

Wronskians of solutions

$$L \equiv \frac{d^2}{dt^2} + p(t) \frac{d}{dt} + q(t)$$

p, q cont's on interval I

suppose $L(y_1) = L(y_2) = 0$

and consider the Wronskian

$$W(y_1, y_2) \equiv \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = y_1 y_2' - y_2 y_1'$$

- if y_1, y_2 are l.d. on I , then

$$W \equiv 0 \text{ on } I$$

- if y_1, y_2 are l.i. on I , then

$W \neq 0$ everywhere on I (show later)

i.e., W is either always 0 or never

motivation for definition of w :

try to solve IVP

$$L(y) = 0, \quad y(a) = b_0, \quad y'(a) = b_1 \quad (*)$$

to see if $y = c_1 y_1 + c_2 y_2$ is
 a viable solution, $(L(y_1) = L(y_2) = 0)$

try to solve for c_1, c_2 . If we
 can solve for c_1, c_2 , the solution of

(*) may be expressed as a
 linear combination of y_1, y_2 . otherwise
 it cannot.

solve for c_1, c_2 :

$$y(a) = b_0 \Rightarrow c_1 y_1(a) + c_2 y_2(a) = b_0$$

$$y'(a) = b_1 \Rightarrow c_1 y_1'(a) + c_2 y_2'(a) = b_1$$

write in matrix form:

$$\begin{pmatrix} y_1(a) & y_2(a) \\ y_1'(a) & y_2'(a) \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} b_0 \\ b_1 \end{pmatrix}$$

for solution of ~~ca~~ for c_1, c_2 to exist, require the determinant of the matrix (which we call the wronskian) to be nonzero.

[to solve for c_1 :

$$c_1 y_1(a) y_2'(a) + c_2 \cancel{y_2(a) y_2'(a)} = y_2'(a) b_0$$

$$- c_1 y_1'(a) y_2(a) + c_2 \cancel{y_2'(a) y_2(a)} = y_2(a) b_1$$

$$c_1 [y_1(a) y_2'(a) - y_1'(a) y_2(a)] = y_2'(a) b_0 - y_2(a) b_1$$

$$c_1 = \frac{y_2'(a) b_0 - y_2(a) b_1}{y_1(a) y_2'(a) - y_1'(a) y_2(a)}$$

denominator is the wronskian. if
nonzero, soln for c_1 exists

Ex $y_1 = e^{2x}$, $y_2 = e^{-2x}$ are

soln's of $y'' - 4y = 0$

show $w(y_1, y_2) \neq 0$

$$w(y_1, y_2) = \begin{vmatrix} e^{2x} & e^{-2x} \\ 2e^{2x} & -2e^{-2x} \end{vmatrix}$$

$$= -2 - (2) = -4 \neq 0$$

Ex ~~$y_1 = \cosh 2x$, $y_2 = \sinh 2x$~~

can also write $y_1 = \cosh 2x$

$$y_2 = \sinh 2x$$

$$y_1 = \frac{e^{2x} + e^{-2x}}{2} = \cosh 2x$$

$$y_2 = \frac{e^{2x} - e^{-2x}}{2} = \sinh 2x$$

So general soln can either be written

as
$$y = c_1 e^{2x} + c_2 e^{-2x}$$

or

$$y = c_1 \cosh 2x + c_2 \sinh 2x$$

$$\left. \begin{aligned} y &= c_1 \cos mt \\ &+ c_2 4 \cos mt \\ &= (c_1 + 4c_2) \cos mt \\ &= A \cos mt \end{aligned} \right\}$$

Ex $y_1 = \cos mt, \quad y_2 = 4 \cos mt$

are soln's of $y'' = -m^2 y$ but

$$W(y_1, y_2) = \begin{vmatrix} \cos mt & 4 \cos mt \\ -m \sin mt & -4m \sin mt \end{vmatrix}$$

$$= -4m \cos mt \sin mt - (-4m \cos mt \sin mt)$$

$$= 0$$

Abel's formula (show w is either always 0 or never 0).

