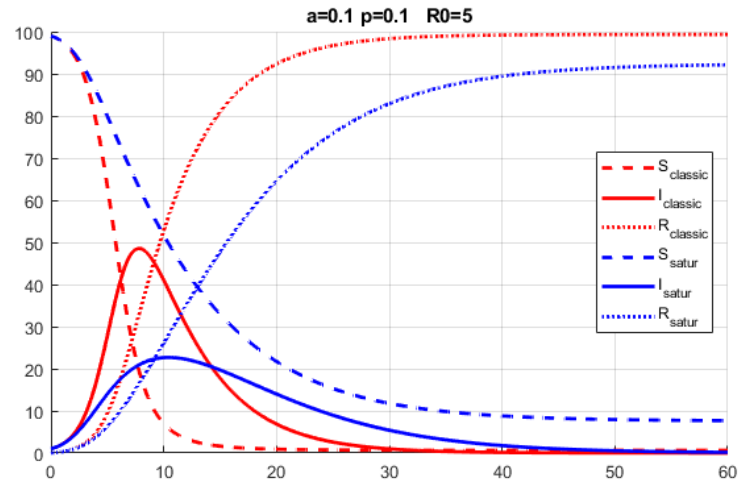
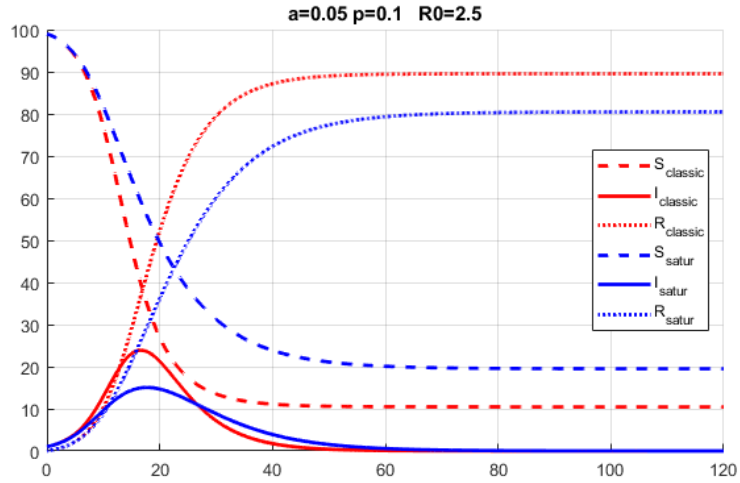
$$R_0 = \frac{\beta}{\gamma} = \frac{pNa}{\gamma} = \rho \frac{pr^2\pi}{\gamma}$$

where ρ is the population density.

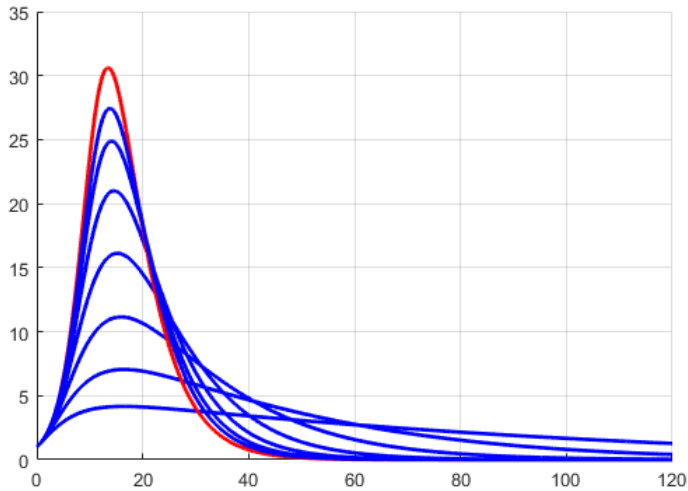
- **Conclusion:** R_0 *is proportional to the population density at the onset of the outbreak.*

