

## Variation of parameters (2.5)

(VI)

(VOP).

- a general method for obtaining particular solution of a linear (second order for us) equation with possibly non-constant ~~co~~ coeff's

$$L(y) = y'' + p(t)y' + q(t)y = f(t)$$

- requires we know  $y_1, y_2$  (homog. soln's)
- " evaluation of integral

Idea: recall, if  $f(t) \equiv 0$ , then

$$y = c_1 y_1 + c_2 y_2 \quad c_{1,2} \text{ constants}$$

with VOP, let particular solution  $y_p$  be written

$$y_p = u_1(t) y_1 + u_2(t) y_2$$

and find  $u_1, u_2$  s.t.

$$L(y_p) = f(t) \quad \leftarrow \text{this is one condition on } u_1, u_2.$$

since we have 2 unknowns, we may specify a second condition that leads to a first order equation for  $u_1$  and  $u_2$  (ie., eliminate  $u_1''$  and  $u_2''$  terms)

so

$$y_p' = u_1' y_1 + u_1 y_1' + u_2' y_2 + u_2 y_2'$$

$$= \underbrace{u_1 y_1' + u_2 y_2'} + \underbrace{u_1' y_1 + u_2' y_2}$$

set this to 0

let  $\boxed{u_1' y_1 + u_2' y_2 = 0}$  condition

$$\Rightarrow y_p' = u_1 y_1' + u_2 y_2'$$

$$y_p'' = u_1' y_1 + u_1 y_1'' + u_2' y_2 + u_2 y_2''$$

sub into ODE:

$$\begin{aligned}
 & \boxed{u_1 y_1''} + \boxed{u_2 y_2''} + u_1' y_1' + u_2' y_2' \\
 & + p(t) \left[ \boxed{u_1 y_1'} + \boxed{u_2 y_2'} \right] + q(t) \left[ \boxed{u_1 y_1} + \boxed{u_2 y_2} \right] \\
 & = f(t)
 \end{aligned}$$

$$\begin{aligned}
 & \cancel{u_1 [y_1'' + p(t)y_1' + q(t)y_1]} + \cancel{u_2 [y_2'' + p(t)y_2' + q(t)y_2]} \quad \Bigg\| \begin{array}{l} y_1, y_2 \\ \text{are} \\ \text{homog.} \\ \text{soln's} \\ \Rightarrow L(y_{1,2}) = 0 \end{array} \\
 & + u_1' y_1' + u_2' y_2' = f(t)
 \end{aligned}$$

$$\Rightarrow \boxed{u_1' y_1' + u_2' y_2' = f(t)} \quad \text{2nd condition.}$$

2 eqns, 2 unknowns ( $u_1', u_2'$ )

$$\begin{cases} u_1' y_1 + u_2' y_2 = 0 \\ u_1' y_1' + u_2' y_2' = f(t) \end{cases}$$

$$\begin{pmatrix} y_1 & y_2 \\ y_1' & y_2' \end{pmatrix} \begin{pmatrix} u_1' \\ u_2' \end{pmatrix} = \begin{pmatrix} 0 \\ f(t) \end{pmatrix}$$

Use Cramer's rule:

$$u_1' = \frac{\begin{vmatrix} 0 & y_2 \\ f & y_2' \end{vmatrix}}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}} = \frac{-y_2 f}{w}$$

wronskian  
 $w(y_1, y_2; t)$

$$u_2' = \frac{\begin{vmatrix} y_1 & 0 \\ y_1' & f \end{vmatrix}}{w} = \frac{y_1 f}{w}$$

$$u_1(t) = - \int \frac{y_2(t) f(t)}{W(y_1, y_2; t)} dt.$$

$$u_2(t) = \int \frac{y_1(t) f(t)}{W(y_1, y_2; t)} dt.$$

\* require  $y_1, y_2$

↑  
can take constants of integration to be 0 wlog.

Ex

find general solution of

$$y'' + y = \tan t \quad \left( -\frac{\pi}{2} < t < \frac{\pi}{2} \right)$$

first find  $y_1, y_2$ :

$$y_1 = \cos t, \quad y_2 = \sin t.$$

$$\text{let } y_p = u_1(t) y_1 + u_2(t) y_2.$$

$$\text{calculate } W(y_1, y_2; t) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$$

$$= \begin{vmatrix} \sin t & \cos t \\ \cos t & -\sin t \end{vmatrix} = -\sin^2 t - \cos^2 t = -1.$$

$$u_1(t) = - \int \frac{y_2(t) f(t)}{W} dt$$

$$= - \int \frac{\cos t \tan t}{-1} dt = \int \sin t dt$$

$$= -\cos t + C \quad \uparrow \text{wlog.}$$

$$u_2(t) = \int \frac{y_1 f(t)}{-1} dt = - \int \sin t \tan t dt$$

$$= \int - \frac{\sin^2 t}{\cos t} dt = - \int \frac{1 - \cos^2 t}{\cos t} dt$$

$$= - \int \sec t - \cos t \, dt.$$

∴ etc

$$= \sin t - \log(\sec t + \tan t) + \underset{\substack{\uparrow \\ \text{wlog.}}}{0}$$

then

$$y_p = -\cos t \sin t + \left[ \sin t - \log(\sec t + \tan t) \right]_{\cos t}$$

$$= -\cos t \log(\sec t + \tan t).$$

$$y = c_1 y_1 + c_2 y_2 + y_p.$$