$$w(y_1, y_2; x) = y_1 y_2' - y_2 y_1'$$

$$\left[y_{1,2}'' + p(x) y_{1,2}' + q(x) y_{1,2} = 0 \right]$$

$$\left(\frac{dw}{dx} = \cancel{y_1' y_2'} + y_1 y_2'' - \cancel{y_2' y_1'} - y_2 y_1'' \right)$$

$$\rightarrow y_{1,2}'' = -p(x) y_{1,2}' - q(x) y_{1,2}$$

therefore

$$\begin{cases} y_1'' = -p(x) y_1' - q(x) y_1 \\ y_2'' = -p(x) y_2' - q(x) y_2 \end{cases}$$

$$\frac{dw}{dx} = y_1 [-p(x) y_2' - q(x) y_2] - y_2 [-p(x) y_1' - q(x) y_1]$$

$$= p(x) [-y_1 y_2' + y_2 y_1'] + q(x) [-y_1 y_2 + y_2 y_1]$$

$$= p(x) (-w)$$

$$\Rightarrow \frac{dw}{dx} = -p(x)W \quad (\text{separable})$$

$$\int \frac{dw}{w} = \int -p(x) dx$$

$$\log w = -\int p(x) dx + C$$

$$w = A e^{-\int p(x) dx}$$

↑ exp. is never 0

therefore, w is always 0 ($A=0$)

or never 0 ($A \neq 0$)

Linear 2nd order equations with constant coeff's

have the form

$$ay'' + by' + cy = 0 \quad (5)$$

where a, b, c are constants.

- since ^{existence and} uniqueness theorem applies, we can guess at form of solution.

- notice that $\frac{d}{dx} e^{rx} = r e^{rx}$

that is : differentiation \rightarrow multiplication
so using this guess in (5), we obtain an algebraic equation for r.

(ODE \rightarrow algebraic equation)

Ex

solve

$$\frac{d^2}{dx^2} y = 4y$$

(a=1, b=0, c=-4)

guess : $y = e^{rx}$

$$y' = r e^{rx}, \quad y'' = r^2 e^{rx}$$

$$r^2 e^{rx} = 4 e^{rx}$$

$$e^{rx} (r^2 - 4) = 0$$

$$e^{rx} \neq 0$$

$$\Rightarrow r^2 - 4 = 0 \quad (\text{characteristic equation c.e.})$$

~~$$r_1 = 2, r_2 = -2$$~~

therefore

$$y_1 = e^{2x}, \quad y_2 = e^{-2x} \quad \text{are}$$

both solutions

so general soln can be written as

$$y = c_1 e^{2x} + c_2 e^{-2x}$$

or

$$y = c_1 \cosh 2x + c_2 \sinh 2x$$

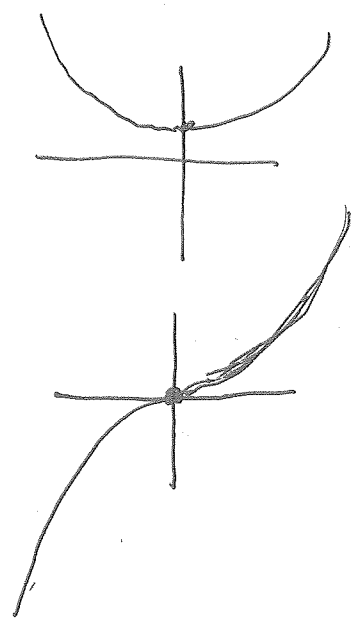
$$= c_1 \left[\frac{e^{2x} + e^{-2x}}{2} \right] + c_2 \left[\frac{e^{2x} - e^{-2x}}{2} \right]$$

$$= e^{2x} \underbrace{\left[\frac{c_1}{2} + \frac{c_2}{2} \right]}_A + e^{-2x} \underbrace{\left[\frac{c_1}{2} - \frac{c_2}{2} \right]}_B$$

$$= A e^{2x} + B e^{-2x} \quad \therefore \text{equivalent.}$$

$$\cosh x \equiv \frac{e^x + e^{-x}}{2}$$

$$\sinh x = \frac{e^x - e^{-x}}{2}$$



$$\cos x = \frac{e^{ix} + e^{-ix}}{2}$$

$$\sin x = \frac{e^{ix} - e^{-ix}}{2i}$$

$$\left| \begin{array}{l} \cosh^2 x - \sinh^2 x = 1 \\ \cos^2 x + \sin^2 x = 1 \end{array} \right.$$