SIR classical vs. SIR saturated

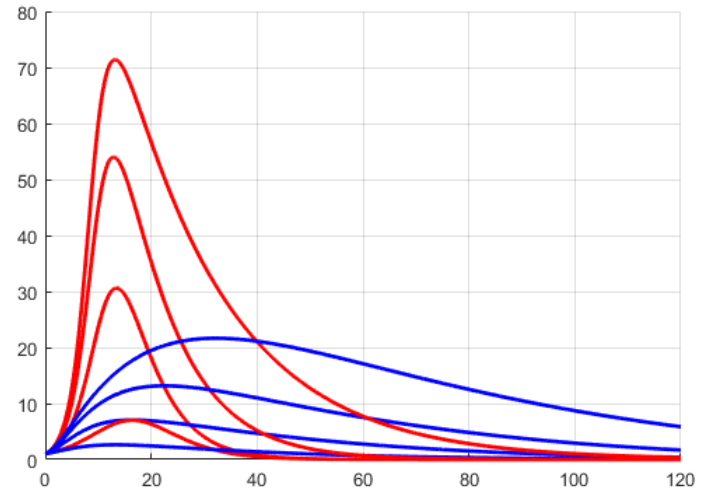
	SIR with saturation	Classical SIR
Equations	$\frac{dS}{dt} = -pS(1 - \exp(-Ia));$ $\frac{dI}{dt} = pS(1 - \exp(-Ia)) - \gamma I$	$\frac{dS}{dt} = -\beta SI/N;$ $\frac{dI}{dt} = \beta SI/N - \gamma I$
Parameters	$a = \frac{\rho}{N} r^2 \pi$ includes $\left\{ \begin{array}{l} \text{pop density } \rho \\ \text{infection radius } r \end{array} \right\}$ p : probability of infection $\gamma \equiv$ recovery rate	$\beta \equiv$ infection rate $\gamma \equiv$ recovery rate
R_0	$\rho p \frac{r^2 \pi}{\gamma}$	β/γ
I_{\max}/N	$I_{\max, \text{sat}} < I_{\max, \text{classical}}$	$1 + \frac{1}{R_0} \left(\log \frac{1}{R_0} - 1 \right)$
Attack rate r_∞	$r_{\infty, \text{sat}} < r_{\infty, \text{classical}}$	$\ln(1 - r_\infty)/r_\infty = R_0$



Red = I (classic), blue = I (saturation)



$p=0.01 \times 2^k$, $k=0..6$
 $a=0.006/p$, $\text{gamma}=0.2$, $N=100$



$a=0.3$, $p=0.02$,
 $\text{gamma}=0.05 \times 2^k$, $k=0..3$

Social distancing

- Suppose that each person has a **“hard-core” repulsion radius** h in addition to **“infection radius”** r .
- Let E be the expected area fraction for I infected individuals. Then

$$E = Ia - \binom{I}{2} \frac{(a-b)^2}{1-2b} + \binom{I}{3} \frac{(a-2b)^3}{(1-3b)^2} \dots$$
$$E = \sum_{j=1}^I -(-1)^j \binom{I}{j} I_j$$

where

$$I_j = \begin{cases} \frac{(a - (j-1)b)^j}{(1-jb)^{j-1}}, & \text{if } a > (j-1)b \\ 0, & \text{if } a < (j-1)b \end{cases}$$
$$a = \frac{\pi r^2}{A}, \quad b = \frac{\pi h^2}{A}$$

- The probability of coming into contact with one of I infected individuals is then given by:

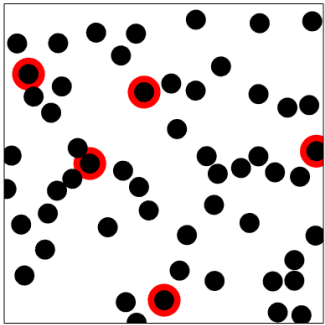
$$F(I; a, b) := \frac{E(k, a, b) - Ib}{1 - Ib}$$

- Note that $F \sim (1 - \exp(-Ka))$ when $b = 0$ so this generalizes the $b = 0$ case.
- Note that $F \sim I(a - b)$ for small I , which reduces to the usual law of mass action (linear in I)