EX (p.109)

$$W(y_1, y_2) = \begin{vmatrix} \cosh 2x & \sinh 2x \\ 2 \sinh 2x & 2 \cosh 2x \end{vmatrix}$$

$$= 2 \cosh^2 2x - 2 \sinh^2 2x$$

$$= 2 \{ \cosh^2 2x - \sinh^2 2x \} = 2$$

(homework)

EX (p.109)

$$y'' - 5y' + 6y = 0$$

guess $y = e^{rx}$

$$y' = r e^{rx}, \quad y'' = r^2 e^{rx}$$

sub into ODE:

$$r^2 e^{rx} - 5r e^{rx} + 6 e^{rx} = 0$$

$$\underbrace{e^{rx}}_{\text{never 0}} [r^2 - 5r + 6] = 0$$

$$\Rightarrow r^2 - 5r + 6 = 0 \quad (\text{C.E.})$$

$$\cancel{r=2}, \quad (r-2)(r-3) = 0$$

$$r = 2, 3$$

$$y_1 = e^{2x}, \quad y_2 = e^{3x}$$

no sinh and cosh because e^{-2x} and e^{-3x} are not solns of the ODE

go back to (5): guess e^{rx}

then C.E. would be

$$ar^2 + br + c = 0$$

$$r_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

the two previous examples were examples in which r_1 and r_2 were real and distinct, i.e., $b^2 - 4ac > 0$

(case 1), Then we had

$$y_1 = e^{r_1 x}, \quad y_2 = e^{r_2 x}$$

$$y = c_1 e^{r_1 x} + c_2 e^{r_2 x}$$

what if $b^2 - 4ac < 0$? (case 2)

r_1 and r_2 would still be distinct but complex. so we can still write

soln as

$$y = c_1 e^{r_1 x} + c_2 e^{r_2 x}$$

but r_1, r_2 are complex, so we can write in a more suggestive form

EX $y'' + 9y = 0$

$$r^2 + 9 = 0 \Rightarrow r = \pm \sqrt{-9} = \pm 3i$$

$$r^2 = -9 \Rightarrow r = \pm \sqrt{-9} = \pm 3i$$

$$y_1 = e^{3ix}, \quad y_2 = e^{-3ix}$$

$$\text{so } y = c_1 e^{3ix} + c_2 e^{-3ix} \text{ is}$$

a general soln

wronskian $\begin{vmatrix} e^{3ix} & e^{-3ix} \\ 3ie^{3ix} & -3ie^{-3ix} \end{vmatrix}$

$$= -3i - 3i = -6i \neq 0$$

can write in different form:

by superposition,

$$y = \frac{y_1 + y_2}{2}, \quad \text{and } y = \frac{y_1 - y_2}{2i}$$

are also soln's

$$\begin{aligned} \frac{y_1 + y_2}{2} &= \frac{e^{i3x} + e^{-i3x}}{2} = \frac{\cancel{\cos 3x} + i\cancel{\sin 3x} + \cos 3x - i\cancel{\sin 3x}}{2} \\ &= \cos 3x \end{aligned}$$

$$\begin{aligned} \frac{y_1 - y_2}{2i} &= \frac{e^{i3x} - e^{-i3x}}{2i} = \frac{\cancel{\cos 3x} + i\sin 3x - (\cancel{\cos 3x} - i\sin 3x)}{2i} \\ &= \frac{2i\sin 3x}{2i} = \sin 3x \end{aligned}$$

so $y_1 = \cos 3x$ and $y_2 = \sin 3x$

are l.i. soln's also

$$\text{so } y = c_1 \cos 3x + c_2 \sin 3x$$

is a general soln

notice: $\cos 3x = \operatorname{Re}(e^{i3x})$

$$\sin 3x = \operatorname{Im}(e^{i3x})$$

so the real and imaginary part of e^{i3x} form two linearly indep.

soln's

(will use this fact later in the course)