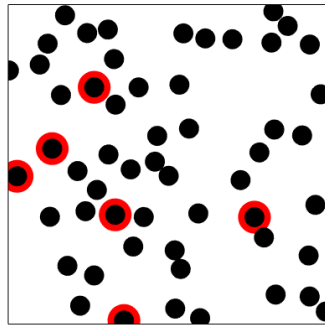
● **Conclusion:**

Replace $\frac{\beta}{N}SI$ by $\beta F(I, \frac{\alpha}{N}, \frac{\mu}{N})$

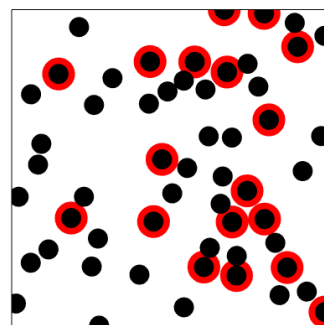
$$\frac{dS}{dt} = -\beta S F(I, \frac{\alpha}{N}, \frac{\mu}{N}); \quad \frac{dI}{dt} = \beta S F(I, \frac{\alpha}{N}, \frac{\mu}{N}) - \gamma I; \quad \frac{dR}{dt} = \gamma I \quad (6)$$



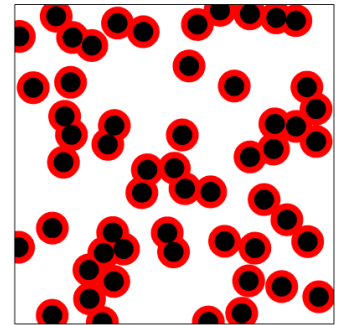
t = 0



t = 20

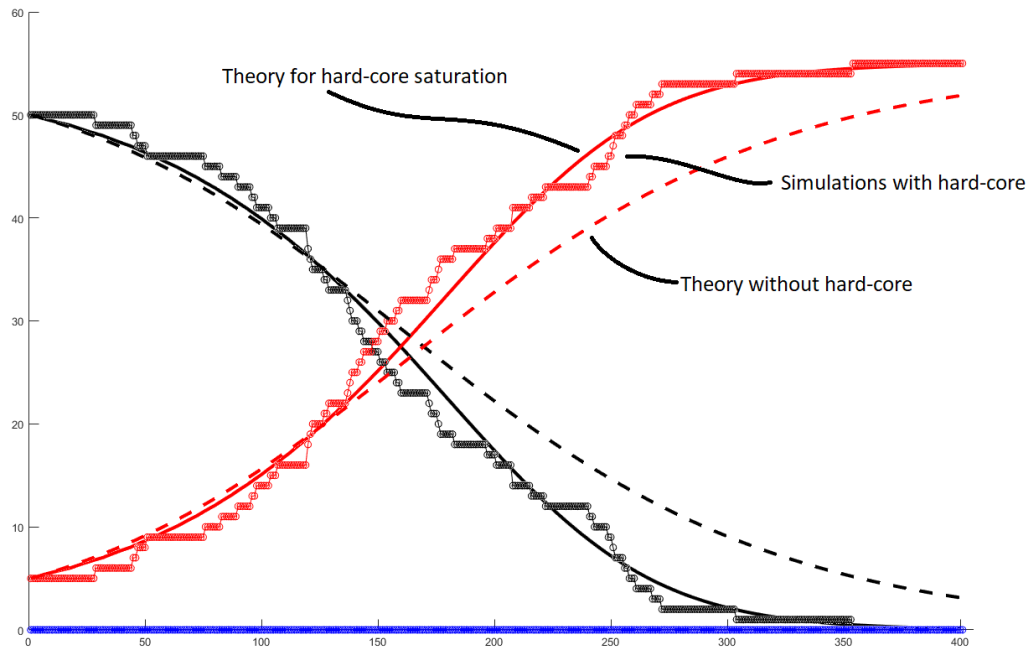


t = 120



t = 400

a=0.0201, b=0.0113, p=0.0300



Future exploration

- Motion of agents (not fully-mixed), spatial propagation
- Piecewise parameter fit: Especially for European countries (e.g. Germany)
- Data fitting with parameters
- Decaying kernels
- Effect of social distancing

Thank you!